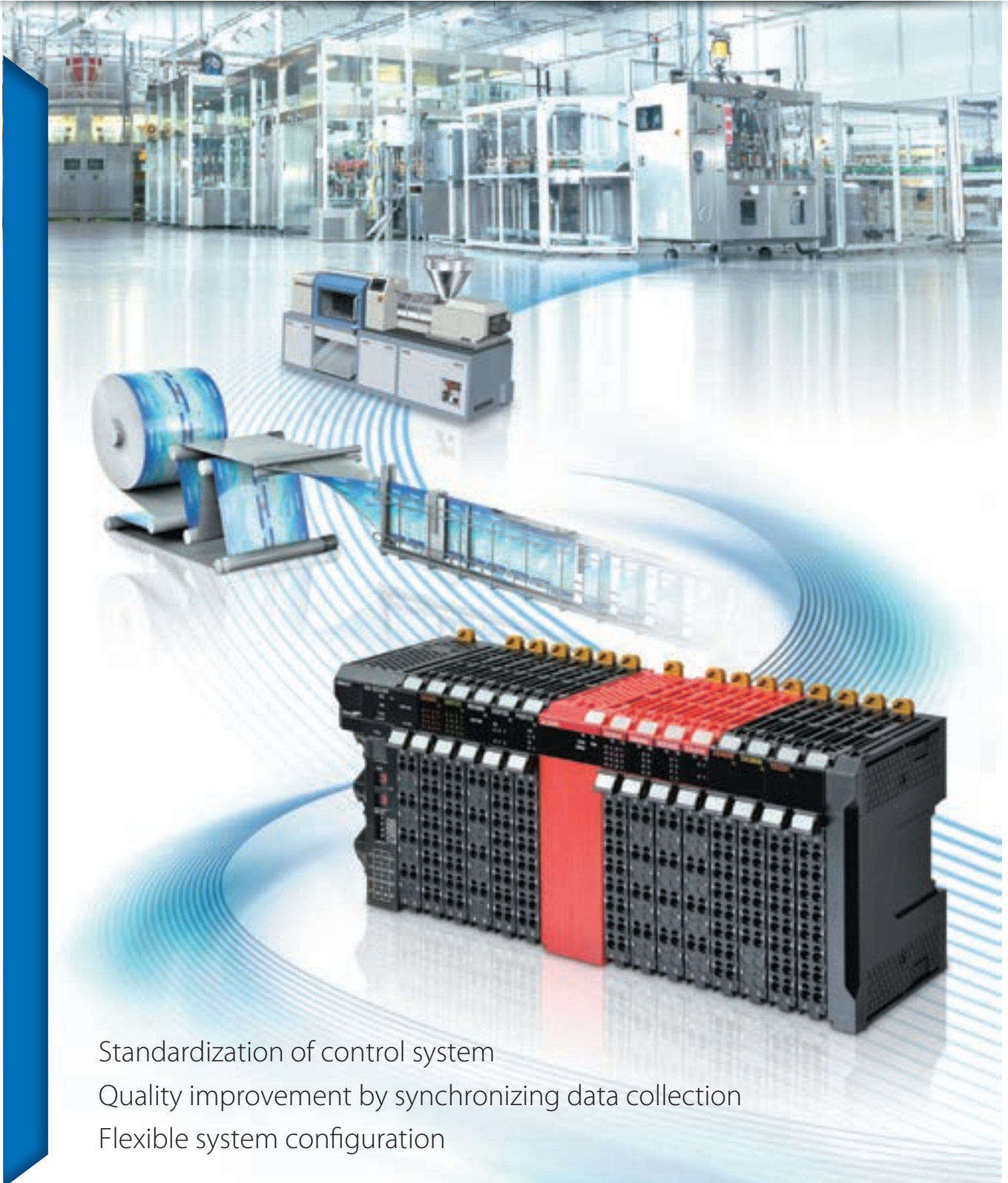


# NX-series I/O System

Unique I/O increases application quality and range



- Standardization of control system
- Quality improvement by synchronizing data collection
- Flexible system configuration

# Unique I/O increases application quality and

The NX I/O connects sensors and actuators on production lines to optimize applications

## Application example



Corresponding to our shared **Value Design for Panel** concept for the specifications of products

## IoT

IO-Link makes communication down to the sensor level visible

**Applicable units:**  
NX-ECC203  
NX-ILM400

## Traceability

Easy and quick set-up for traceability using RFID

**Applicable units:**  
NX-V680C1  
NX-V680C2

## Measuring

PLC systems can measure analog signals at high speeds for inspections

**Applicable units:**  
NX-HAD401

## Weighing

High-accuracy weighing using load cells

**Applicable units:**  
NX-RS1201



### Communications coupler

- EtherCAT®
- EtherNet/IP™

### IO-Link master

- Up to 4 IO-Link devices with one master

### Serial communications

- RS-232C or RS-422A/485 interface

### EtherCAT Slave Unit

- NX Series available as subsystem controller on EtherCAT

### RFID

- Direct connection to V680 amplifiers and antennas
- 1 or 2 channels

### Digital I/O

- 4, 8, 16, or 32 channels per input unit
- 2, 4, 8, 16, or 32 channels per output unit (8 channels per relay output unit)
- 16 channels per mixed I/O unit
- Standard, high-speed, and time-stamp models
- Units with Push-In Plus/MIL/Fujitsu/OTAX/M3 Screw connector

### Analog I/O

- +/-10V voltage and 4-20 mA current signals
- 2, 4 or 8 channels per input unit
- 2 or 4 channels per output unit
- Standard and high-performance models
- Single-ended input and differential input models

### High-speed analog inputs

- 4 channels per input unit
- Differential input
- Sampling as fast as every 5 µs

### Load cell inputs

- One load cell with one unit
- Fastest conversion cycle of 125 µs

# range

## Servo press

High-speed, high-precision press fit using load cells

**Applicable units:**  
NX-RS1201  
NX-SID800  
NX-SOD400

## Safety control

Simplify safety control systems

**Applicable units:**  
NX-SL3300  
NX-SID800  
NX-SOD400

## Temperature control

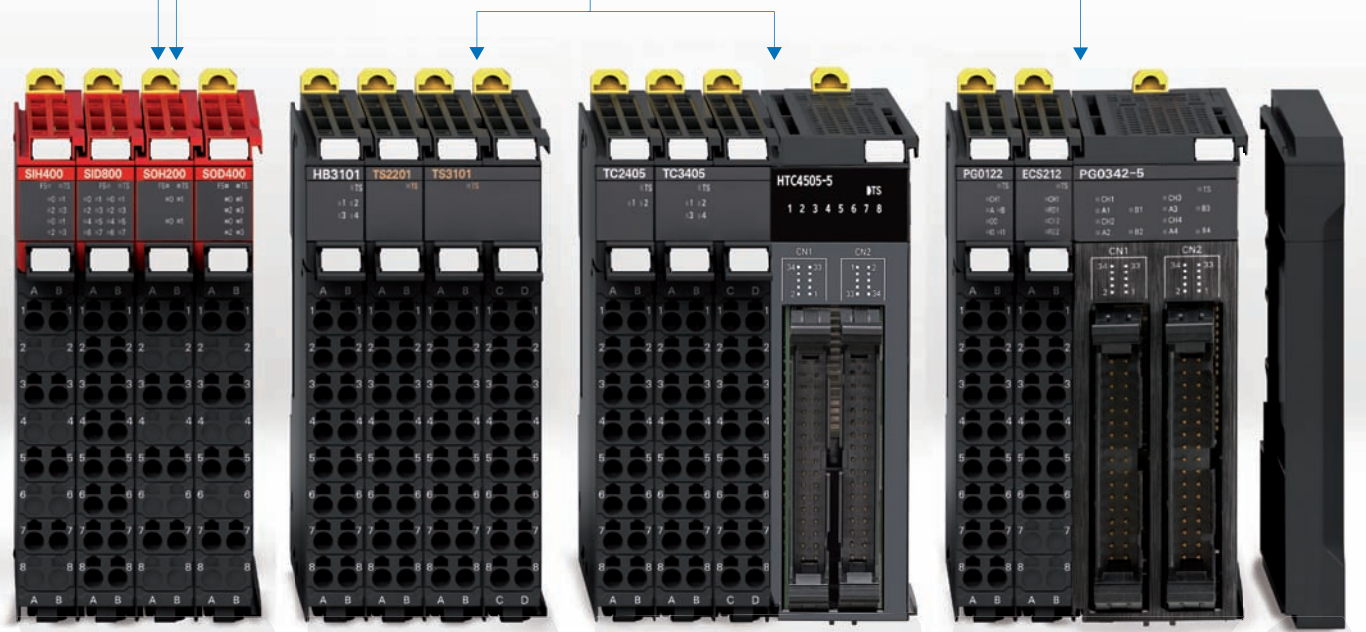
Simplify temperature control systems using temperature sensors

**Applicable units:**  
NX-TS3101  
NX-HB3101  
NX-TC3405  
NX-HTC4505-5

## Motion

Simplify position control systems using pulse-train input type motors

**Applicable units:**  
NX-ECS212  
NX-PG0342-5



### Safety I/O

- 4 or 8 safety input points per unit
- 2 or 4 safety output points per unit
- Free allocation of the safety I/O units on the internal high speed bus

### Safety CPU

- EN ISO13849-1 (PLe/Safety Category 4), IEC 61508 (SIL3) certified
- Controls up to 128 safety I/O units

### Temperature inputs

- Thermocouple or RTD inputs, 2 or 4 per unit
- Conversion time of 10 ms, 60 ms or 250 ms

### Heater burnout detection

- 4 CT sensor inputs and 4 trigger outputs to drive SSRs

### Temperature control

- 2 or 4 multi-input (thermocouple and resistance thermometer) channels per unit
- Conversion time of 50 ms
- Voltage output (for driving SSR) or linear current output
- Number of CT inputs 1 point per channel

### Advanced temperature control **NEW**

- 4 or 8 universal inputs (thermocouple, platinum resistance thermometer, analog voltage, analog current) channels per unit

### Position interface

- Incremental and absolute encoder support
- Pulse output unit (line driver output model)

### End cover

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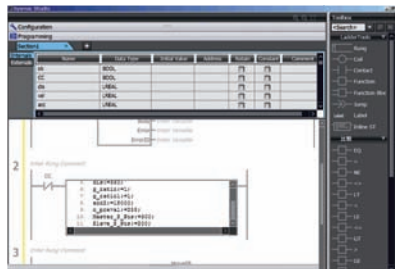
# Simplicity for advanced control

## A fully integrated platform

The NX I/O is used to integrate sequence, motion, analog, vision, and safety control, previously done by PLC and dedicated controllers, and visualization of previously invisible sensor data within the Sysmac automation platform.

### Sequence control

Multi-tasking and fully compliant with IEC 61131-3 standard programming and PLCopen® Function Blocks.



EtherNet/IP®

### Motion control

PLCopen® Function Blocks for the motion control library are available to implement advanced motion control.



### Analog control

The Sysmac Library\* and instructions make temperature, weighing, and load control easier.



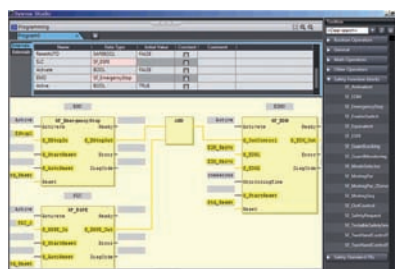
Weighing Control Library  
Servo Press Library



\*The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX/NY Controllers. Sample programs and HMI templates are also available. Download from Omron website and install to use in the Automation Software Sysmac Studio. [http://www.iia.omron.com/sysmac\\_library/](http://www.iia.omron.com/sysmac_library/)

### Safety control

Conforms with PLCopen® Function Blocks for Safety.



### Feature of Sysmac

One Control through  
 One Software and  
 One Network  
 simplifies control system configuration

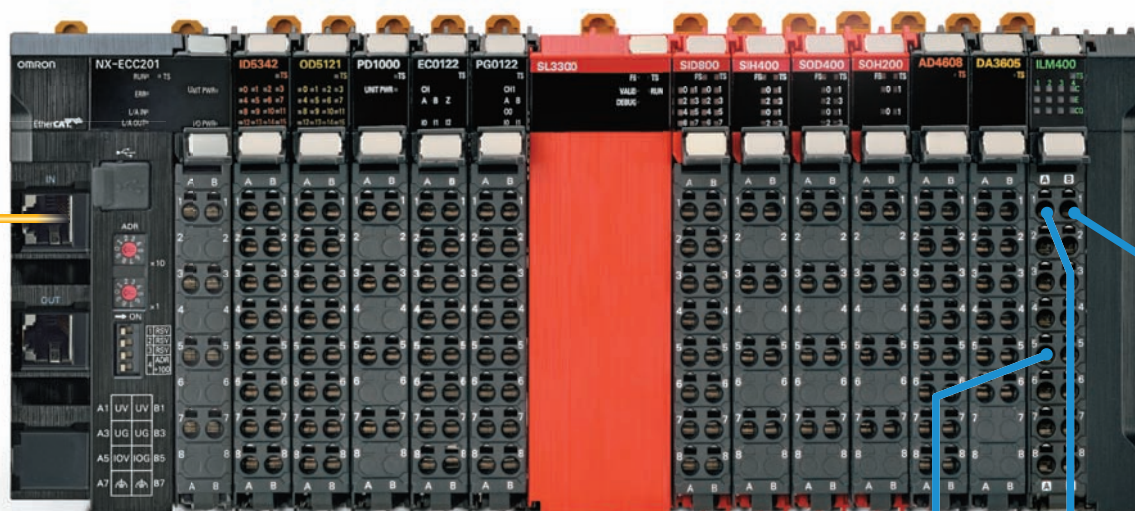
Interfaces for sequence, motion, safety, and analog control and communications required for machines

### Visualized sensor data

IO-Link makes communication down to the sensor level visible



EtherCAT



Connecting directly to most sensors, actuators, and safety components



IO-Link sensors  
**IO-Link**

Note: Functionality provided by the EtherCAT coupler unit

# Synchronized control for high-speed performance

## Production data collection synchronized at high speed

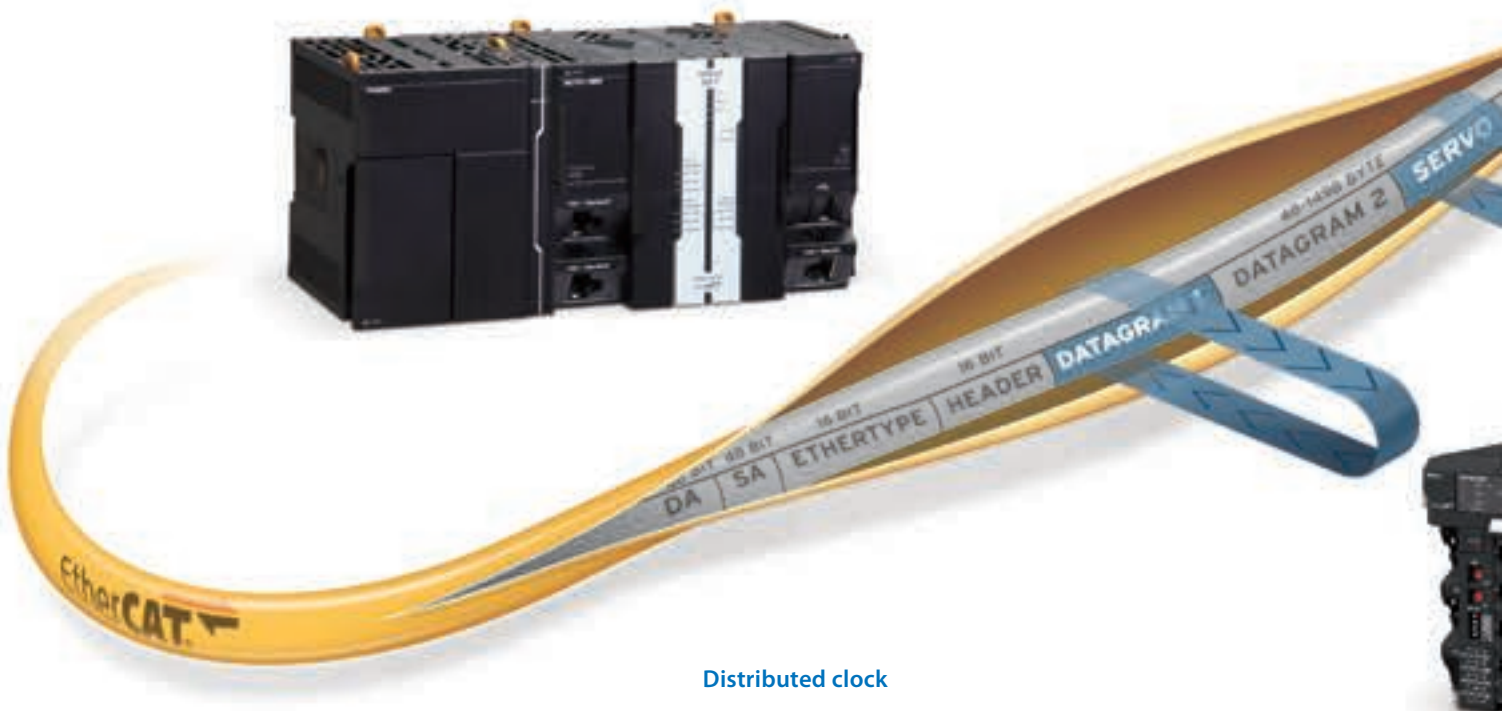
Based on an internal high-speed bus running in synchronization with the EtherCAT network and CPU cycle, the NX I/O can be controlled and used for position, analog, and digital data collection with microsecond accuracy and with nanosecond resolution.

### Feature

#### High-speed I/O units accurately synchronized with the CPU cycle\*1

- Digital I/O: High-speed and time-stamp models (NsynX)
- Analog I/O: 10  $\mu$ s conversion time per channel and 1:30000 resolution
- Load cell inputs: 125  $\mu$ s conversion time per channel and 24-bit resolution

\*1. Fastest cycle time: NX7=125  $\mu$ s, NJ5=500  $\mu$ s



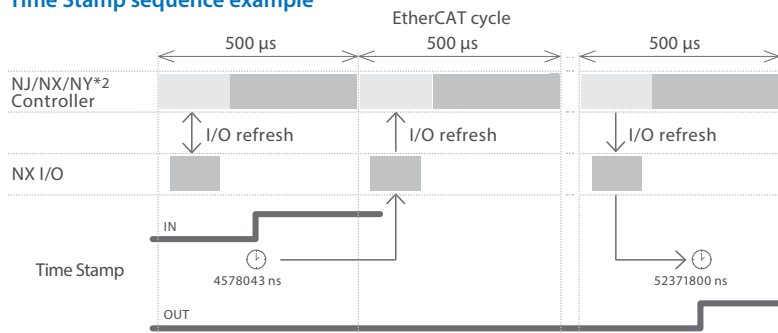
### Distributed clock

The EtherCAT node slave measures the time difference between incoming and returning frame - Time-Stamp function. With this Time-Stamp function the master can determine the propagation delay offset to the individual slave accurately. This mechanism ensures accurate synchronization between devices with less than 1  $\mu$ s jitter.

### NsynX technology

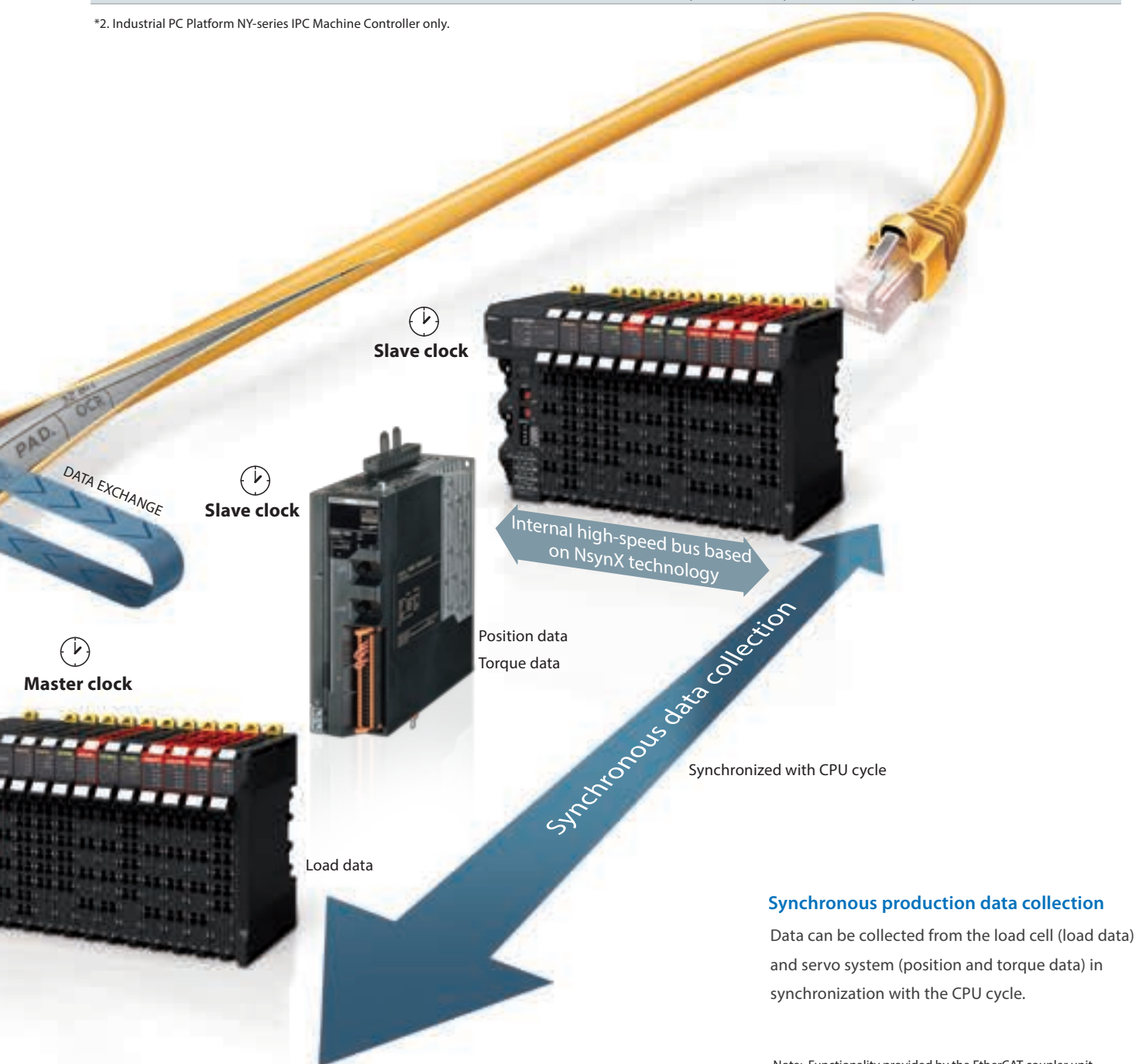
- The NsynX technology is provided by the internal high-speed bus synchronized with the EtherCAT network. This technology is designed for machine control and includes:
- I/O units with distributed clock
- High-speed I/O units synchronized with the EtherCAT cycle
- I/O units with Time-Stamp function

#### Time Stamp sequence example



Accurate control of input events and perfect control of output with nanosecond resolution

\*2. Industrial PC Platform NY-series IPC Machine Controller only.



#### Synchronous production data collection

Data can be collected from the load cell (load data) and servo system (position and torque data) in synchronization with the CPU cycle.

Note: Functionality provided by the EtherCAT coupler unit

# Simplify system configurations

## The choice is yours

The modern control system demands increasing levels of flexibility.

The NX I/O enables connection with various controllers through the global standard network, which expands system configuration possibilities.

Modular remote I/O systems offer flexibility in I/O configuration and a wide choice of signal types and performance levels so that every I/O station can be assembled with just the right combination without changing the control architecture.

### EtherCAT®

EtherCAT specification is governed by the EtherCAT Technology Group (ETG). EtherCAT is suitable for motion control and other applications that require high speed and high precision because of no need of handshaking and high bandwidth utilization.



NJ/NX/NY Series or EtherCAT master from other vendors



### EtherNet/IP®

EtherNet/IP specification is governed by the Open DeviceNet Vendors Association (ODVA). Based on standardized Ethernet protocols (TCP/IP, UDP/IP), EtherNet/IP devices can be mixed with standard Ethernet devices.



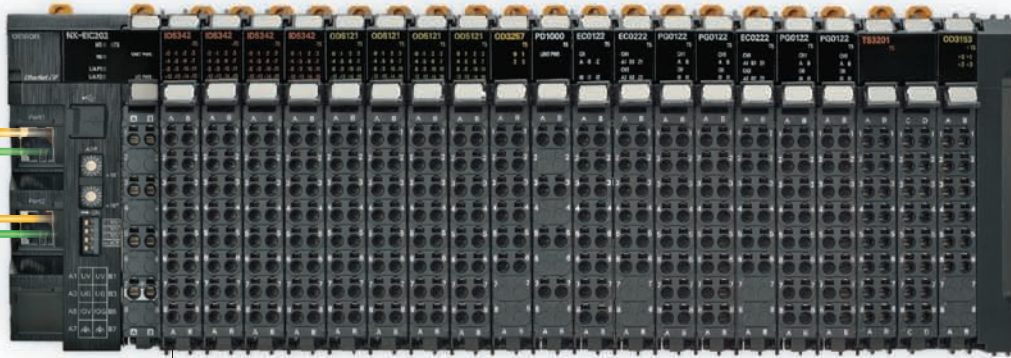
CJ Series or PLC from other vendors





## Feature

**Wide choice:** More than 100 types of I/O unit, from 2 to 32 points in one unit



### Types of NX I/O Units

- Digital Input/Output Units
- Analog Input/Output Units
- Temperature Input Units
- Encoder/Positioning Units
- System Units
- Serial communication Units



### Quick connections

- Detachable screwless terminal block for easy commissioning and maintenance
- Push-In Plus connections speed up installation
- MIL/Fujitsu/OTAX connectors for high-density I/O



### Safety integrated

The NX Safety CPU Unit and Safety I/O Units can be mixed with standard I/O units to create a complete modular safety control system

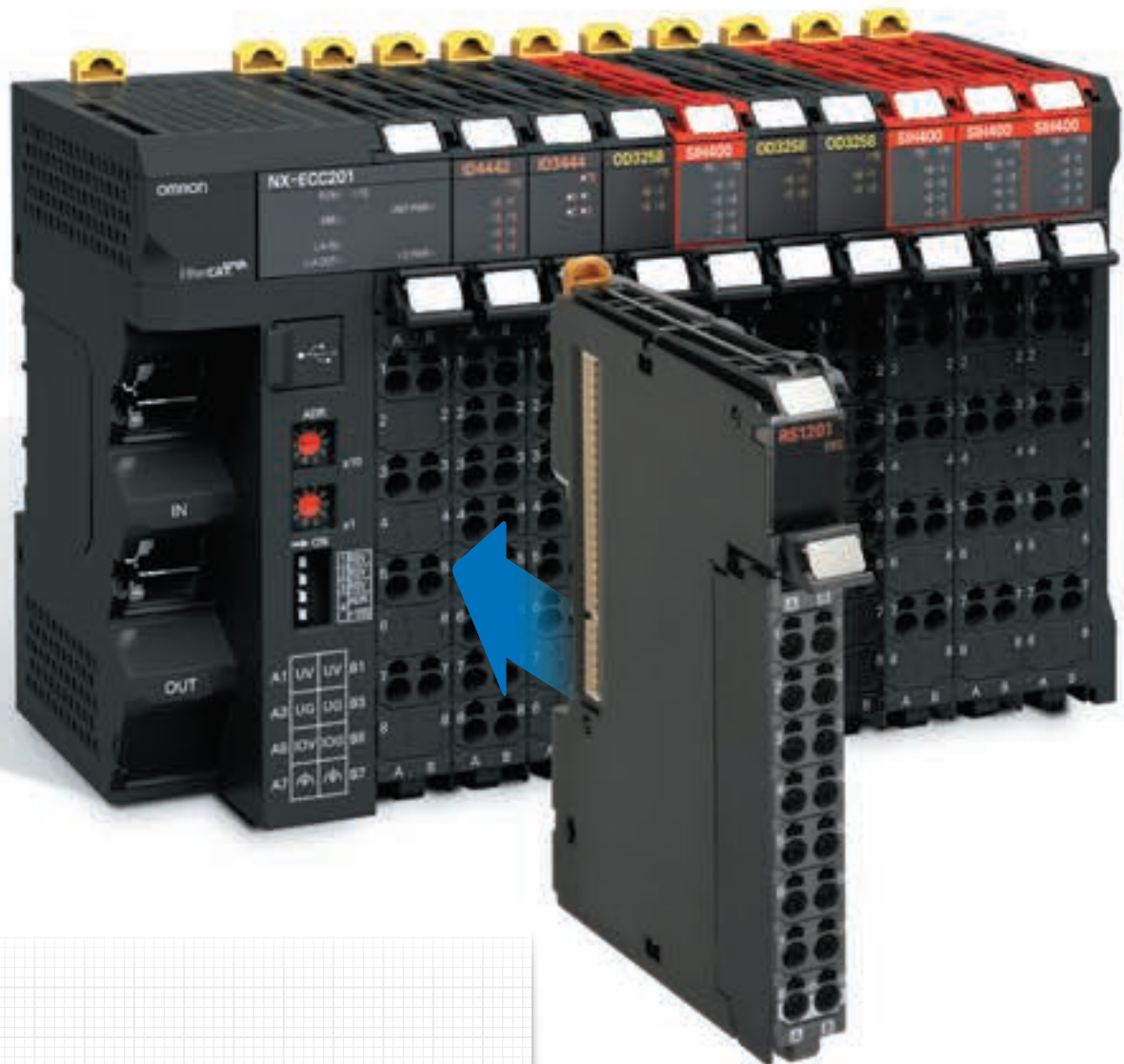
- Note: 1. Communications coupler units vary depending on the connected network.  
 2. Connectable units vary depending on the communications coupler unit.  
 3. The number of connectable nodes varies depending on the master.

# Downsize machines and control panels

## Reduce wiring time and save space

Push-In Plus connections reduce the work and time required for wiring. Modular design saves space. Also designed for installation in any orientation, the NX I/O can be freely allocated in machines.

Up to 63 units per communication coupler



### Feature

**Compact design:** Up to 16 digital signals in 12 mm width

12mm

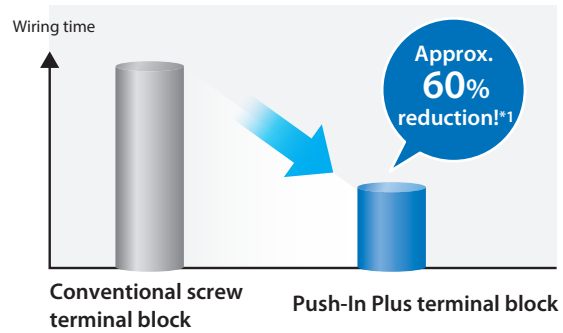


Corresponding to our shared Value Design for Panel concept for the specifications of products



### Greatly reduce wiring work with Push-In Plus terminal blocks

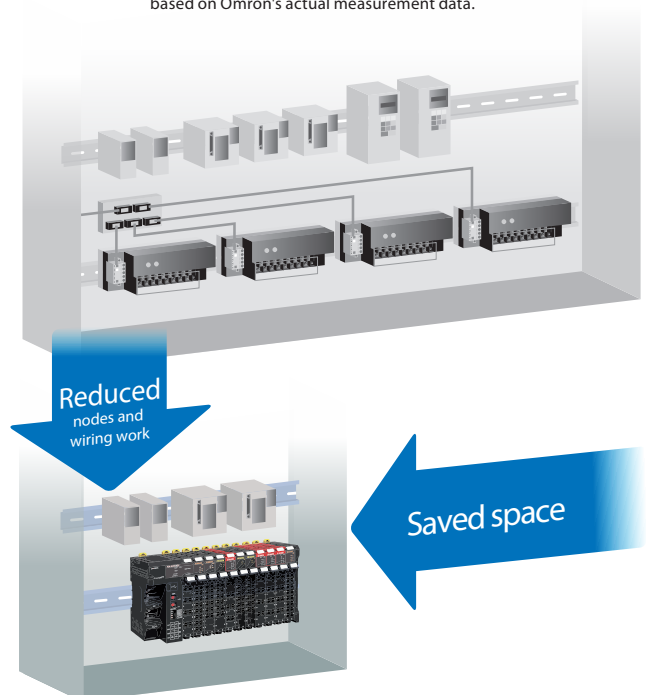
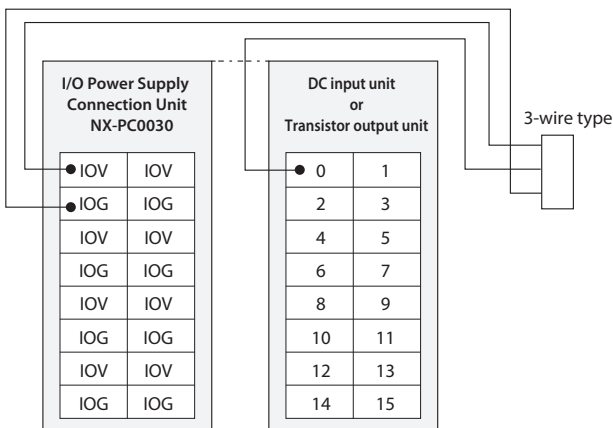
Push-In Plus terminal blocks make wiring work easy - just insert wires.



\*1. Information for Push-In Plus and screw terminal blocks is based on Omron's actual measurement data.

### Save space in control panels

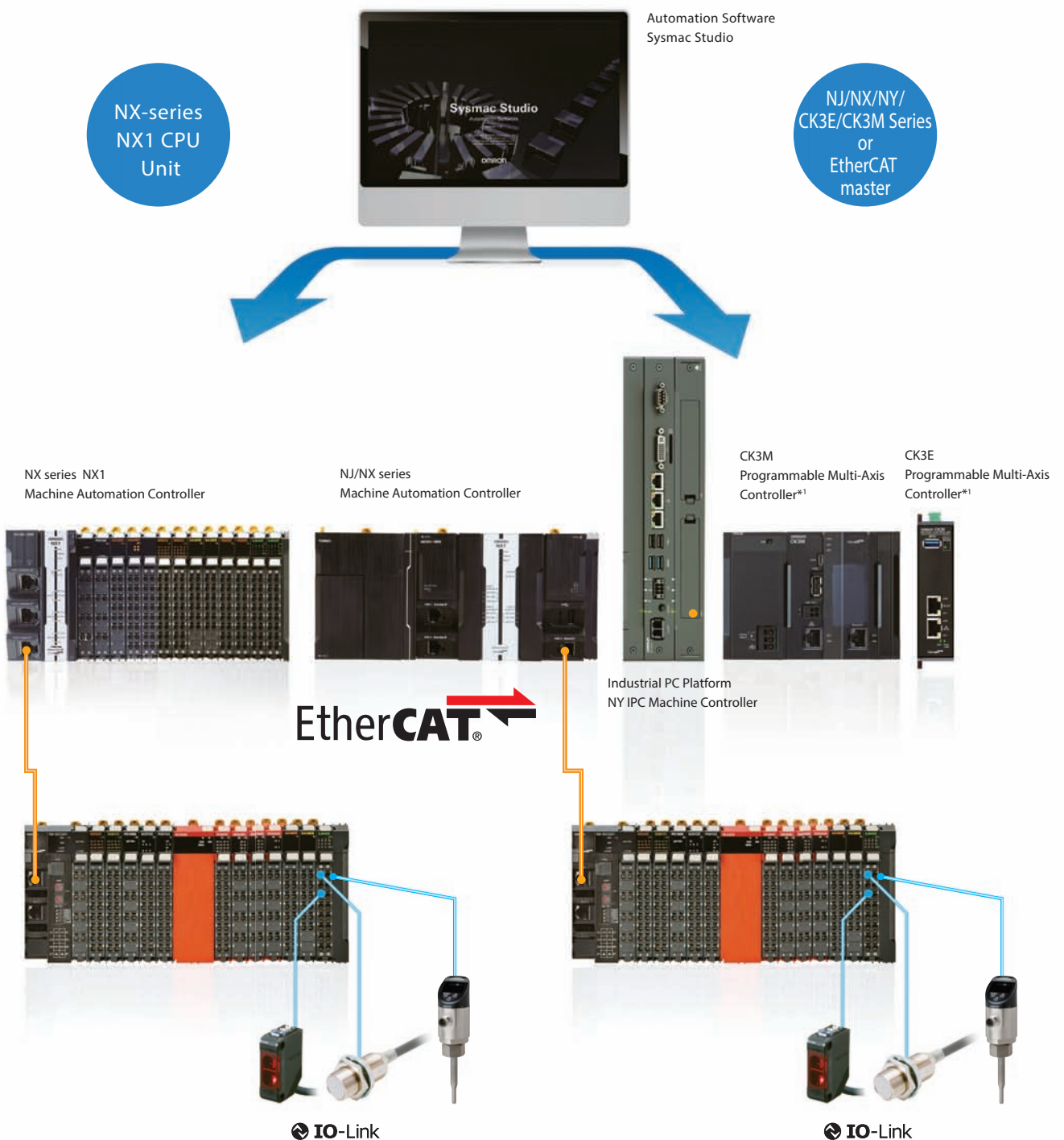
V and G terminals are provided for each input signal (NX-PC0030). No relay terminal block is required, which saves space in control panels.



# Flexible connectivity expands system configuration possibilities

## One I/O system for various controllers

While different machines may require different levels of controller performance, the NX I/O is the only remote I/O system you will need. This will unify wiring and installation techniques, and simplify spare parts stock.

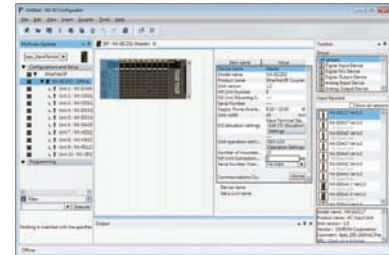


\*1. Dedicated software is required to use the CK3M and CK3E Series.

### Features

- Multivendor compatibility  
The NX I/O can be connected with PLC from other vendors as well as Omron PLC
- Start a small-scale IO-Link  
IO-Link and other unique I/O systems can be easily integrated into existing machine configurations

### Easy configuration with NX-IO Configurator



The NX-IO Configurator is software to set up and maintain EtherNet/IP coupler units and NX I/O Units on an EtherNet/IP coupler

FA Integrated Tool Package CX-One

CJ Series  
or  
PLC from  
other  
vendors



CJ Programmable Controller\*2



PLC from other vendors\*3



EtherNet/IP

W451  
Industrial Switching Hub



IO-Link



IO-Link

\*2. Dedicated software is required to use the CJ PLC or other vendor's PLC with the NX Safety Units.

\*3. Connect the NX I/O system to a PLC from another vendor via a switching hub and set up with the CX-One.

# Various software components help reduce programming time

The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX Machine Automation Controllers or Industrial PC Platform NY IPC Machine Controllers.

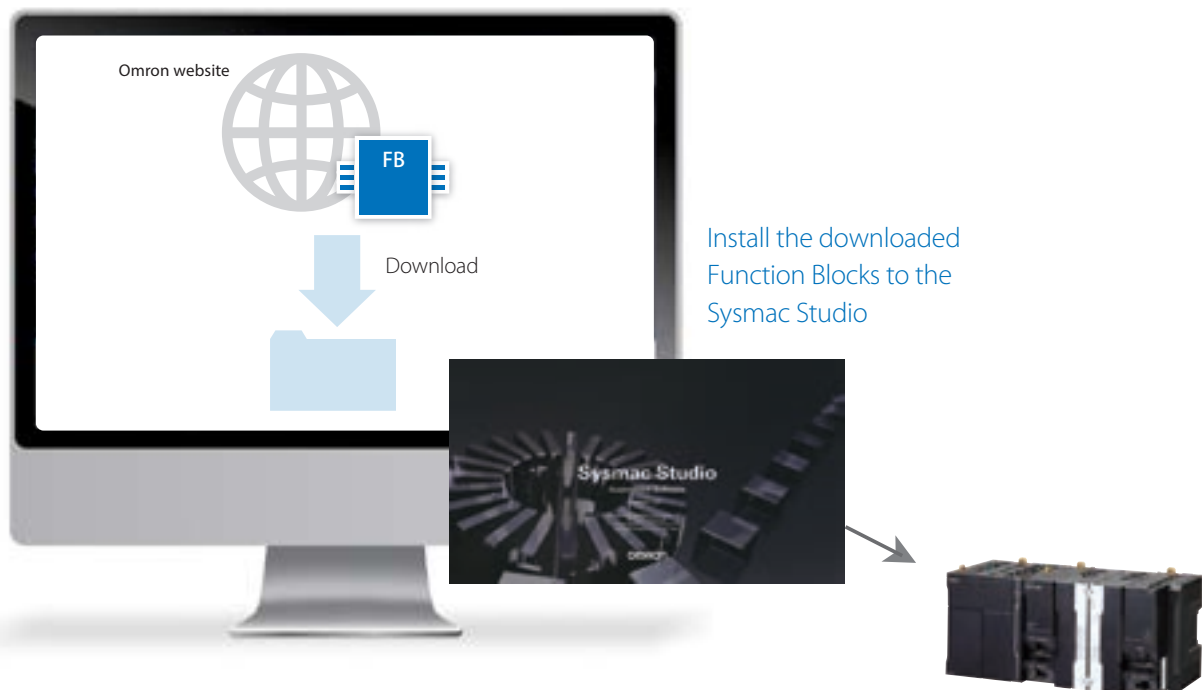
Packed with Omron's rich technical know-how on control programs, the Sysmac Library makes advanced control easy.



## Easy-to-obtain Library

The Sysmac Library is freely available to download from Omron website.

These software components specially designed for the NJ/NX/NY Controller can be used in your programs without the need for additional work.



Download from

[http://www.ia.omron.com/sysmac\\_library/](http://www.ia.omron.com/sysmac_library/)

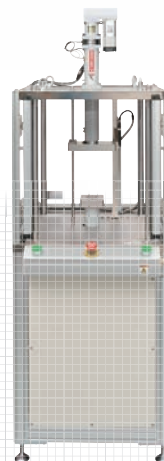
Note: Ask your Omron representative to obtain Libraries that are not provided on the above website.

## Application example (1) Load cells

# Press fit using servo press

### Improve both speed and quality of the press-fit process

Load data is collected in synchronization with the CPU cycle for high-speed measurement, high-speed servo press control, and precision improvement.



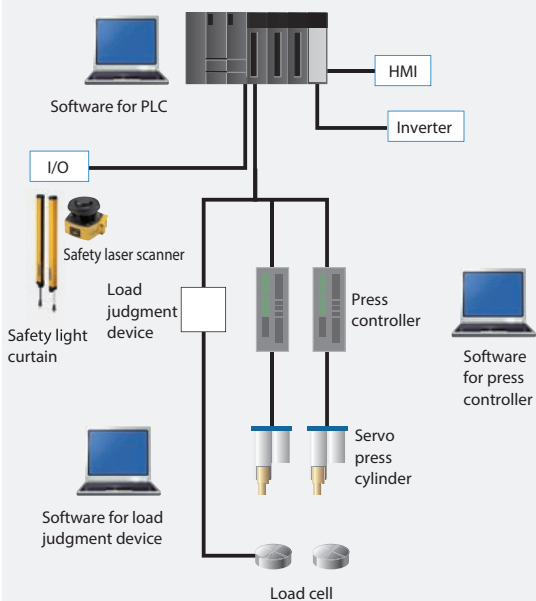
#### Previous issues

- Wait time must be considered to operate the dedicated press controller together with the main PLC.
- Load, position, and torque data collected at the same time cannot be checked from the host device.

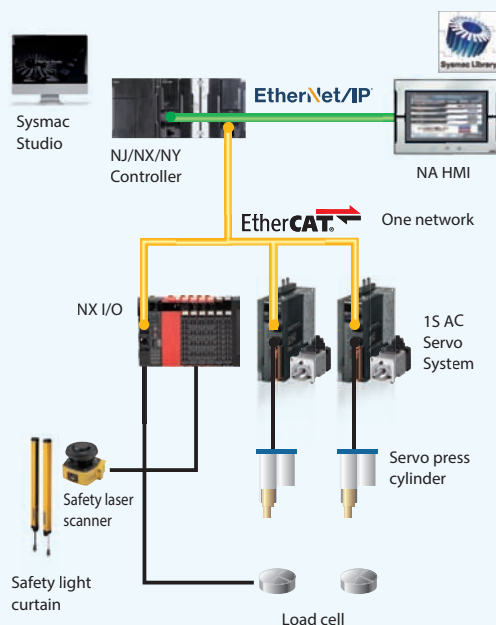
#### Solution using Sysmac

- One CPU system capable of switching between position, velocity, and torque control without stopping
- Fastest control cycle of 125  $\mu$ s and servo press function using software for required control
- High-speed measurement and control by collecting load data synchronized with servo data (position and torque data).

#### FROM Conventional system (Ex. multi-axis)



#### TO NJ/NX/NY Controller + NX I/O + 1S Servo integrate control elements



# Application example (2) Temperature control

## Packaging machines and molding machines

(Temperature/motion/weighing)

### Reduce material and design costs to implement temperature control

TCO can be reduced by eliminating the need for the dedicated temperature controller and reducing inventory control work and communications programming work.

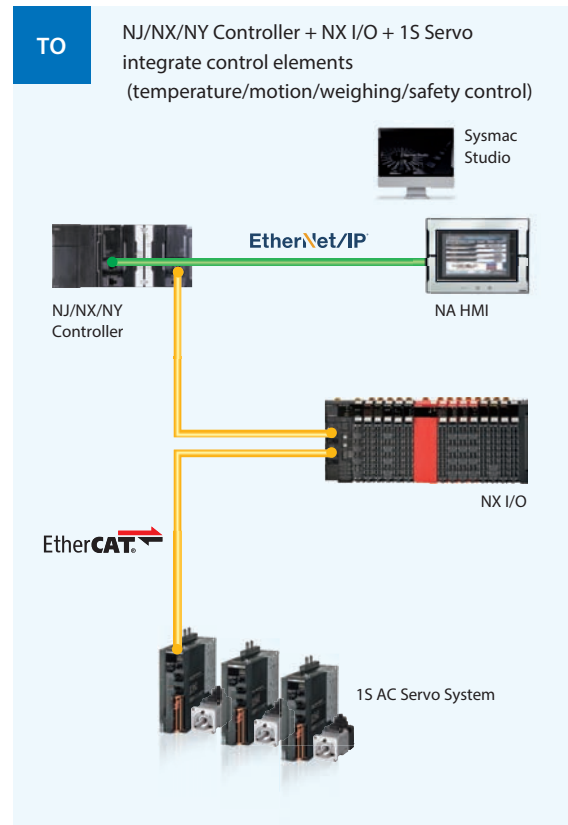
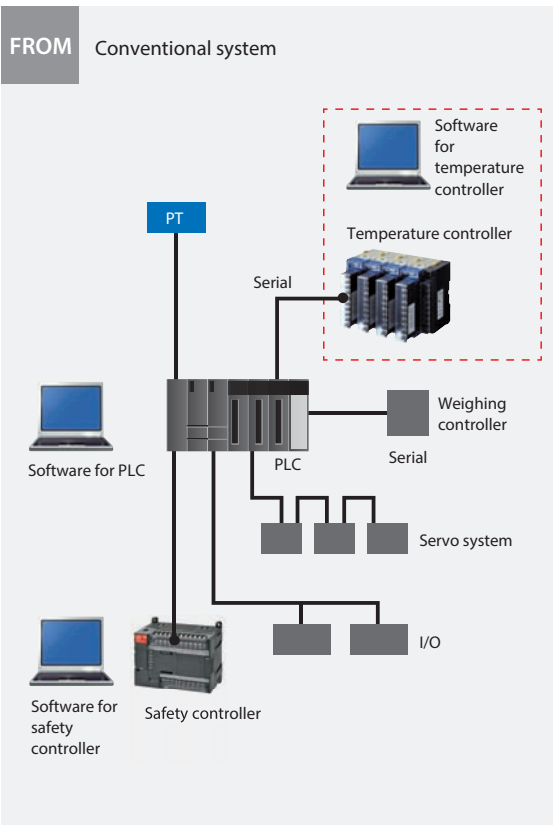


#### Previous issues

- Communications networks are selected for each device, and dedicated software for each component is used.
- Ladder program and memory configuration for communications are required.

### Solution using Sysmac

- Dedicated controllers, dedicated software, separate networks, and separate programs are no longer required





# Application example (3) Photoelectric sensors and proximity sensors

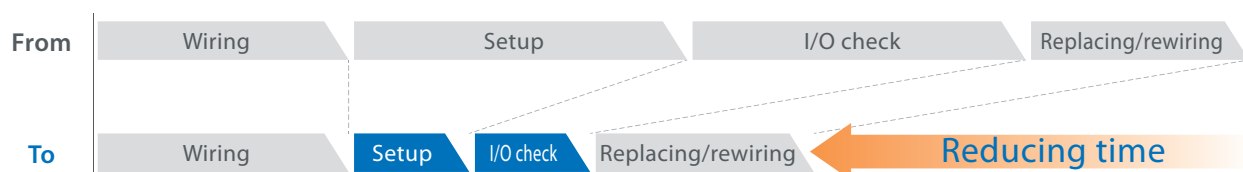
## Improving system commissioning and changeover efficiency

### Reduce work by individual identification

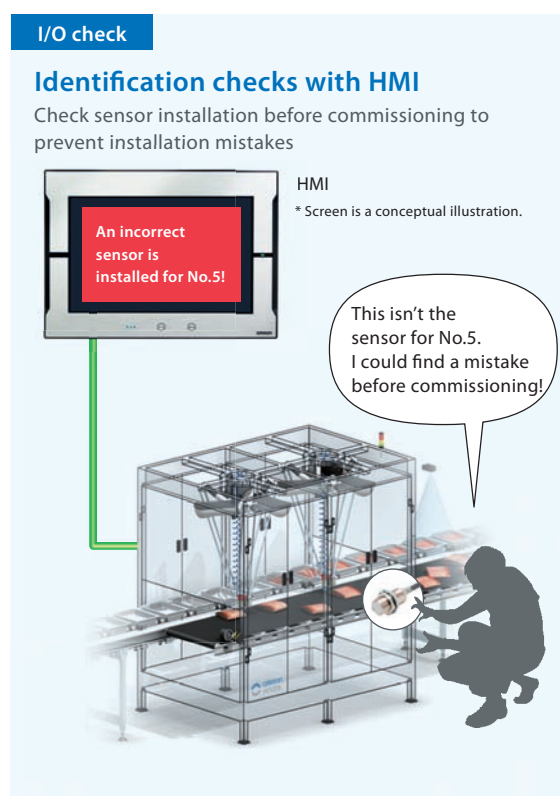
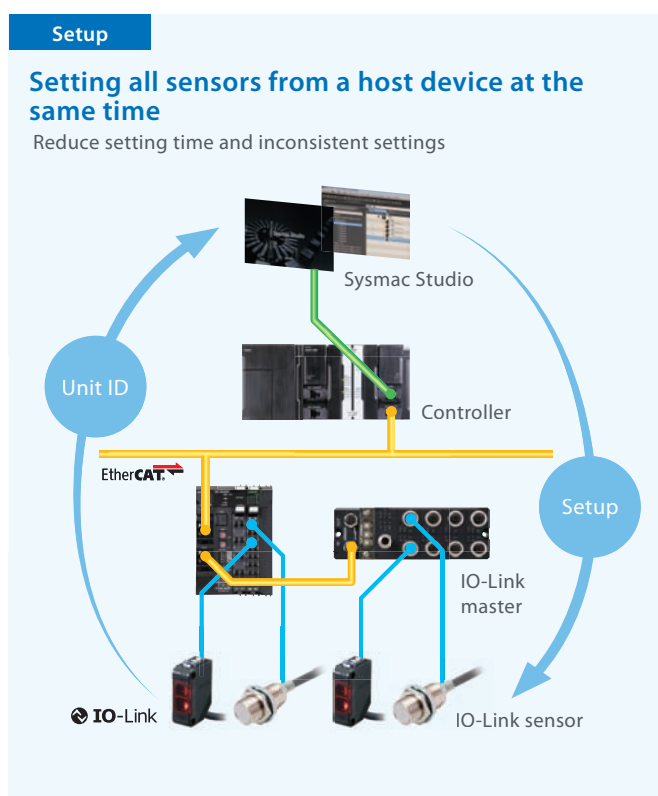
IO-Link sensors allow you to check individual sensor identifications in batches without going to the site, which results in a significant reduction of commissioning time.

#### Previous issues

- During system commissioning or changeover, operators have to perform the I/O check for each of the thousands of sensors installed on the line, and it took an enormous amount of time.
- Incorrect sensor installation creates unnecessary extra work.



\* The graph above is a conceptual illustration.



## Application example (4) Traceability using RFID

# Improving system commissioning efficiency

### Reduce time required for system design and wiring

Distributed installation of RFID units simplifies system design and wiring, even for high-mix production.

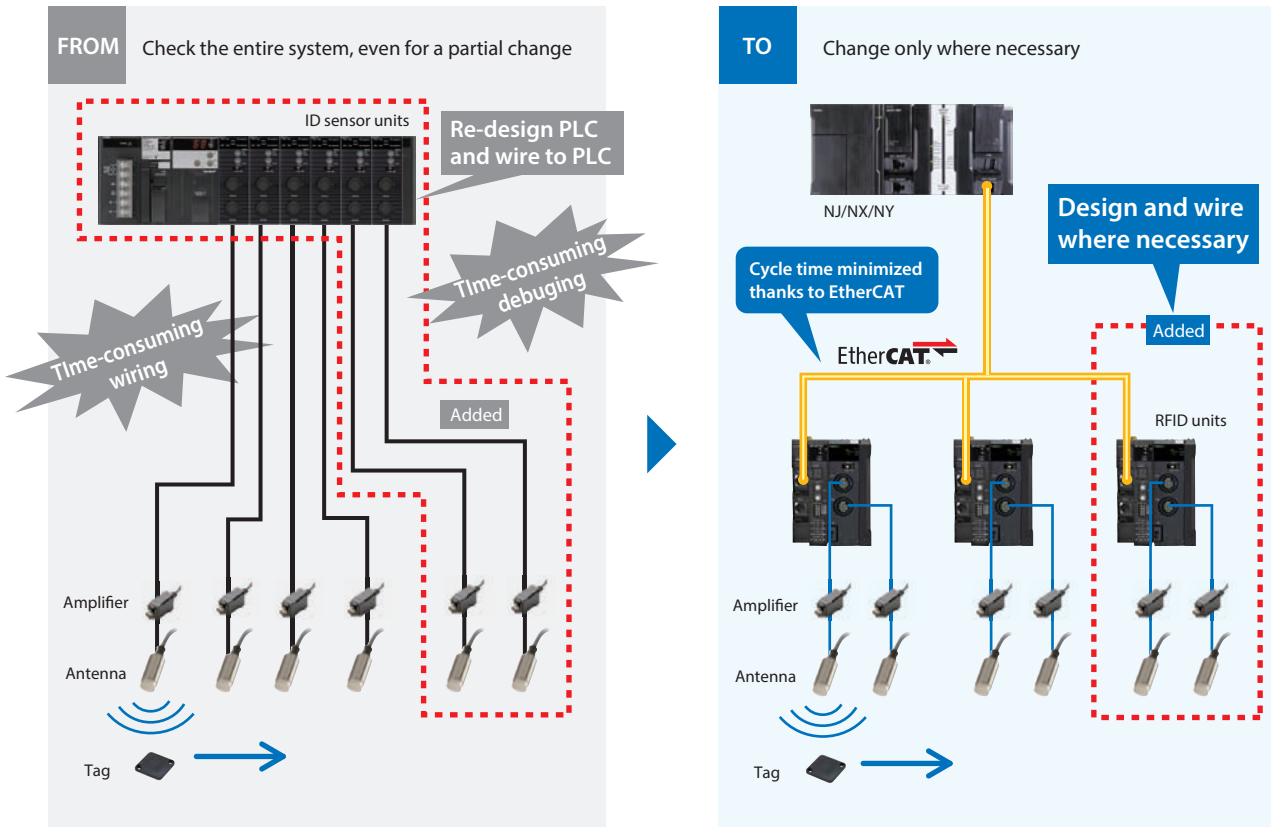


#### Previous issues

- When the system configuration is changed, it requires considerable time and effort to re-design and debug the entire program because ID sensor units cannot be distributed.
- It is difficult and time-consuming to wire an additional antenna to the ID sensor unit that is located away from it.

#### Solution using Sysmac

- The RFID units can be installed near each antenna, allowing addition or change of programs only where necessary and reducing wiring time



EtherNet/IP connection is also available.

# Slave Terminals **NX Series**


## Ordering Information

### Applicable standards

Refer to the OMRON website ([www.ia.omron.com](http://www.ia.omron.com)) or ask your OMRON representative for the most recent applicable standards for each model.

## Communications Coupler Units


### EtherCAT Coupler Units

Product name	Communications cycle in DC Mode	Current consumption	Maximum I/O power supply current	Model
	250 to 4000 $\mu$ s *2	1.45 W or lower	4 A	<b>NX-ECC201</b>
	250 to 4000 $\mu$ s *2		10 A	<b>NX-ECC202</b>
	125 to 10000 $\mu$ s *2	1.25 W or lower		<b>NX-ECC203</b>

\*1. One End Cover NX-END01 is provided with the EtherCAT Coupler Unit.


\*2. This depends on the specifications of the EtherCAT master. For example, the values are as follows when the EtherCAT Coupler Unit is connected to the built-in EtherCAT port on an NJ5-series CPU Unit: 500  $\mu$ s, 1,000  $\mu$ s, 2,000  $\mu$ s, and 4,000  $\mu$ s. For the specifications of the built-in EtherCAT port, refer to the user's manual for the built-in EtherCAT port on the connected CPU Unit or the Industrial PC. This depends on the Unit configuration.

### EtherNet/IP Coupler Unit

Product name	Current consumption	Maximum I/O power supply current	Model
	1.60 W or lower	10 A	<b>NX-EIC202</b>

\* One End Cover NX-END01 is provided with the EtherCAT Coupler Unit.






## EtherCAT Slave Unit

Product name	Specifications		Model
	Send/receive PDO data sizes *	Refreshing method	
	<ul style="list-style-type: none"> <li>Data input by the EtherCAT master (TxPDOs) 1,204 bytes max.</li> <li>Data output by the EtherCAT master (RxPDOs) 1,200 bytes max.</li> </ul>	Free-Run Mode	<b>NX-ECT101</b>

\* The following shows the contents of the TxPDO data.






- I/O data set from the CPU Unit to the EtherCAT master: 1,200 bytes or less
- Status to notify the EtherCAT master: 4 bytes or less

Digital Input Units

Product Name	Specifications					Model	
	Number of points	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time		
<b>DC Input Unit</b>  (Screwless Clamping Terminal Block, 12 mm Width/ 24 mm Width)	4 points	NPN	12 to 24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	<b>NX-ID3317</b>	
			24 VDC		Input refreshing with input changed time only *	100 ns max./100 ns max.	<b>NX-ID3343</b>
			12 to 24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing		20 μs max./400 μs max.	<b>NX-ID3417</b>
		24 VDC	PNP		Input refreshing with input changed time only *	100 ns max./100 ns max.	<b>NX-ID3443</b>
						24 VDC	NPN
				<b>NX-ID4442</b>			
	16 points	PNP	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	<b>NX-ID5342</b>	
	32 points				NPN	<b>NX-ID5442</b>	
			PNP			<b>NX-ID6342</b> <i>NEW</i>	
						<b>NX-ID6442</b> <i>NEW</i>	
<b>DC Input Unit</b>  (M3 Screw Terminal Block, 30 mm Width)	16 points	For both NPN/PNP	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	<b>NX-ID5142-1</b>	
<b>DC Input Unit</b>  (MIL Connector, 30 mm Width)	16 points	For both NPN/PNP	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	<b>NX-ID5142-5</b>	
	32 points					<b>NX-ID6142-5</b>	
<b>DC Input Unit</b>  (Fujitsu/OTAX Connector, 30 mm Width)	32 points	For both NPN/PNP	24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	<b>NX-ID6142-6</b>	
<b>AC Input Unit</b>  (Screwless Clamping Terminal Block, 12 mm Width)	4 points	200 to 240 VAC, 50/60 Hz (170 to 264 VAC, ±3 Hz)		Free-Run refreshing	10 ms max./40 ms max.	<b>NX-IA3117</b>	



\* To use input refreshing with input changed time, the EtherCAT Coupler Unit with unit version 1.1 or later and the Sysmac Studio version 1.07 or higher are required.

Digital Output Units

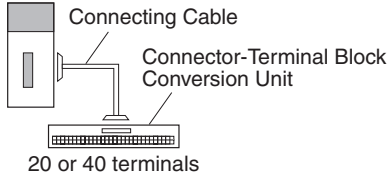
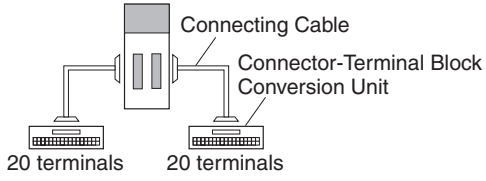
Product Name	Specifications						Model
	Number of points	Internal I/O common	Maximum value of load current	Rated voltage	I/O refreshing method	ON/OFF response time	
<b>Transistor Output Unit</b>  (Screwless Clamping Terminal Block, 12 mm Width/ 24 mm Width)	2 points	NPN	0.5 A/point, 1 A/ Unit	24 VDC	Output refreshing with specified time stamp only *	300 ns max./ 300 ns max.	NX-OD2154
		PNP				NX-OD2258	
	4 points	NPN	0.5 A/point, 2 A/ Unit	12 to 24 VDC	Switching Synchronous I/O refreshing and Free- Run refreshing	0.1 ms max./ 0.8 ms max.	NX-OD3121
						300 ns max./ 300 ns max.	NX-OD3153
		PNP		24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD3256
				2 A/point, 8 A/Unit		300 ns max./ 300 ns max.	NX-OD3257
	8 points	NPN	0.5 A/point, 4 A/ Unit	12 to 24 VDC	0.1 ms max./ 0.8 ms max.	NX-OD4121	
		PNP		24 VDC	0.5 ms max./ 1.0 ms max.	NX-OD4256	
	16 points	NPN	0.5 A/point, 4 A/ Unit	12 to 24 VDC	0.1 ms max./ 0.8 ms max.	NX-OD5121	
		PNP		24 VDC	0.5 ms max./ 1.0 ms max.	NX-OD5256	
	32 points	NPN	0.5 A/point, 4 A/ terminal block, 8 A/Unit	12 to 24 VDC	0.1 ms max./ 0.8 ms max.	NX-OD6121 <i>NEW</i>	
		PNP		24 VDC	0.5 ms max./ 1.0 ms max.	NX-OD6256 <i>NEW</i>	
<b>Transistor Output Unit</b>  (M3 Screw Terminal Block, 30 mm Width)	16 points	NPN	0.5 A/point, 5 A/ Unit	12 to 24 VDC	Switching Synchronous I/O refreshing and Free- Run refreshing	0.1 ms max./ 0.8 ms max.	NX-OD5121-1
		PNP		24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD5256-1
<b>Transistor Output Unit</b>  (MIL Connector, 30 mm Width)	16 points	NPN	0.5 A/point, 2 A/ Unit	12 to 24 VDC	Switching Synchronous I/O refreshing and Free- Run refreshing	0.1 ms max./ 0.8 ms max.	NX-OD5121-5
		PNP		24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD5256-5
	32 points	NPN	0.5 A/point, 2 A/ common, 4 A/Unit	12 to 24 VDC		0.1 ms max./ 0.8 ms max.	NX-OD6121-5
		PNP		24 VDC		0.5 ms max./ 1.0 ms max.	NX-OD6256-5
<b>Transistor Output Unit</b>  (Fujitsu/OTAX Connector, 30 mm Width)	32 points	NPN	0.5 A/point, 2 A/ common, 4 A/Unit	12 to 24 VDC	Switching Synchronous I/O refreshing and Free- Run refreshing	0.1 ms max./ 0.8 ms max.	NX-OD6121-6
<b>Relay Output Unit</b>  (Screwless Clamping Terminal Block, 12 mm Width/24 mm Width)	2 points	Relay type: N.O.	250 VAC/2 A (cosφ=1), 250 VAC/ 2 A (cosφ=0.4), 24 VDC/2 A, 4 A/ Unit		Free-Run refreshing	15 ms max./ 15 ms max.	NX-OC2633
		Relay type: N.O.+N.C.					NX-OC2733
	8 points	Relay type: N.O.	250 VAC/2 A (cosφ=1), 250 VAC/ 2 A (cosφ=0.4), 24 VDC/2 A, 8 A/ Unit		Free-Run refreshing	15 ms max./ 15 ms max.	NX-OC4633

\* To use output refreshing with specified time stamp, the EtherCAT Coupler Unit with unit version 1.1 or later and the Sysmac Studio version 1.07 or higher are required.

**Digital Mixed I/O Units**

Product Name	Specifications					Model
	Number of points	Internal I/O common	Maximum value of load current	I/O refreshing method	ON/OFF response time	
<b>DC Input/Transistor Output Unit</b>  (MIL Connector, 30 mm Width)	Outputs: 16 points Inputs: 16 points	Outputs: NPN Inputs: For both NPN/PNP	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	Outputs: 0.1 ms max./ 0.8 ms max. Inputs: 20 μs max./ 400 μs max.	<b>NX-MD6121-5</b>
		Outputs: PNP Inputs: For both NPN/PNP	Outputs: 24 VDC Inputs: 24 VDC		Outputs: 0.5 ms max./ 1.0 ms max. Inputs: 20 μs max./ 400 μs max.	
<b>DC Input/Transistor Output Unit</b>  (Fujitsu/OTAX Connector, 30 mm Width)	Outputs: 16 points Inputs: 16 points	Outputs: NPN Inputs: For both NPN/PNP	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Synchronous I/O refreshing and Free-Run refreshing	Outputs: 0.1 ms max./ 0.8 ms max. Inputs: 20 μs max./ 400 μs max.	<b>NX-MD6121-6</b>

Connection Patterns for Connector-Terminal Block Conversion Units

Pattern	Configuration	Number of connectors	Branching
A	 <p>Connecting Cable Connector-Terminal Block Conversion Unit 20 or 40 terminals</p>	1	None
B	 <p>Connecting Cable Connector-Terminal Block Conversion Unit 20 terminals 20 terminals</p>	2	None

Connections to Connector-Terminal Block Conversion Units

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Connecting Cable *	Connector-Terminal Block Conversion Unit	Wiring method	Common terminal
NX-ID5142-5	16 inputs	1 MIL connector	NPN/ PNP	A	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No
					XW2Z-□□□X-R	XW2K-20G-O16A-IN	Push-In Plus	Yes
					XW2Z-□□□X	XW2D-20G6	Phillips screw	No
					XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No
NX-ID6142-5	32 inputs	1 MIL connector	NPN/ PNP	A	XW2Z-□□□K	XW2K-40G-O32C	Push-In Plus	No
				A	XW2Z-□□□K	XW2K-40G-O32C-IN	Push-In Plus	Yes
				A	XW2Z-□□□K	XW2R-J34GD-C2	Phillips screw	No
				A	XW2Z-□□□K	XW2D-40G6	Phillips screw	No
				A	XW2Z-□□□K	XW2R-E34GD-C2	Slotted screw (rise up)	No
NX-ID6142-6	32 inputs	1 Fujitsu/ OTAX connector	NPN/ PNP	A	XW2Z-□□□B	XW2K-40G-O32A	Push-In Plus	No
				A	XW2Z-□□□B	XW2K-40G-O32A-IN	Push-In Plus	Yes
				A	XW2Z-□□□B	XW2R-J34GD-C1	Phillips screw	No
				A	XW2Z-□□□B	XW2D-40G6	Phillips screw	No
				A	XW2Z-□□□B	XW2R-E34GD-C1	Slotted screw (rise up)	No
NX-OD5121-5	16 outputs	1 MIL connector	NPN	A	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No
				A	XW2Z-□□□X-R	XW2K-20G-O16B-OUT	Push-In Plus	Yes
				A	XW2Z-□□□X	XW2D-20G6	Phillips screw	No
				A	XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No
NX-OD5256-5	16 outputs	1 MIL connector	PNP	A	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No
				A	XW2Z-□□□X-R	XW2K-20G-O16B-OUT	Push-In Plus	Yes
				A	XW2Z-□□□X	XW2D-20G6	Phillips screw	No
				A	XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No

# Slave Terminals NX Series

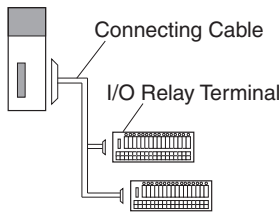
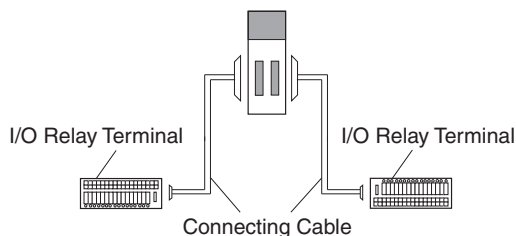
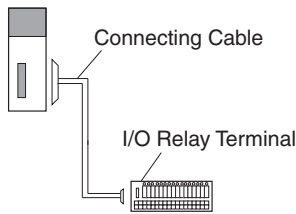
Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Connecting Cable *	Connector-Terminal Block Conversion Unit	Wiring method	Common terminal	
NX-OD6121-5	32 outputs	1 MIL connector	NPN	A	XW2Z-□□□K	XW2K-40G-O32C	Push-In Plus	No	
				A	XW2Z-□□□K	XW2K-40G-O32C-OUT	Push-In Plus	Yes	
				A	XW2Z-□□□K	XW2R-J34GD-C4	Phillips screw	No	
				A	XW2Z-□□□K	XW2D-40G6	Phillips screw	No	
				A	XW2Z-□□□K	XW2R-E34GD-C4	Slotted screw (rise up)	No	
NX-OD6121-6	32 outputs	1 Fujitsu/OTAX connector	NPN	A	XW2Z-□□□B	XW2K-40G-O32B	Push-In Plus	No	
				A	XW2Z-□□□B	XW2K-40G-O32B-OUT	Push-In Plus	Yes	
				A	XW2Z-□□□B	XW2R-J34GD-C3	Phillips screw	No	
				A	XW2Z-□□□B	XW2D-40G6	Phillips screw	No	
				A	XW2Z-□□□B	XW2R-E34GD-C3	Slotted screw (rise up)	No	
NX-OD6256-5	32 outputs	1 MIL connector	PNP	A	XW2Z-□□□K	XW2K-40G-O32C	Push-In Plus	No	
				A	XW2Z-□□□K	XW2K-40G-O32C-OUT	Push-In Plus	Yes	
				A	XW2Z-□□□K	XW2R-J34GD-C4	Phillips screw	No	
				A	XW2Z-□□□K	XW2D-40G6	Phillips screw	No	
				A	XW2Z-□□□K	XW2R-E34GD-C4	Slotted screw (rise up)	No	
NX-MD6121-5	16 inputs	1 MIL connector	NPN/PNP	B	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No	
				B	XW2Z-□□□X-R	XW2K-20G-O16A-IN	Push-In Plus	Yes	
				B	XW2Z-□□□X	XW2D-20G6	Phillips screw	No	
				B	XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No	
	16 outputs	1 MIL connector	NPN	NPN	B	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No
					B	XW2Z-□□□X-R	XW2K-20G-O16B-OUT	Push-In Plus	Yes
					B	XW2Z-□□□X	XW2D-20G6	Phillips screw	No
					B	XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No
NX-MD6121-6	16 inputs	1 Fujitsu/OTAX connector	NPN/PNP	B	XW2Z-□□□A	XW2K-20G-T	Push-In Plus	No	
				B	XW2Z-□□□A	XW2K-20G-O16A-IN	Push-In Plus	Yes	
				B	XW2Z-□□□A	XW2D-20G6	Phillips screw	No	
				B	XW2Z-□□□A	XW2R-E20GD-T	Slotted screw (rise up)	No	
	16 outputs	1 Fujitsu/OTAX connector	NPN	NPN	B	XW2Z-□□□A	XW2K-20G-T	Push-In Plus	No
					B	XW2Z-□□□A	XW2K-20G-O16B-OUT	Push-In Plus	Yes
					B	XW2Z-□□□A	XW2D-20G6	Phillips screw	No
					B	XW2Z-□□□A	XW2R-E20GD-T	Slotted screw (rise up)	No
NX-MD6256-5	16 inputs	1 MIL connector	NPN/PNP	B	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No	
				B	XW2Z-□□□X-R	XW2K-20G-O16A-IN	Push-In Plus	Yes	
				B	XW2Z-□□□X	XW2D-20G6	Phillips screw	No	
				B	XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No	
	16 outputs	1 MIL connector	NPN	NPN	B	XW2Z-□□□X	XW2K-20G-T	Push-In Plus	No
					B	XW2Z-□□□X-R	XW2K-20G-O16B-OUT	Push-In Plus	Yes
					B	XW2Z-□□□X	XW2D-20G6	Phillips screw	No
					B	XW2Z-□□□X	XW2R-E20GD-T	Slotted screw (rise up)	No

**Note:** For other models and specifications that are not listed above, refer to the *XW2K Series Datasheet* (Cat. No. G152), *XW2R Datasheet* and *XW2D Series Datasheet* for details.

\* □□□ in the model number indicates the cable length. Refer to the *XW2Z Datasheet* for details.



Connection Patterns for I/O Relay Terminals

Pattern	Configuration	Number of connectors	Branching
A		1	2 branches
E		2	None
F		1	

Connections to I/O Relay Terminals

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Number of branches	Connecting Cable *1	I/O Relay Terminal	Wiring method
NX-ID5142-5	16 inputs	1 MIL connector	NPN	F	None	XW2Z-RO□C	G7TC-ID16	Phillips screw
				F	None	XW2Z-RO□C	G7TC-IA16	Phillips screw
				F	None	XW2Z-RO□C	G70V-SID16P	Push-in spring
				F	None	XW2Z-RO□C	G70V-SID16P-C16	Push-in spring
			PNP	F	None	XW2Z-RO□C	G70V-SID16P-1	Push-in spring
				F	None	XW2Z-RO□C	G70V-SID16P-1-C16	Push-in spring
NX-ID6142-5	32 inputs	1 MIL connector	NPN	A	2	XW2Z-RO□-□-D1	G7TC-ID16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G7TC-IA16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70V-SID16P	Push-in spring
				A	2	XW2Z-RO□-□-D1	G70V-SID16P-C16	Push-in spring
			PNP	A	2	XW2Z-RO□-□-D1	G70V-SID16P-1	Push-in spring
				A	2	XW2Z-RO□-□-D1	G70V-SID16P-1-C16	Push-in spring
NX-ID6142-6	32 inputs	1 Fujitsu/OTAX connector	NPN	A	2	XW2Z-RI□C-□	G7TC-ID16	Phillips screw
				A	2	XW2Z-RI□C-□	G7TC-IA16	Phillips screw
				A	2	XW2Z-RI□C-□	G70V-SID16P	Push-in spring
				A	2	XW2Z-RI□C-□	G70V-SID16P-C16	Push-in spring
			PNP	A	2	XW2Z-RI□C-□	G70V-SID16P-1	Push-in spring
				A	2	XW2Z-RI□C-□	G70V-SID16P-1-C16	Push-in spring
NX-OD5121-5	16 outputs	1 MIL connector	NPN	F	None	XW2Z-RO□C	G7TC-OC08	Phillips screw
				F	None	XW2Z-RO□C	G70D-SOC08	Phillips screw
				F	None	XW2Z-RO□C	G70R-SOC08 *2	Phillips screw
				F	None	XW2Z-RO□C	G7TC-OC16	Phillips screw
				F	None	XW2Z-RO□C	G70D-SOC16	Phillips screw
				F	None	XW2Z-RO□C	G70D-VSOC16	Phillips screw
				F	None	XW2Z-RO□C	G70D-FOM16	Phillips screw
				F	None	XW2Z-RO□C	G70D-VFOM16	Phillips screw
				F	None	XW2Z-RO□C	G70A-ZOC16-3	Phillips screw
				F	None	XW2Z-RO□C	G70V-SOC16P	Push-in spring
F	None	XW2Z-RO□C	G70V-SOC16P-C4	Push-in spring				

# Slave Terminals NX Series

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Number of branches	Connecting Cable #1	I/O Relay Terminal	Wiring method
NX-OD5256-5	16 outputs	1 MIL connector	PNP	F	None	XW2Z-RI□C	G7TC-OC16-1	Phillips screw
				F	None	XW2Z-RO□C	G70D-SOC16-1	Phillips screw
				F	None	XW2Z-RO□C	G70D-FOM16-1 *2	Phillips screw
				F	None	XW2Z-RO□C	G70A-ZOC16-4	Phillips screw
				F	None	XW2Z-RO□C	G70V-SOC16P-1	Push-in spring
				F	None	XW2Z-RO□C	G70V-SOC16P-1-C4	Push-in spring
NX-OD6121-5	32 outputs	1 MIL connector	NPN	A	2	XW2Z-RO□-□-D1	G7TC-OC16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G7TC-OC08	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-SOC16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-FOM16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-VSOC16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-VFOM16	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70A-ZOC16-3 and Relay	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70R-SOC08 *2	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-SOC08	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70V-SOC16P	Push-in spring
				A	2	XW2Z-RO□-□-D1	G70V-SOC16P-C4	Push-in spring
NX-OD6121-6	32 outputs	1 Fujitsu/OTAX connector	NPN	A	2	XW2Z-RO□C-□	G7TC-OC16	Phillips screw
				A	2	XW2Z-RO□C-□	G7TC-OC08	Phillips screw
				A	2	XW2Z-RO□C-□	G70D-SOC16	Phillips screw
				A	2	XW2Z-RO□C-□	G70D-FOM16	Phillips screw
				A	2	XW2Z-RO□C-□	G70D-VSOC16	Phillips screw
				A	2	XW2Z-RO□C-□	G70D-VFOM16	Phillips screw
				A	2	XW2Z-RO□C-□	G70A-ZOC16-3 and Relay	Phillips screw
				A	2	XW2Z-RO□C-□	G70R-SOC08 *2	Phillips screw
				A	2	XW2Z-RO□C-□	G70D-SOC08	Phillips screw
				A	2	XW2Z-RO□C-□	G70V-SOC16P	Push-in spring
				A	2	XW2Z-RO□C-□	G70V-SOC16P-C4	Push-in spring
NX-OD6256-5	32 outputs	1 MIL connector	PNP	A	2	XW2Z-RI□-□-D1	G7TC-OC16-1	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-SOC16-1	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70D-FOM16-1 *2	Phillips screw
				A	2	XW2Z-RO□-□-D1	G70A-ZOC16-4 and Relay	Phillips screw
NX-MD6121-5	16 inputs	1 MIL connector	NPN	E	None	XW2Z-RO□C	G7TC-ID16	Phillips screw
				E	None	XW2Z-RO□C	G7TC-IA16	Phillips screw
				E	None	XW2Z-RO□C	G70V-SID16P	Push-in spring
				E	None	XW2Z-RO□C	G70V-SID16P-C16	Push-in spring
	16 outputs	1 MIL connector	NPN	E	None	XW2Z-RO□C	G7TC-OC16	Phillips screw
				E	None	XW2Z-RO□C	G7TC-OC08	Phillips screw
				E	None	XW2Z-RO□C	G70D-SOC16	Phillips screw
				E	None	XW2Z-RO□C	G70D-FOM16	Phillips screw
				E	None	XW2Z-RO□C	G70D-VSOC16	Phillips screw
				E	None	XW2Z-RO□C	G70D-VFOM16	Phillips screw
				E	None	XW2Z-RO□C	G70A-ZOC16-3 and Relay	Phillips screw
				E	None	XW2Z-RO□C	G70R-SOC08 *2	Phillips screw
				E	None	XW2Z-RO□C	G70D-SOC08	Phillips screw
				E	None	XW2Z-RO□C	G70V-SOC16P	Push-in spring
E	None	XW2Z-RO□C	G70V-SOC16P-C4	Push-in spring				

Unit	I/O capacity	Number of connectors	Polarity	Connection pattern	Number of branches	Connecting Cable *1	I/O Relay Terminal	Wiring method
NX-MD6121-6	16 inputs	1 Fujitsu/OTAX connector	NPN	E	None	XW2Z-R□C	G7TC-ID16	Phillips screw
				E	None	XW2Z-R□C	G7TC-IA16	Phillips screw
				E	None	XW2Z-R□C	G70V-SID16P	Push-in spring
				E	None	XW2Z-R□C	G70V-SID16P-C16	Push-in spring
	16 outputs	1 Fujitsu/OTAX connector	NPN	E	None	XW2Z-R□C	G7TC-OC16	Phillips screw
				E	None	XW2Z-R□C	G7TC-OC08	Phillips screw
				E	None	XW2Z-R□C	G70D-SOC16	Phillips screw
				E	None	XW2Z-R□C	G70D-FOM16	Phillips screw
				E	None	XW2Z-R□C	G70D-VSOC16	Phillips screw
				E	None	XW2Z-R□C	G70D-VFOM16	Phillips screw
				E	None	XW2Z-R□C	G70A-ZOC16-3 and Relay	Phillips screw
				E	None	XW2Z-R□C	G70R-SOC08 *2	Phillips screw
				E	None	XW2Z-R□C	G70D-SOC08	Phillips screw
				E	None	XW2Z-R□C	G70V-SOC16P	Push-in spring
E	None	XW2Z-R□C	G70V-SOC16P-C4	Push-in spring				
NX-MD6256-5	16 inputs	1 MIL connector	PNP	E	None	XW2Z-RO□C	G70V-SID16P-1	Push-in spring
				E	None	XW2Z-RO□C	G70V-SID16P-1-C16	Push-in spring
	16 outputs	1 MIL connector	PNP	E	None	XW2Z-RO□C	G7TC-OC16-1	Phillips screw
				E	None	XW2Z-RI□C	G70D-SOC16-1	Phillips screw
				E	None	XW2Z-RI□C	G70D-FOM16-1 *2	Phillips screw
				E	None	XW2Z-RI□C	G70A-ZOC16-4 and Relay	Phillips screw
				E	None	XW2Z-RI□C	G70V-SOC16P-1	Push-in spring
				E	None	XW2Z-RI□C	G70V-SOC16P-1-C4	Push-in spring

**Note:** 1. For other models and specifications that are not listed above, refer to the datasheets.


2. The G70V Series includes models that provide internal connections. Refer to the *G70V Datasheet* (Cat. No. J215) for details.

3. The G70A is a socket only. Mountable relays and timers are sold separately.



\*1. □ in the model number indicates the cable length. Refer to the *XW2Z-R Datasheet* (Cat. No. G126) for details.

\*2. Product no longer available to order.



## High-speed Analog Input Units

Product name	Specification								Model
	Number of points	Input range	Resolution	Input method	Conversion time	Trigger input section		I/O refreshing method	
						Number of points	Internal I/O common		
High-speed Analog Input Units 	4 points	-10 to +10V -5 to +5V 0 to 10V 0 to 5V 1 to 5V 0 to 20mA 4 to 20mA	<ul style="list-style-type: none"> <li>Input range of -10 to 10 V or -5 to 5 V: 1/64,000 (full scale)</li> <li>Other input range: 1/32,000 (full scale)</li> </ul>	Differential input	5 μs per channel	4	NPN	Synchronous I/O refreshing	NX-HAD401
							PNP		NX-HAD402

## Analog Input Units



Product name	Specification									Model
	Number of points	Input range	Resolution	Conversion value, decimal number (0 to 100%)	Over all accuracy (25°C)	Input method	Conversion time	Input impedance	I/O refreshing method	
Voltage Input type 	2 points	-10 to +10 V	1/8000	-4000 to 4000	±0.2% (full scale)	Single-ended input Differential input	250 μs/point	1 MΩ min.	Free-Run refreshing	NX-AD2603 NX-AD2604
			1/30000	-15000 to 15000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD2608
	4 points		1/8000	-4000 to 4000	±0.2% (full scale)	Single-ended input Differential input	250 μs/point		Free-Run refreshing	NX-AD3603 NX-AD3604
			1/30000	-15000 to 15000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD3608
	8 points		1/8000	-4000 to 4000	±0.2% (full scale)	Single-ended input Differential input	250 μs/point		Free-Run refreshing	NX-AD4603 NX-AD4604
			1/30000	-15000 to 15000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD4608
Current Input type 	2 points	4 to 20 mA	1/8000	0 to 8000	±0.2% (full scale)	Single-ended input Differential input	250 μs/point	250 Ω	Free-Run refreshing	NX-AD2203 NX-AD2204
			1/30000	0 to 30000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD2208
	4 points		1/8000	0 to 8000	±0.2% (full scale)	Single-ended input Differential input	250 μs/point		Free-Run refreshing	NX-AD3203 NX-AD3204
			1/30000	0 to 30000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD3208
	8 points		1/8000	0 to 8000	±0.2% (full scale)	Single-ended input Differential input	250 μs/point		Free-Run refreshing	NX-AD4203 NX-AD4204
			1/30000	0 to 30000	±0.1% (full scale)	Differential input	10 μs/point		Selectable Synchronous I/O refreshing or Free-Run refreshing	NX-AD4208

## Analog Output Units



Product name	Specification							Model
	Number of points	Input range	Resolution	Output setting value, decimal number (0 to 100%)	Over all accuracy (25°C)	Conversion time	I/O refreshing method	
<b>Voltage Output type</b> 	2 points	-10 to +10 V	1/8000	-4000 to 4000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	<b>NX-DA2603</b>
			1/30000	-15000 to 15000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	<b>NX-DA2605</b>
	4 points		1/8000	-4000 to 4000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	<b>NX-DA3603</b>
			1/30000	-15000 to 15000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	<b>NX-DA3605</b>
<b>Current Output type</b> 	2 points	4 to 20 mA	1/8000	0 to 8000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	<b>NX-DA2203</b>
			1/30000	0 to 30000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	<b>NX-DA2205</b>
	4 points		1/8000	0 to 8000	±0.3% (full scale)	250 μs/point	Free-Run refreshing	<b>NX-DA3203</b>
			1/30000	0 to 30000	±0.1% (full scale)	10 μs/point	Selectable Synchronous I/O refreshing or Free-Run refreshing	<b>NX-DA3205</b>

## Advanced Temperature Control Units/Temperature Control Units/ Temperature Input Units/Heater Burnout Detection Units



### Advanced Temperature Control Units

Product name	Specification								Model	
	Number of channels	Input type	Output	Output capacity	CT Input capacity	Control type	Conversion time	I/O refreshing method		
<b>Advanced Temperature Control Unit 4Ch type</b> 	4 Ch	Universal inputs (thermocouple, platinum resistance thermometer, analog voltage, analog current)	Voltage output (for driving SSR)	4 points	4 points	Heating and Cooling Control	50 m sec	Free-Run refreshing	<b>NX-HTC3510-5</b>	
			Linear current output							
<b>Advanced Temperature Control Unit 8Ch type</b> 	8 Ch		Voltage output (for driving SSR)	8 points	8 points	Standard Control				<b>NX-HTC4505-5</b>

### Temperature Control Units

Product name	Specification								Model
	Number of channels	Input type	Output	Output capacity	CT Input capacity	Control type	Conversion time	I/O refreshing method	
<b>Temperature Control Unit 2Ch type</b> 	2 Ch	Multi-input (Thermocouple and Resistance thermometer)	Voltage output (for driving SSR)	2 points	2 points	Standard Control	50 m sec	Free-Run refreshing	<b>NX-TC2405</b>
					None	Standard Control			<b>NX-TC2406</b>
			Voltage output (for driving SSR)	4 points	None	Heating and Cooling Control			<b>NX-TC2407</b>
					Linear current output	2 points			None
<b>Temperature Control Unit 4Ch type</b> 	4 Ch		Voltage output (for driving SSR)	4 points	4 points	Standard Control			<b>NX-TC3405</b>
					None	Standard Control			<b>NX-TC3406</b>
			Voltage output (for driving SSR)	8 points	None	Heating and Cooling Control			<b>NX-TC3407</b>
					Linear current output	4 points			None


## Temperature Input Units

Product name	Specification							Model
	Number of points	Input type	Resolution (25°C)	Over all accuracy (25°C)	Conversion time	I/O refreshing method	Terminals	
 Thermocouple Input type	2 points	Thermocouple	0.1°C max. *1	Refer to your OMRON website for details.	250 ms/Unit	Free-Run refreshing	16 Terminals	NX-TS2101
	4 points						16 Terminals X 2	NX-TS3101
	2 points		0.01°C max.		10 ms/Unit		16 Terminals	NX-TS2102
	4 points				16 Terminals X 2		NX-TS3102	
	2 points		0.001°C max.		60 ms/Unit		16 Terminals	NX-TS2104
	4 points						16 Terminals X 2	NX-TS3104
 Resistance Thermometer Input type	2 points	Resistance Thermometer (Pt100/Pt1000, three-wire) *2	0.1°C max.	Refer to your OMRON website for details.	250 ms/Unit	Free-Run refreshing	16 Terminals	NX-TS2201
	4 points						16 Terminals X 2	NX-TS3201
	2 points		0.01°C max.		10 ms/Unit		16 Terminals	NX-TS2202
	4 points						16 Terminals X 2	NX-TS3202
	2 points		0.001°C max.		60 ms/Unit		16 Terminals	NX-TS2204
	4 points						16 Terminals X 2	NX-TS3204

\*1. The resolution is 0.2°C max. when the input type is R, S, or W.

\*2. The NX-TS2202 and NX-TS3202 only support Pt100 three-wire sensor.

## Heater Burnout Detection Units

Product name	Specification							Model
	CT input section		Control output section					
	Number of inputs	Maximum heater current	Number of outputs	Internal I/O common	Maximum load current	Rated voltage	I/O refreshing method	
 Heater Burnout Detection Unit	4	50 A AC	4	NPN	0.1 A/point, 0.4 A/Unit	12 to 24 VDC	Free-Run refreshing	NX-HB3101
				PNP		24 VDC		NX-HB3201


## Optional Products

Product name	Specification	Model
Unit/Terminal Block Coding Pins	Pins for 10 Units (30 terminal block pins and 30 Unit pins)	NX-AUX02

Product name	Specification	Model
Current Transformer (CT)	Hole diameter: 5.8 mm	E54-CT1
	Hole diameter: 5.8 mm	E54-CT1L *
	Hole diameter: 12.0 mm	E54-CT3
	Hole diameter: 12.0 mm	E54-CT3L *


\* Lead wires are included with these CTs. If UL certification is required, use these CTs.

## Load Cell Input Unit


Product name	Specification					Model
	Number of points	Conversion cycle	I/O refreshing method *	Load cell excitation voltage	Input range	
 Load Cell Input Unit	1	125 $\mu$ s	<ul style="list-style-type: none"> <li>Free-Run refreshing</li> <li>Synchronous I/O refreshing</li> <li>Task period prioritized refreshing</li> </ul>	5 VDC $\pm$ 10%	-5.0 to 5.0 mV/V	NX-RS1201

\* Refer to the *I/O Refreshing* in the *NX-series Load Cell Input Unit User's Manual* (Cat. No. W565) for detailed information on I/O refresh cycle.  
**Note:** The NX-RS1201-K Load Cell Input Unit with the test and calibration certificate is also available. Ask your OMRON representative for details.


## Position Interface Units: Incremental Encoder Input Units

Product name	Specification						Model
	Number of channels	External inputs	Maximum response frequency	I/O refreshing method	Number of I/O entry mappings	Remarks	
 Incremental Encoder Input Unit	1 (NPN)	3 (NPN)	500 kHz	<ul style="list-style-type: none"> <li>Free-Run refreshing</li> <li>Synchronous I/O refreshing</li> </ul>	1/1	24-V voltage input	NX-EC0112
	1 (PNP)	3 (PNP)					NX-EC0122
	1	3 (NPN)	4 MHz			Line receiver input	NX-EC0132
		3 (PNP)			NX-EC0142		
	2 (NPN)	None	500 kHz		2/2	24-V voltage input	NX-EC0212
	2 (PNP)						NX-EC0222

## Position Interface Units: SSI Input Units

Product name	Specification					Model
	Number of channels	Input/Output form	Maximum data length	Encoder power supply	Type of external connections	
 SSI Input Unit	1	EIA standard RS-422-A	32 bits	24 VDC, 0.3 A/CH	Screwless push-in terminal block (12 terminals)	NX-ECS112
	2	EIA standard RS-422-A	32 bits	24 VDC, 0.3 A/CH	Screwless push-in terminal block (12 terminals)	NX-ECS212

## Position Interface Units: Pulse Output Units




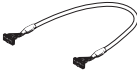
Product name	Specification							Model	
	Number of channels *1	External inputs	External outputs	Maximum pulse output speed	I/O refreshing method	Number of I/O entry mappings	Control output interface		
 Pulse Output Unit	1 (NPN)	2 (NPN)	1 (NPN)	500 kpps	<ul style="list-style-type: none"> <li>Synchronous I/O refreshing</li> <li>Task period prioritized refreshing *2</li> </ul>	1/1	Open collector output	NX-PG0112	
	1 (PNP)	2 (PNP)	1 (PNP)					NX-PG0122	
	2	5 inputs/CH (NPN)	3 outputs/CH (NPN)	4 Mpps		2/2	Line driver output	NX-PG0232-5	
		5 inputs/CH (PNP)	3 outputs/CH (PNP)					NX-PG0242-5	
	4	5 inputs/CH (NPN)	3 outputs/CH (NPN)			4/4		4/4	NX-PG0332-5
		5 inputs/CH (PNP)	3 outputs/CH (PNP)						NX-PG0342-5

\*1. This is the number of pulse output channels.

\*2. Unit version 1.2 or later and an NX-ECC203 EtherCAT Coupler Unit are required.


## Slave Terminals NX Series

### Cables and Connectors for Line Driver Output Units with MIL Connectors



Product name	Specifications		Model	
Connector-Terminal Block Conversion Unit	MIL Connectors type (Push-In Plus) 34 terminals		XW2K-34G-T	
	MIL Connectors type (Phillips screw) 34 terminals		XW2D-34G6	
	MIL Connectors type (Slotted screw (rise up)) 34 terminals		XW2R-E34GD-T	
Cable for Connector-Terminal Block Conversion Unit	34-terminal MIL Connector to 34-terminal MIL Connector		Cable length: 0.5 m	XW2Z-050EE
			Cable length: 1 m	XW2Z-100EE
			Cable length: 1.5 m	XW2Z-150EE
			Cable length: 2 m	XW2Z-200EE
			Cable length: 3 m	XW2Z-300EE
			Cable length: 5 m	XW2Z-500EE

**Note:** Each of NX-PG0232-5 and NX-PG0242-5 has one MIL connector. Therefore, one Connector-Terminal Block Conversion Unit is required.  
Each of NX-PG0332-5 and NX-PG0342-5 has two MIL connectors. Therefore, two Connector-Terminal Block Conversion Units are required.


### Communications Interface Units

Product name	Serial interface	External connection terminals	Number of serial ports	Communications function	Model
	RS-232C	Screwless clamping terminal block	1 port	<ul style="list-style-type: none"> <li>No-protocol serial communications</li> <li>Serial line monitor</li> </ul>	NX-CIF101
	RS-422A/485				NX-CIF105
	RS-232C	D-Sub connector	2 ports		NX-CIF210

### RFID Units

Product name	Amplifier/Antenna	No. of unit numbers used	Model
RFID Unit (1Ch) 	V680 series	1	NX-V680C1
RFID Unit (2Ch) 		2	NX-V680C2





### IO-Link Master Unit

Product name	Specification			Model
	Number of IO-Link ports	I/O refreshing method	I/O connection terminals	
IO-Link Master Unit 	4	Free-Run refreshing	Screwless clamping terminal block	NX-ILM400

**Note:** For details of IO-Link sensors and sensor I/O connectors, refer to the *IO-Link Series Catalog* (Cat. No. Y229).



## System Units

Product Name	Specifications	Model
<b>Additional NX Unit Power Supply Unit</b> 	Power supply voltage: 24 VDC (20.4 to 28.8 VDC) NX Bus power supply capacity: 10 W max.	<b>NX-PD1000</b>
<b>Additional I/O Power Supply Unit</b> 	Power supply voltage: 5 to 24 VDC (4.5 to 28.8 VDC) I/O power feed maximum current: 4 A	<b>NX-PF0630</b>
	Power supply voltage: 5 to 24 VDC (4.5 to 28.8 VDC) I/O power feed maximum current: 10 A	<b>NX-PF0730</b>
<b>I/O Power Supply Connection Unit</b> 	Number of I/O power terminals: IOG: 16 terminals Current capacity of I/O power terminal: 4 A/terminal max.	<b>NX-PC0010</b>
	Number of I/O power terminals: IOV: 16 terminals Current capacity of I/O power terminal: 4 A/terminal max.	<b>NX-PC0020</b>
	Number of I/O power terminals: IOV: 8 terminals, IOG: 8 terminals Current capacity of I/O power terminal: 4 A/terminal max	<b>NX-PC0030</b>
<b>Shield Connection Unit</b> 	Number of shield terminals: 14 terminals (The lower two terminals are functional ground terminals.)	<b>NX-TBX01</b>

## Optional Products and Maintenance Products



Product name	Specification	Model
<b>Unit/Terminal Block Coding Pins</b>	For 10 Units (Terminal Block: 30 pins, Unit: 30 pins)	<b>NX-AUX02</b>
<b>End Cover</b>	One End Cover is provided as a standard accessory with the Communication Coupler Unit.	<b>NX-END01</b>
<b>DIN Track Insulation Spacer</b>	A Spacer to insulate the control panel from the DIN Track. To insulate the Slave Terminal from the control panel, use Din Track Insulation Spacers.	<b>NX-AUX01</b>

Product name	Specification				Model
	No. of terminals	Terminal number indications	Ground terminal mark	Terminal current capacity	
<b>Terminal Block</b>	8	A/B	None	10 A	<b>NX-TBA082</b>
	12	A/B			<b>NX-TBA122</b>
	16	A/B			<b>NX-TBA162</b>
	12	C/D			<b>NX-TBB122</b>
	16	C/D			<b>NX-TBB162</b>
	8	A/B			Provided
	16	A/B	<b>NX-TBC162</b>		

# Safety Control Units **NX Series**



## Ordering Information

### Safety CPU Units

Unit type	Appearance	Specification					Model
		Maximum number of safety I/O points	Program capacity	Number of safety master connections	I/O refreshing method	Unit version	
Safety CPU Unit		256 points	512 KB	32	Free-Run refreshing	Ver.1.1	<b>NX-SL3300</b>
		1024 points	2048 KB	128	Free-Run refreshing	Ver.1.1	<b>NX-SL3500</b>



**Note:** Connect the Safety CPU Unit to the NX1P2 CPU Unit via the EtherCAT Coupler Unit.

### Safety Input Units

Unit type	Appearance	Specification								Model
		Number of safety input points	Number of test output points	Internal I/O common	Rated input voltage	OMRON special safety input devices	Number of safety slave connections	I/O refreshing method	Unit version	
Safety Input Unit		4 points	2 points	Sinking inputs (PNP)	24 VDC	Can be connected.	1	Free-Run refreshing	Ver.1.1	<b>NX-SIH400</b>
		8 points	2 points	Sinking inputs (PNP)	24 VDC	Cannot be connected.	1	Free-Run refreshing	Ver.1.0	<b>NX-SID800</b>

**Note:** Connect the Safety Input Unit to the NX1P2 CPU Unit via the EtherCAT Coupler Unit.

### Safety Output Units

Unit type	Appearance	Specification							Model
		Number of safety output points	Internal I/O common	Maximum load current	Rated voltage	Number of safety slave connections	I/O refreshing method	Unit version	
Safety Output Unit		2 points	Sourcing outputs (PNP)	2.0 A/point, 4.0 A/Unit at 40°C, and 2.5 A/Unit at 55°C The maximum load current depends on the installation orientation and ambient temperature.	24 VDC	1	Free-Run refreshing	Ver.1.0	<b>NX-SOH200</b>
		4 points	Sourcing outputs (PNP)	0.5 A/point and 2.0 A/Unit	24 VDC	1	Free-Run refreshing	Ver.1.0	<b>NX-SOD400</b>

**Note:** Connect the Safety Output Unit to the NX1P2 CPU Unit via the EtherCAT Coupler Unit.

## Optional Products

Product Name	Specification				Model
Unit/Terminal Block Coding Pins	For 10 Units (Terminal Block: 30 pins, Unit: 30 pins)				<b>NX-AUX02</b>
Product name	Specification				Model
	No. of terminals	Terminal number indications	Ground terminal mark	Terminal current capacity	
Terminal Block	8	A/B	None	10 A	<b>NX-TBA082</b>
	16	A/B	None	10 A	<b>NX-TBA162</b>

**MEMO**

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