

Draw advanced inspection closer within your reach

A new camera with advanced image processing functions









GUM

880 30 ac

The functionality and speed that your production site demands packed in an all-in-one device

The FHV7 Smart Camera is an all-in-one camera with the functionalities of the high-spec vision system FH Series packed in its compact, robust body that is easy to deploy. It provides almost all inspection and measurement functions of the FH Series, and allows for easier image inspections of matching quality, even in processes where inspection had previously been omitted due to restrictions in durability, space, and system deployment time.

Integrated controller structure

Smart camera FHV7 Series

Difficulties in processing product variation

Flexibly accommodates object changes

P.6

Harsh installation environments

A robust all-in-one body that makes it easy to install

P.4

0

Urgent need to improve manufacturing quality

The second

0

Excellent productivity performance

P.8

A robust all-in-one body that makes it easy to install

Installable anywhere

Integrated camera/controller structure

Integrates everything you need for image processing. All-in-one structure includes not only the controller but the lens and lights as well, allowing you to easily attach it wherever you want additional inspections or measurements, without having to worry about control panel space.







Robust structure

IP67 waterproof structure

IP67 compatible to allow use in wet conditions, such as regular wash-downs at the sites where the cameras are installed.

Captive screws

Replaceable modules use captive screws, to prevent problems caused by the screws falling into the production line, etc.

Replaceable covers

The light cover and optical filter are easy to remove and replace, so you don't need a protective cover, etc., against dirt.





Dirty cover filters can be removed separately for replacement

High scalability

External lights supported

The FLV and FL Series have a broad lineup of more than 150 models, and they can easily be attached as external lights to FHV7 Smart Cameras. By connecting the lighting controller, you can, from FHV7's setting window, easily adjust the light emission intensity and set light emissions to synchronize with the release of the shutter.



Flexibly accommodates object changes



Multi-color Light Accommodates color variations

Multi-color light provides a quick solution to the issue of measuring different colors. For example, objects with variously colored packages on a production line are properly measured with the light that changes its illumination color to fit each object. When the product design is changed or a new models is added, you can simply change a parameter instead of replacing or fine-tuning lights. The production line is always ready for a wider variety of product.

Autofocus Lens Accommodates size variations

The autofocus lens covers a focal length range from 59 mm to 2,000 mm^{*1}. Even when products in different sizes are produced, the focus range can be changed easily by parameters. ^{*2} This feature eliminates mechanical operation for changeover during product replacement, leading to a simpler system with higher productivity.

*1. Differs depending on the lens type. See the optical chart on page 52 for details.
*2. Set focuses for different product heights in advance and switch between them when you perform a changeover.



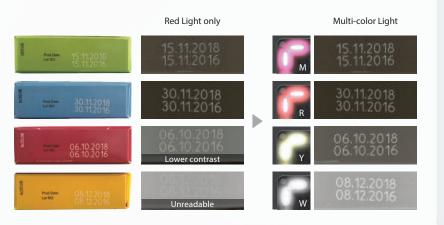
Best-in-class resolution^{*3}: 12 megapixels Location variation

The image sensor with a 12 megapixels enables highprecision inspections for wider areas. This eliminates the need for installing multiple cameras or a mechanism to move a camera to capture different inspection points on different models on the same production line.

*3. Based on Omron investigation in October 2018.



As a product has more color options, some of the colors may cause low contrast under a single color illumination. The multi-color illumination allows switching colors for different product color options, ensuring stable inspections.



Working distance 90mm→100mm

When inspecting products of different sizes

When inspecting products such as plastic bottles that come in different sizes, you can perform a changeover only by switching the setting of the autofocus lens. The autofocus lens does not need the mechanism for moving the camera.

Always in focus even when the focal length changes



Delicious safety

Expanding the range of parts inspection

Accurate and extensive inspection of parts mounting points on different automobile models is enabled without moving cameras. 5 Mpix







Excellent productivity performance

Best-in-class speed*1

Image capture Maximum speed 2.3 ms

Distributed processing across 2 cores

High-speed algorithm

High-speed processing

The all-in-one FHV7 Smart Camera is packed with capabilities garnered through the FH Series. Its high performance, comparable to a dedicated image processing system, supports advanced applications as well.

Clear images facilitate inspection

The FHV7 Smart Camera can measure 1.6 megapixels in 24 ms.

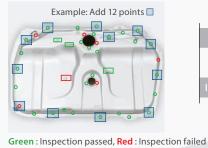
0.4 Mpix

1.6 Mpi>

It can perform high-resolution inspections without compromising speed capabilities, and can be used in places where image processing systems are currently deployed.

More inspection points

FHV7's high processing performance enables you to easily conduct inspections equivalent to an image processing system. It is optimal for multipoint inspections that would significantly compromise speed when conducted with traditional smart cameras.



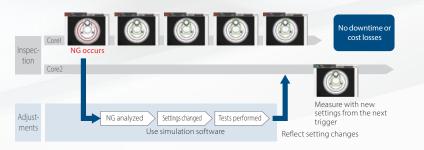


24 ms

Shorter inspection time even when the number of pixels is increased

Settings can be adjusted with zero downtime

Measured values may change gradually due to workpiece variation or changes in external circumstance. Even in such cases, distributed processing across 2 cores allows you to perform cause analysis and setting adjustments as you make measurements. You can eliminate downtime and visual inspection of uninspected items.



*1. Based on Omron investigation in October 2018.

*2. Sample comparison to inspection time using vision sensors installed in customer's machine. Based on Omron investigation in October 2018

Traceability and serial number management

The FHV7 Smart Camera is suitable for applications in which inspection results and images are managed by product serial numbers.

Stable reading regardless of printing quality

2D Code II delivers powerful code reading

The dedicated algorithm for stable 2D code reading under adverse conditions is implemented. Data based on the print quality specifications can be output, which contributes to stable printing.

Print Quality Grading Function

· ISO/IEC 15415

· ISO/IEC TR29158

Changing ambient brightness





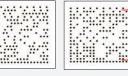




After processing/washing

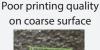


high-speed line



Variations in start Uneven line spacing

Poor printing quality in



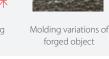


Chips due to reflection

Low contrast



positions



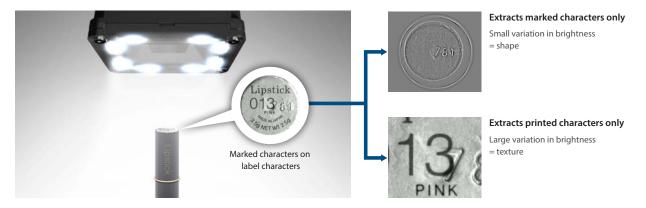
Stable reading of difficult-to-read characters (OCR)

Printed characters can be too close to each other, and characters can be printed on curved surfaces. Even in these cases, stable reading is possible. Also plus signs can be read.



Photometric stereo light extracts marked characters NEW

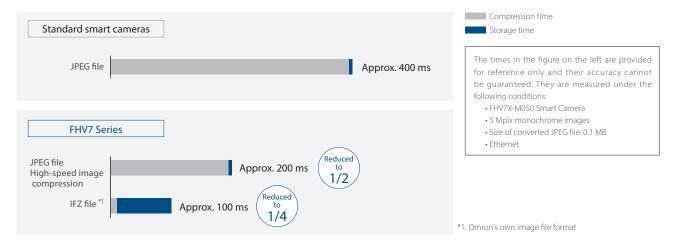
Our unique lighting algorithm separates an image into shapes and textures. Marked characters can be reliably read from the image containing only shapes which are separated from printed characters and patterns. This function is available when the FHV-LTM-W/R/IR Lighting Module (single color) or FL-PS Photometric Stereo Light is connected.



Evidence management

High-speed image storage and image compression

Image data is so large that conventional controllers could not store all images due to limited storage time and storage capacity. The FHV7 Smart Camera has algorithms and hardware that can save images in Omron formats and compress image data at high speed, enabling all images to be stored to meet increasing needs in guality control.



Images are saved even during measurements

Distributed processing across 2 cores allows the CPU to perform parallel processing of measurements and image logging. With connection to a high-speed, large-capacity NAS, all images on the high-speed line can be saved, which was previously difficult. *2 Trend analysis of all saved images quickly isolates errors and facilitates countermeasures.

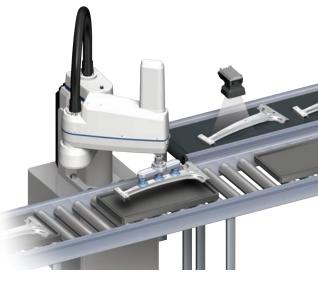
- *2. All images can be saved under the following conditions
 - One 0.4 Mpix camera
 - Measurement time of 30 ms
 - JPEG file
 - Images can be saved continuously for approx. 380 days when a 3 TB NAS is used (based on 8 hours of operation a day)

Standard smart cameras			
1	1 1	I	Issue
Priority on measurement Image input 1 Measurement	Image input 2 Measurement Imag	ge input 3 Measurement	Since logging was not possible during
processing	Image logging 1 Interruption	2 Interruption	measurement, the user had to choose either measurement or logging.
	The next image input is delayed		Accordingly, not all images could be saved or image input triggers had to be delayed
Priority on image logging Image input 1 Measurement	Image input 2	Measurement	depending on the measurement trigger intervals.
1	Image logging 1	Image logging 2	
FHV7 Series			
			Solution
Image input 1 Measurement	Image input 2 Measurement Image	ge input 3 Measurement	Measurement and image logging are
	Image logging 1 🔶 Imag	ge logging 2	processed in parallel. As a result, you can save all images.
	All images are save	ed	
1		1	

Application Examples

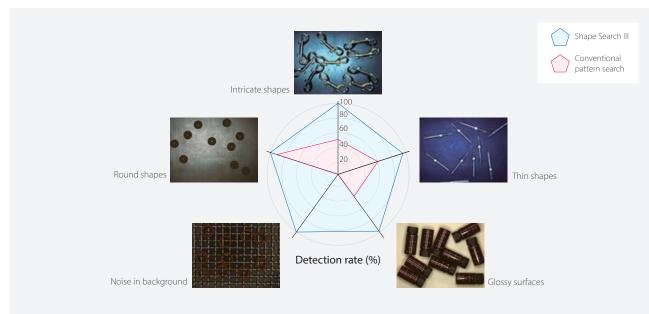
Pick and place

The FHV7 Smart Camera can be combined with robots for picking and assembling applications.



Shape Search III stably detects all types of objects

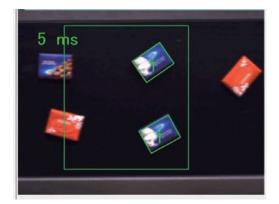
Stable position detection is performed regardless of shape, material, or background.



Sorting mixed models

Different types of the searched objects can be sorted.





Think & See, the core technology of Shape Search III

"Think & See" is Omron's powerful core technology for image sensing. Omron is continuously developing technologies to measure, detect, or identify the positions, orientations, shapes, materials, colors, status, or attributes of things, people, vehicles, or other objects faster, more precisely, and more easily than the human eye under various conditions.

Think &See



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Easy output to major robot manufacturers' devices

The dialog boxes for the FHV7 Smart Camera and the programs for various vendors' robots greatly reduce the set-up time for robot applications. Refer to the system configuration diagram (P. 22) for connection details.









3-step easy setting

Verified robot communication programs and flowcharts required for robot applications are provided. You don't need to design communications and create a flowchart to set up a robot application.

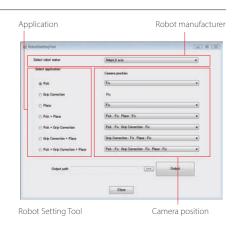
STEP 1

Obtain robot program and flowchart

Just a few clicks in Robot Setting Tool

Select 3 items to obtain the communication program and flowchart you need.

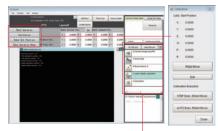
You can download the Robot Setting Tool from the following URL: http://www.ia.omron.com/fhv



STEP **2** Calibrate

Move robot for calibration from the FHV7 Series

The obtained flowchart can be used to move the robot for calibration from the FHV7 Smart Camera. There is no need to create a program for robot calibration.



Flowchart Move robot

STEP **3** Check operations

Set up and check application from the FHV7 Series

Set the coordinates of the robot and check robot operations using the dialog boxes.



Set the coordinates of the robot

operations

Application Examples

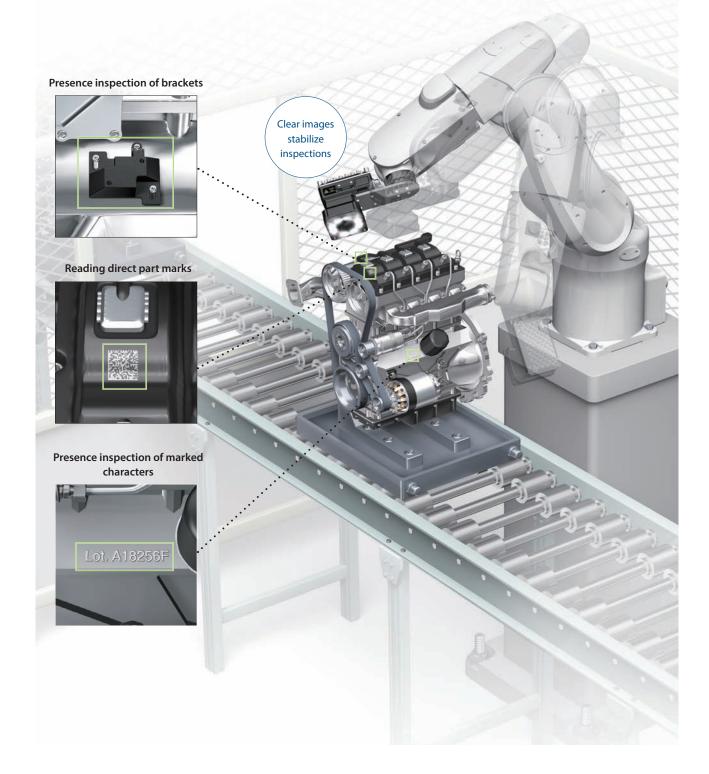
Flexible multipoint inspection using robots

The FHV7 Smart Camera can be installed on robot arms to inspect objects from multiple directions.

Vision inspection suited to each location

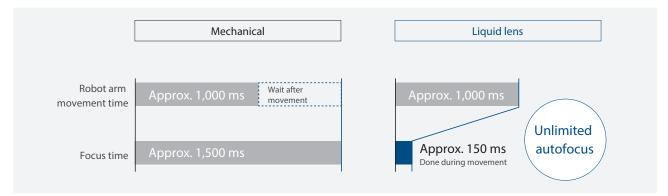
The FHV7 Smart Camera, which is moved to each inspection point, adjusts field of view, precision, and focus to match the location.

External inspection by the human eye can be replaced with automated inspection using robots.



Ultra-high-speed, long-life lens module PATENT PENDING *1

New high-speed lens modules using a liquid lens have been added to the lineup. Advanced control of the liquid lens enables the lens to focus about 10 times faster than a mechanical focus lens, allowing settings to be changed during movement of the robot arm.*² General mechanical focus mechanisms break due to deterioration of the drive mechanism or motor when they perform autofocus tens of thousands of times. The liquid lens provides unlimited autofocus and long life.



Note: The above times are when the focus value is changed from minimum to maximum. These times are provided for reference only and are not guaranteed. *1. "Patent pending" means that we applied for a patent in Japan, and "Patented" means that we obtained a patent in Japan. (As of April 2019) *2. Set focuses for different product heights in advance and switch between them.

Much less maintenance Super-flexible cable

The new cable offers approximately 10 times the bending resistance of conventional FHV7 flexible cables. High bending resistance significantly reduces the frequency of replacing the cables on robot arms.



Reduces halation from metallic or glossy surfaces

The High Dynamic Range (HDR) function minimizes the influence of changes in lighting conditions and light reflection. This enables stable inspections even for materials that are difficult to light evenly, such as metal parts or glossy films, or in locations subject to external light interference. Original image



Halation

Halation-reduced image



Stable detection for metallic surfaces subject to gloss and inconsistent lighting

Filtering to emphasize difficult-to-find defects

Image input & filtering



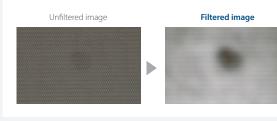
Stripe Removal Filter II 🖳

The stripped pattern is filtered out so that only required aspects are shown clearly. Vertical, horizontal, and diagonal stripes can be removed.



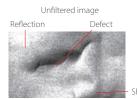
Even Emphasis Unevenness 🍖

This filter removes background pattern and enhances low-contrast unevenness.



Brightness Correct Filter

This filter cuts out uneven lighting and changes in brightness caused by workpiece surface irregularities to make characteristic features stand out clearly.



The wavy inconsistencies are judged as defects.



Uneven areas are removed so that only the defect appears in the inspection.

Anti Color Shading 📳 PATENTED



Specific shades that hide defects are removed so that tiny scratches and dirt can be precisely detected. This advanced filtering was achieved through the Real Color Sensing technology.



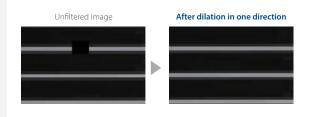
Emphasis Line Defect/Emphasis Circle Defect 둯

These filters enhance defects in high background noise or scratches on embossed surfaces.



Custom Filter 🐚

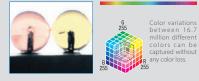
You can set the mask coefficients as required for these filters. The mask size can be up to 21 x 21. You can flexibly set smoothing, edge extraction, dilation, and erosion for the image.



Real Color Sensing PATENTED

Real-color processing is an image processing technology that performs high-speed processing of full-color images with a total of 16.7 million colors (256 tones per RGB channel). This means that image processing can be performed with the same color information that is visible to the human eye, and stable measurements can be performed under lighting that closely resembles natural light.

Real Color Sensing



The camera image is processed as-is without any loss of quality. This enables even the slightest of color differences to be captured with high accuracy



Captured images are converted to a 256-shade monochrome image and processed. This enables more stable inspection compared to binary level processing, but slight changes in color cannot be detected with this method.

Color segmentation processing



Captured images are converted to a black and white two-color image and processed. This reduces the amount of data and enables high-speed processing.

OMRON [17

Processing items for various types of inspections

Inspection & measurement



Precise Defect 🔉

Detection of dirt on paper cups

This processing item is used to detect scratches and dirt on paper cups and molded plastics, as well as oil stains on metal surfaces. Real Color Sensing makes it possible to detect dirt in various colors.

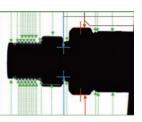




Scan Edge Position and Scan Edge Width

Inspection of groove depth of metal shafts

The maximum and minimum widths within the region are measured simultaneously. This processing item is very useful especially for the measurement of groove depths of metal shafts.



Labeling 🌆

Hole counting

The number of labels with the specified color and size is counted. Also, the area and center of gravity of the specified labels are measured.



Character Inspection

Label printing inspection

Characters are recognized by pattern search, and this enables special fonts and non-alphanumeric characters to be inspected. Automatically extracting a model and selecting an index from the list help you easily set up your dictionary. Using the user dictionary, the Character Inspection performs pattern search to recognize characters. Auto model extraction (Special fonts can be read)



Index selection from list



Search II 👔

2 times faster and higher detection*

Cable arrangement inspection

Just register a model, and the cable arrangement inspection is completed in one go. Repeating color detection is not necessary.



* Compared with Search under our test conditions in April 2019.

Fine Matching 🚹

Inspection for label rips

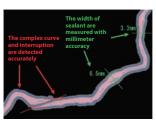
The registered reference image is compared against the input image and tiny differences are detected at high speed. Scratches on the intricate patterns and unexpected dirt in the color are precisely detected.



Glue Bead Inspection 🎢

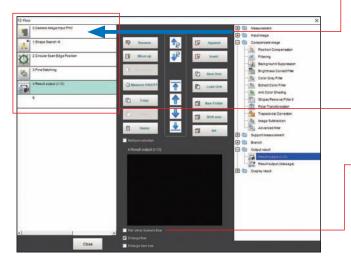
Path and width inspection

Just define the start and end points of the object to evaluate sealing numerically. This minimizes inconsistencies in inspection. This method enables accurate inspection of complex curves and interruptions.



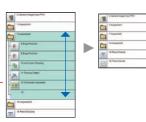
Easy-to-use system with high functionality

Easy measurement flow creation



Drag and drop

Just drag and drop pre-installed processing items from the processing item list to the flowchart to build a measurement flow.



Complex and long processes can be grouped into folders.

Copy & paste processing items from other scenes

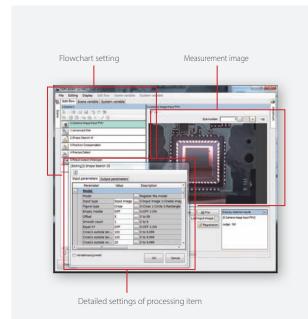
1.Scen	e 1	
1.Scen	e 1	^
2.Scen	e 2	
3.Scen	e 3	
4.Scen	e 4	
5.Scen	e 5	
6.Scen	e 6	
7.Scen	e 7	
8.Scen	e 8	~
4-4		
	3.Edge Position	

You can set up a new flow menu by combining different processing items copied from other scenes. When reusing the setting of other scenes, you don't need to make adjustments.

Simple setting with menus

Total Design Management Editor

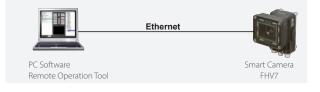
The design interface allows you to design complex measurement processes while managing variables. This simple GUI manages complicated branching processes and data sharing across measurement scenes and eliminates the need to switch screens.



Setting and operating from a computer

Use a dedicated software to create measurement flows and measurement conditions. The software can also be used for remote monitoring and control via a network.

You can download the software for free after purchasing the product and signing up online. For details, see the member registration sheet attached to the FHV7 Smart Camera.



Operation via touch panel monitor

The touch panel monitor with pre-installed software for the FHV7 Smart Camera can be used as an easy-to-install operator interface.



Touch Panel Monitor OMRON Model NYE Series Advantech Model PPC-310-OMR*

* Ask Advantech about the warranty period and coverage of this product. https://www.advantech.com/contact/offices/

Customizable user interface prevents incorrect operation

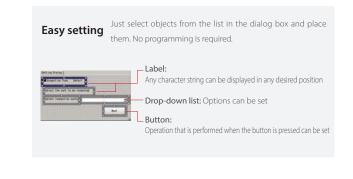
The processing item setting window includes parameters for initial setting and for daily adjustments. To prevent incorrect operation, you can customize the adjustment window to show only parameters that are required for your daily operation.

Example 1: Show only necessary parameters

elegection Type Detect	
Select parts to be mapeched	
Selectors	

Example 2: Show a wizard





Easy machine control design

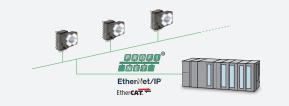
Connecting Sysmac devices via EtherCAT and using the integrated development environment Sysmac Studio allow you to design machine operation as you want.



Easy connection to field networks

EtherCAT *, EtherNet/IP, PROFINET

The FHV7 Smart Camera includes communication interfaces for compatibility with a wide range of network protocols used at production sites. This helps reduce the design work required for data communications between the camera and a PLC.



Easy setting of output items

Just select variables to output measurement results.

0 0 Integer 123					
	No.	Offset	Data Type	Data	Value
	0	0	Integer	123	
	1	4	Double	123.456	
2 12 String ABCDE 3	2	12	String	ABCDE	

Product lineup

The product lineup includes general-use Smart Cameras and high-speed, high-accuracy vision systems. You can choose the right one according to your requirements for speed and accuracy of each process. Both FH Series and FHV7 Series have the common user interface and operating procedures, so it is possible to share the same image inspection method across the production line. This reduces the time for operator training. The compatibility of setting data enables you to upgrade hardware easily when speed and accuracy enhancement is needed.

		For various Smart Cam FHV7 Serie		pections	For proces high spee Vision Sys FH Series	stem	ng resolution
				Ĵ	œ		
			FHV7X		FH-2050	0	FH-5050
	Performance *1		*		**		***
Hardware	No. of cameras		1		8		8
Grade	Resolution	0.4 _{Mpix}	1.6 Mpix 6.3	3.2 Mpix 12	0.4 _{Mpix}	1.6 Mpix 12	3.2 _{Mpix} 20.4
		Мріх	Мріх	Mpix	Мріх	Mpix	Mpix
One Software	Screens	Main :	screen		ment flow screen		tent condition ng screen
	Image logging format		JPEG	BMF	Omron for		
	Setting data			Compa	tible *2		

*1. \star : The more starts, the higher the performance.

^{*2.} Settings for the common functions can be shared between series.

Processing items

Most frequently used processing items come standard, according to customer usage of the high-spec vision system FH Series.

Group	Processing Item	FHV7 Series	FH Series	Group	Processing Item	FHV7 Series	Fł Ser
	Search	√	\checkmark		Unit Macro	-	√
	Search II	√	√		Unit Calculation Macro	-	✓
	Flexible Search	\checkmark	✓		Calculation	✓	√
	Sensitive Search	\checkmark	√		Line Regression	~	✓
	ECM Search	-	√		Circle Regression	~	V
	EC Circle Search	-	√		Precise Calibration	~	V
	Shape Search II	-	√		User Data	-	V
	Shape Search III	√	√		Set Unit Data	-	V
	EC Corner	-	\checkmark		Get Unit Data	-	✓
	Ec Cross	-	√		Set Unit Figure	-	V
	Classification	√	√		Get Unit Figure	-	V
	Edge Position	√	√		Trend Monitor	✓	v
	Edge Pitch	~	√		Image Logging	√	,
	Scan Edge Position	√	√		Image Conversion Logging	~	v
	Scan Edge Width	√	✓		Data Logging	_	,
	Circular Scan Edge Position	√	✓		Elapsed Time	✓	,
	Circular Scan Edge Width	√	✓		Wait	✓	×
	Intersection	√	\checkmark		Focus		v
asurement	Color Data	· √	· · · · · · · · · · · · · · · · · · ·	Support	Iris	-	- ·
	Gravity and Area	 ✓	✓ ✓	measurement	Parallelize	-	
	Labeling	 ✓	✓ ✓	measurement	Parallelize Task	✓ ✓	,
	Label Data	-	✓ ✓		Statistics	✓ ✓	
	Defect		✓ ✓		Reference Calib Data	✓ ✓	
	Precise Defect	-	✓ ✓		Position Data Calculation	✓ ✓	
	Fine Matching	 ✓	✓ ✓		Stage Data	 ✓	
	Character Inspect	 ✓	✓ ✓		Robot Data	✓ ✓	
		 ✓	✓ ✓		Vision Master Calibration	✓ ✓	
	Date Verification	 ✓	✓		PLC Master Calibration		,
	Model Dictionary		✓			-	
	2DCode II	✓			Convert Position Data	✓	
	2DCode	✓ ✓	\checkmark		Movement Single Position	✓ ✓	,
	Barcode				Movement Multi Points		
	OCR User Dictionary	✓	✓		Detection Point	-	`
	OCR	\checkmark	✓		Manual Position Setting	-	,
	Circle Angle	-	✓		Camera Calibration	√	``
	Glue Bead Inspection	~	✓		Data Save	-	`
	Al FineMatching ²²	-	✓		Conveyor Calibration	-	`
	Camera Image Input	-	✓		Scene	✓	`
	Camera Image Input FH	-	✓		System Information	√	`
	Camera Image Input FHV	~	-		Conditional Branch	-	,
	Camera Image Input HDR	\checkmark	✓		End	✓	`
out Image	Camera Image Input HDR Lite	-	✓		DI Branch	-	`
	Photometric Stereo Image Input	√	✓		Control Flow Normal	-	,
	Camera Switch	-	✓		Control Flow PLC Link	-	,
	Measurement Image Switching	\checkmark	✓		Control Flow Parallel	-	,
	Multi-trigger Imaging	\checkmark	✓	Branch	Control Flow Fieldbus	-	`
	Multi-trigger Imaging Task	\checkmark	✓	Dialicii	Selective Branch	-	`
	Position Compensation	\checkmark	✓		Conditional Execution (If)	√	1
	Filtering	\checkmark	✓		Conditional Execution (Else)	√	1
	Background Suppression	\checkmark	✓		Loop	√	,
	Brightness Correct Filter	\checkmark	✓		Loop Suspension	√	,
	Color Gray Filter	\checkmark	✓		Select Execution(Select)	√	,
	Extract Color Filter	√	√		Select Execution(Case)	√	
	Anti Color Shading	\checkmark	√		Result Output (I/O)	√	
mponcato	Stripes Removal Filter II	√	✓		Result Output(Message)	√	,
-	1 11	\checkmark	✓		Result Output (Parallel I/O)	√	,
-	Polar Transformation			Queters et une es elte *1	Data Output	-	,
-		√	√	Output result			
-	Trapezoidal Correction	√ -	✓ ✓	Output result *1		-	,
-	Trapezoidal Correction Machine Simulator		✓	Output result	Parallel Data Output		
-	Trapezoidal Correction Machine Simulator Image Subtraction	-		Output result	Parallel Data Output Parallel Judgement Output	-	, ,
mpensate age	Trapezoidal Correction Machine Simulator Image Subtraction Advanced filter	-	\checkmark	Output result	Parallel Data Output Parallel Judgement Output Fieldbus Data Output	- - -	, ,
-	Trapezoidal Correction Machine Simulator Image Subtraction Advanced filter Panorama	-	✓ ✓ ✓ ✓	Output result	Parallel Data Output Parallel Judgement Output Fieldbus Data Output Result Display	-	,
ige	Trapezoidal Correction Machine Simulator Image Subtraction Advanced filter	- √ - -	✓ ✓ ✓ ✓ ✓ ✓	Display result	Parallel Data Output Parallel Judgement Output Fieldbus Data Output	- - -	,

Display Image Hold

Use the Result Output (I/O) processing item to output data via PLC Link or Fieldbus (EtherNet/IP, PROFINET).
Use the Result Output (Message) processing item to output data through non-procedure communications.
Use the Result Output (I/O) processing item to output data through non-procedure communications.

Procedure communications.
Use the Result Output (I/O) processing item to output data using the FHV-SDU30 Smart Camera Data Unit EtherCAT Interface.
Use the Result Output (Parallel I/O) processing item to output data using the FHV-SDU10 Smart Camera Data Unit Parallel Interface.
*2. Refer to the FH Series catalog for the usage conditions of Al processing.

Note : Refer to page 43 for details of processing items.

Smart Camera FHV7 Series

The functionality and speed that your production site demands packed in an all-in-one device

- A robust all-in-one body that makes it easy to install
- Flexibly accommodates object changes
- Excellent productivity performance



Smart camera All-in-one Models All-in-one Models All-in-one Models with with Lens Module Lens and Lighting Modules I/O cable O -----External light FLV/FL Series Trigger PI C 24 VDC Data unit cable input sensor Lighting controller Junction Cable Data unit Parallel interface Ethernet cable 0 Parallel I/O cable Hub Data unit MDMC Light EtherCAT interface FL-MD EtherCAT cable NJ/NX/NY EtherCAT Touch Panel Monitor PC (Remote Robot Series slave NYE Series Operation Tool) * controller

* After purchasing the product, you can register as a member to download this for free. For details, see the member registration sheet included with the FHV7 Smart Camera.

Model Selection

To select a model of Smart Camera, use the WEB Selector.

http://www.ia.omron.com/fhv_select_e

Note: With certain module types, the operation of some combinations cannot be guaranteed. Use the Web Selector to select the correct combination of image sensor, lens, resolution, and light.

Smart Camera Inc.	some model award		tops (2)
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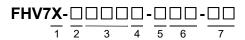
System Configuration

22

Model Number Structure

FHV7 Series Model Number Legend

Use this legend when determining the product specifications from the model number. When ordering, use a model number from the table in *Ordering Information*.



No.	Classification	Code	Meaning	
1	Controller specification	Х	64-bit OS model	
2		М	Monochrome	
Z	Image sensors	С	Color	
		004	0.4 million pixels	
		016	1.6 million pixels	
3	Resolution	032	3.2 million pixels	
3		Resolution	050	5 million pixels
			063	6.3 million pixels
		120	12 million pixels	
	Obutton ton a	-	Global shutter	
4	Shutter type	R	Rolling shutter	
		С	C mount	
5	Lens	Н	High-speed lens module (autofocus)	
		S	Standard lens module (autofocus)	

No.	Classification	Code	Meaning
		06	6 mm
	Focal length	09	9 mm
6		12	12 mm
0		16	16 mm
		19	19 mm
		25	25 mm
		R	Red
7	light color	W	White
7	Light color	IR	IR
		MC	Multi color

Configuration

For the Smart Camera FHV7 series, there are five configurations below by module combinations.

Smart	camera	Lens	Internal lighting	Protective structure	Integrated model	Appearance	Configuration
0.4 million pixels 1.6 million pixels 3.2 million pixels	FHV7X004 FHV7X016 FHV7X032	C mount lens 3Z4SLE		IP40	FHV7X-		C mount lens/IP40
5 million pixels 6.3 million pixels 12 million pixels	FHV7X-050-0 FHV7X-063R-0 FHV7X-0120R-0	SVV 3Z4SLE SVH	N/A	IP67 Waterproof Hoods required FHV-XHD-S FHV-XHD-L	N/A	ব্	C mount lens/IP67
			N/A	IP40	FHV7X		Lens module/IP40
0.4 million pixels 1.6 million pixels 3.2 million pixels 6.3 million pixels	FHV7X004 FHV7X016 FHV7X032 FHV7X063R	FHV lens module FHV-LEM-H FHV-LEM-S		IP67 Waterproof Hoods required FHV-XHD-LEM	N/A	Ŵ	Lens module/IP67
			FHV-LTM-🗆	IP67	FHV7X H FHV7X S		Lens module /Internal lighing - IP67

Ordering Information

Smart Cameras C Mount Models

Item	Resolution	Мо	del
item	Resolution	Color	Monochrome
	0.4 million pixels	FHV7X-C004-C	FHV7X-M004-C
	1.6 million pixels	FHV7X-C016-C	FHV7X-M016-C
31	3.2 million pixels	FHV7X-C032-C	FHV7X-M032-C
	5 million pixels	FHV7X-C050-C	FHV7X-M050-C
	6.3 million pixels	FHV7X-C063R-C	FHV7X-M063R-C
	12 million pixels	FHV7X-C120R-C	FHV7X-M120R-C

All-in-one Models with Lens Module

ltem	Resolution	Lens	Feed length	1	Model
item	Resolution	Lens	Focal length	Color	Monochrome
0.4 million		High-speed lens module	6 mm	FHV7X-C004-H06	FHV7X-M004-H06
		(autofocus)	19 mm	FHV7X-C004-H19	FHV7X-M004-H19
			6 mm	FHV7X-C004-S06	FHV7X-M004-S06
	0.4 million pixels		9 mm	FHV7X-C004-S09	FHV7X-M004-S09
		Standard lens module (autofocus)	12 mm	FHV7X-C004-S12	FHV7X-M004-S12
		(autolocus)	16 mm	FHV7X-C004-S16	FHV7X-M004-S16
			25 mm	FHV7X-C004-S25	FHV7X-M004-S25
-		High-speed lens module	6 mm	FHV7X-C016-H06	FHV7X-M016-H06
		(autofocus)	19 mm	FHV7X-C016-H19	FHV7X-M016-H19
			6 mm	FHV7X-C016-S06	FHV7X-M016-S06
-	1.6 million pixels	Standard lens module (autofocus)	9 mm	FHV7X-C016-S09	FHV7X-M016-S09
Constraint of the			12 mm	FHV7X-C016-S12	FHV7X-M016-S12
		(autolocus)	16 mm	FHV7X-C016-S16	FHV7X-M016-S16
3 6			25 mm	FHV7X-C016-S25	FHV7X-M016-S25
		High-speed lens module (autofocus)	6 mm	FHV7X-C032-H06	FHV7X-M032-H06
			19 mm	FHV7X-C032-H19	FHV7X-M032-H19
			6 mm	FHV7X-C032-S06	FHV7X-M032-S06
	3.2 million pixels		9 mm	FHV7X-C032-S09	FHV7X-M032-S09
		Standard lens module (autofocus)	12 mm	FHV7X-C032-S12	FHV7X-M032-S12
		(uutoroodo)	16 mm	FHV7X-C032-S16	FHV7X-M032-S16
			25 mm	FHV7X-C032-S25	FHV7X-M032-S25
		High-speed lens module	6 mm	FHV7X-C063R-H06	FHV7X-M063R-H0
		(autofocus)	19 mm	FHV7X-C063R-H19	FHV7X-M063R-H1
			6 mm	FHV7X-C063R-S06	FHV7X-M063R-S0
	6.3 million pixels		9 mm	FHV7X-C063R-S09	FHV7X-M063R-S0
		Standard lens module (autofocus)	12 mm	FHV7X-C063R-S12	FHV7X-M063R-S12
		(44.010040)	16 mm	FHV7X-C063R-S16	FHV7X-M063R-S1
			25 mm	FHV7X-C063R-S25	FHV7X-M063R-S2

* For the focal length and horizontal field of view, refer to specifications (P.33) and optical charts of the lens module (P.52).

All-in-one Models with Lens and Lighting Modules

Item F	Resolution	Lens	Focal length	Light color		odel
		Long	i oouriongili	Light color	Color	Monochrome
				Multi color	FHV7X-C004-H06-MC	FHV7X-M004-H06-M
			6 mm	Red		FHV7X-M004-H06-R
				White	FHV7X-C004-H06-W	FHV7X-M004-H06-W
		High-speed		IR		FHV7X-M004-H06-IF
		lens module (autofocus)		Multi color	FHV7X-C004-H19-MC	FHV7X-M004-H19-M
		()		Red		FHV7X-M004-H19-R
			19 mm	White	FHV7X-C004-H19-W	FHV7X-M004-H19-W
				IR		FHV7X-M004-H19-IF
				Multi color	FHV7X-C004-S06-MC	FHV7X-M004-S06-M
				Red		FHV7X-M004-S06-R
			6 mm	White	FHV7X-C004-S06-W	FHV7X-M004-S06-W
				IR		FHV7X-M004-S06-IF
				Multi color	FHV7X-C004-S09-MC	FHV7X-M004-S09-M
					FHV/X-C004-S09-WC	
0.4	million pixels		9 mm	Red		FHV7X-M004-S09-R
				White	FHV7X-C004-S09-W	FHV7X-M004-S09-W
				IR		FHV7X-M004-S09-IF
		o		Multi color	FHV7X-C004-S12-MC	FHV7X-M004-S12-N
		Standard lens module	12 mm	Red		FHV7X-M004-S12-R
		(autofocus)	12	White	FHV7X-C004-S12-W	FHV7X-M004-S12-W
		(441010043)		IR		FHV7X-M004-S12-IF
				Multi color	FHV7X-C004-S16-MC	FHV7X-M004-S16-N
			10	Red		FHV7X-M004-S16-R
			16 mm	White	FHV7X-C004-S16-W	FHV7X-M004-S16-V
				IR		FHV7X-M004-S16-IF
				Multi color	FHV7X-C004-S25-MC	FHV7X-M004-S25-N
				Red		FHV7X-M004-S25-R
			25 mm	White	FHV7X-C004-S25-W	FHV7X-M004-S25-W
				IR		FHV7X-M004-S25-IF
				Multi color		FHV7X-M004-325-II
					FHV7X-C016-H06-MC	
			6 mm	Red		FHV7X-M016-H06-F
		High-speed		White	FHV7X-C016-H06-W	FHV7X-M016-H06-V
		lens module		IR		FHV7X-M016-H06-I
		(autofocus)		Multi color	FHV7X-C016-H19-MC	FHV7X-M016-H19-N
			19 mm	Red		FHV7X-M016-H19-R
				White	FHV7X-C016-H19-W	FHV7X-M016-H19-V
				IR		FHV7X-M016-H19-I
				Multi color	FHV7X-C016-S06-MC	FHV7X-M016-S06-N
			•	Red		FHV7X-M016-S06-R
			6 mm	White	FHV7X-C016-S06-W	FHV7X-M016-S06-W
				IR		FHV7X-M016-S06-IF
				Multi color	FHV7X-C016-S09-MC	FHV7X-M016-S09-N
				Red		FHV7X-M016-S09-R
1.6	million pixels		9 mm	White	FHV7X-C016-S09-W	FHV7X-M016-S09-W
				IR		FHV7X-M016-S09-IF
					 FHV7X-C016-S12-MC	
		Standard		Multi color		FHV7X-M016-S12-M
		lens module	12 mm	Red		FHV7X-M016-S12-R
		(autofocus)		White	FHV7X-C016-S12-W	FHV7X-M016-S12-W
				IR		FHV7X-M016-S12-IF
				Multi color	FHV7X-C016-S16-MC	FHV7X-M016-S16-M
			16 mm	Red		FHV7X-M016-S16-R
			10 11111	White	FHV7X-C016-S16-W	FHV7X-M016-S16-V
				IR		FHV7X-M016-S16-IF
				Multi color	FHV7X-C016-S25-MC	FHV7X-M016-S25-M
				Red		FHV7X-M016-S25-R
			25 mm	White	FHV7X-C016-S25-W	FHV7X-M016-S25-W
			1	IR		FHV7X-M016-S25-I

Item	Resolution	Lens	Focal length	Light color	Color	Monochrome
				Multi color	FHV7X-C032-H06-MC	FHV7X-M032-H06-MC
				Red		FHV7X-M032-H06-R
			6 mm	White	FHV7X-C032-H06-W	FHV7X-M032-H06-W
		High-speed lens module (autofocus)		IR		FHV7X-M032-H06-IR
				Multi color	FHV7X-C032-H19-MC	FHV7X-M032-H19-MC
		(autolocus)		Red		FHV7X-M032-H19-R
			19 mm	White	FHV7X-C032-H19-W	FHV7X-M032-H19-W
				IR		FHV7X-M032-H19-IR
				Multi color	FHV7X-C032-S06-MC	FHV7X-M032-S06-MC
				Red		FHV7X-M032-S06-R
			6 mm	White	FHV7X-C032-S06-W	FHV7X-M032-S06-W
				IR	111177-0032-000-11	FHV7X-M032-S06-IR
					 FUN/7X C022 C00 MC	
				Multi color	FHV7X-C032-S09-MC	FHV7X-M032-S09-MC
	3.2 million pixels		9 mm	Red		FHV7X-M032-S09-R
				White	FHV7X-C032-S09-W	FHV7X-M032-S09-W
				IR		FHV7X-M032-S09-IR
		Standard		Multi color	FHV7X-C032-S12-MC	FHV7X-M032-S12-MC
		lens module	12 mm	Red		FHV7X-M032-S12-R
		(autofocus)		White	FHV7X-C032-S12-W	FHV7X-M032-S12-W
				IR		FHV7X-M032-S12-IR
				Multi color	FHV7X-C032-S16-MC	FHV7X-M032-S16-MC
			16 mm	Red		FHV7X-M032-S16-R
			10 1111	White	FHV7X-C032-S16-W	FHV7X-M032-S16-W
				IR		FHV7X-M032-S16-IR
				Multi color	FHV7X-C032-S25-MC	FHV7X-M032-S25-MC
			25 mm	Red		FHV7X-M032-S25-R
The second s				White	FHV7X-C032-S25-W	FHV7X-M032-S25-W
I IIIII K				IR		FHV7X-M032-S25-IR
				Multi color	FHV7X-C063R-H06-MC	FHV7X-M063R-H06-M
				Red		FHV7X-M063R-H06-R
ALC: NOT			6 mm	White	FHV7X-C063R-H06-W	FHV7X-M063R-H06-W
		High-speed		IR		FHV7X-M063R-H06-IR
		lens module		Multi color	FHV7X-C063R-H19-MC	FHV7X-M063R-H19-M
		(autofocus)		Red		FHV7X-M063R-H19-R
			19 mm	White	FHV7X-C063R-H19-W	FHV7X-M063R-H19-W
				IR		FHV7X-M063R-H19-IR
				Multi color		
					FHV7X-C063R-S06-MC	FHV7X-M063R-S06-M
			6 mm	Red		FHV7X-M063R-S06-R
				White	FHV7X-C063R-S06-W	FHV7X-M063R-S06-W
				IR		FHV7X-M063R-S06-IR
				Multi color	FHV7X-C063R-S09-MC	FHV7X-M063R-S09-M0
	6.3 million pixels		9 mm	Red		FHV7X-M063R-S09-R
	F			White	FHV7X-C063R-S09-W	FHV7X-M063R-S09-W
				IR		FHV7X-M063R-S09-IR
		o		Multi color	FHV7X-C063R-S12-MC	FHV7X-M063R-S12-M0
		Standard lens module	12 mm	Red		FHV7X-M063R-S12-R
		(autofocus)	12 11111	White	FHV7X-C063R-S12-W	FHV7X-M063R-S12-W
				IR		FHV7X-M063R-S12-IR
				Multi color	FHV7X-C063R-S16-MC	FHV7X-M063R-S16-M0
			40 -	Red		FHV7X-M063R-S16-R
			16 mm	White	FHV7X-C063R-S16-W	FHV7X-M063R-S16-W
				IR		FHV7X-M063R-S16-IR
				Multi color	FHV7X-C063R-S25-MC	FHV7X-M063R-S25-M0
				Red		FHV7X-M063R-S25-R
			25 mm	White	FHV7X-C063R-S25-W	FHV7X-M063R-S25-W
			1			

* For the focal length and horizontal field of view, refer to specifications (P.33) and optical charts of the lens module (P.52)

Lens Modules

lt	tem	Focal length	Model
	High-speed lens module	6 mm	FHV-LEM-H06
	(Autofocus)	19 mm	FHV-LEM-H19
	Standard lens module (Autofocus)	6 mm	FHV-LEM-S06
		9 mm	FHV-LEM-S09
		12 mm	FHV-LEM-S12
		16 mm	FHV-LEM-S16
		25 mm	FHV-LEM-S25

* For the focal length and horizontal field of view, refer to specifications (P.33) and optical charts of the lens module (P.52). **Note:** Refer to the *Vision Accessory Catalog* (Cat No. Q198) for details on C-mount lenses.

Lia	htina	Modules
LIM	i i ci i g	modulos

ltem	Light color	Model
	Multi color	FHV-LTM-MC
	Red	FHV-LTM-R
	White	FHV-LTM-W
	IR	FHV-LTM-IR

Optical Filters

tem				
Polarization Filter	For visible light	FHV-XPL		
Polarization Filter	For both infrared light and visible light	FHV-XPL-IR		
Diffusion Filter		FHV-XDF		

Waterproof Hoods Required to ensure IP67 protection without using a lighting module.

Item	Model
Waterproof Hood for Lens Modules	FHV-XHD-LEM
Waterproof Hood for C-mount Lens (Short) *1	FHV-XHD-S
Waterproof Hood for C-mount Lens (Long) *2	FHV-XHD-L

***1.** Can be used with the following lenses.

3Z4S-LE SV-0614V, 3Z4S-LE SV-0813V, 3Z4S-LE SV-1214V, 3Z4S-LE SV-1614V, 3Z4S-LE SV-2514V

*2. Can be used with the following lenses. 3Z4S-LE SV-0614H, 3Z4S-LE SV-0814H, 3Z4S-LE SV-1214H, 3Z4S-LE SV-1614H, 3Z4S-LE SV-2514H, 3Z4S-LE SV-3514H, 3Z4S-LE SV-5014H

Cables

	Item	Cable length	Model
		2m	FHV-VDB2 2M
		3m	FHV-VDB2 3M
	I/O Cable (Bend Resistant) * 1	5m	FHV-VDB2 5M
		10m	FHV-VDB2 10M
1		20m	FHV-VDB2 20M
		2m	FHV-VDLB2 2M
		3m	FHV-VDLB2 3M
	I/O Cable (Bend Resistant, Right-angle) *1	5m	FHV-VDLB2 5M
		10m	FHV-VDLB2 10M
1		20m	FHV-VDLB2 20M
\bigcirc		5m	FHV-VDBX2 5M
~ 9	I/O Cable (Super Bend Resistant) *1	10m	FHV-VDBX2 10M
	I/O Cable (Super Bend Resistant, Right-angle) *1	5m	FHV-VDLBX2 5M
	I/O Cable (Super Bend Resistant, Right-angle) *1	10m	FHV-VDLBX2 10M
	Ethernet Cable (Bend Resistant)	2m	FHV-VNB2 2M
		3m	FHV-VNB2 3M
		5m	FHV-VNB2 5M
		10m	FHV-VNB2 10M
		20m	FHV-VNB2 20M
		2m	FHV-VNLB2 2M
		3m	FHV-VNLB2 3M
	Ethernet Cable (Bend Resistant, Right-angle)	5m	FHV-VNLB2 5M
		10m	FHV-VNLB2 10M
2		20m	FHV-VNLB2 20M
\bigcirc	Ethernet Cable (Super Bend resistant)	5m	FHV-VNBX2 5M
		10m	FHV-VNBX2 10M
\bigcirc		5m	FHV-VNLBX2 5M
	Ethernet Cable (Super Bend resistant, Right-angle)	10m	FHV-VNLBX2 10M
and a	External Light Conversion Cable for MDMC Light/ Photometric Stereo Light	0.1m	FHV-VFLX-GD

*1. The FHV-VDB2/VDLB2/VDBX2/VDLBX2 I/O Cable cannot be connected when the smart camera data unit is used. Use the FHV-VUB2/VULB2/VULB2/VULBX2 Smart Camera Data Unit Cable.

Smart Camera Data Unit

Item	Model
Paralle linterface	FHV-SDU10
EtherCAT interface	FHV-SDU30

Smart Camera Data Unit Cable

	Item		Cable length	Model
			2m	FHV-VUB2 2M
		-	3m	FHV-VUB2 3M
	Smart Camera data unit cable(3end resistant) * 1	5m	FHV-VUB2 5M
		-	10m	FHV-VUB2 10M
•		-	20m	FHV-VUB2 20M
			2m	FHV-VULB2 2M
		-	3m	FHV-VULB2 3M
	Smart Camera data unit cable(3end resistant, Right-angle) ≭ 1	5m	FHV-VULB2 5M
		-	10m	FHV-VULB2 10M
		-	20m	FHV-VULB2 20M
	Smart Camera data unit cable(Survey Dand resistant) 44	5m	FHV-VUBX2 5M
		super benu resistant) * i	10m	FHV-VUBX2 10M
	Smart Camera data unit cable(Super Bend resistant, Right-angle)			FHV-VULBX2 5M
	*1		10m	FHV-VULBX2 10M
			2m	XW2Z-S013-2
7	Parallel I/O Cable	-	5m	XW2Z-S013-5
~			0.5m	XW2Z-050EE
		-	1m	XW2Z-100EE
	Parallel I/O Cable for Connecto		1.5m	XW2Z-150EE
	Connector-Terminal Block Conv (Terminal Blocks Recommende	version Units can be connected d Products: OMRON XW2R-[]34G-T)	2m	XW2Z-200EE
•			3m	XW2Z-300EE
		-	5m	XW2Z-500EE
~	Connector-Terminal Block	Phillips screw		XW2R-J34GD-T
ADDING TO A	Conversion Units, General-	Slotted screw (rise up)		XW2R-E34GD-T
and the	purpose devices *2	Push-in spring		XW2R-P34GD-T

*1. The FHV-VDB2/VDLB2/VDBX2/VDLBX2 I/O Cable cannot be connected when this cable is used.

***2.** Refer to the XW2R datasheet for details.

Accessories

	Model			
	Base Mount for Smart Cameras and Light	Base Mount for Smart Cameras and Lighting Controllers		
	Base Mount for Lighting Controllers		FHV-XMT-7-TCC	
	Light Cover (for replacement) * 1		FHV-XCV	
0	Weterproof Cap (for replacement)	for Ethernet Connecter	FHV-XWC-ECN	
	Waterproof Cap (for replacement)	for Light Connecter	FHV-XWC-LCN	
		for Camera	FHV-XWP-CAM	
\bigcirc	Waterproof Packing * 2 (for replacement, 5 pcs)	for Lighting Module	FHV-XWP-LTM	
\bigcirc		for Waterproof Hood	FHV-XWP-HD-SL	
	Light-shielding for Lighting Module (for rep	placement, 3 pcs) *3	FHV-XLS-LTM	
	Cover for High-speed Lens Module (for replacement, cover 1pcs, screws 5 pc	Cover for High-speed Lens Module (for replacement, cover 1pcs, screws 5 pcs (including one spare piece))		
	Cover for Standard Lens Module (for replacement, cover 1pcs, screws 5 pc	Cover for Standard Lens Module (for replacement, cover 1pcs, screws 5 pcs (including one spare piece))		
Q	Cover for C-mount Lens (for replacement, cover 1pcs, screws 5 pc	Cover for C-mount Lens (for replacement, cover 1pcs, screws 5 pcs (including one spare piece))		
	Screw for microSD card cover (for replace	ement, 10 pcs)	FHV-XSCR-MSD	

*1. Adapted lighting module FHV-LTM-W, FHV-LTM-R, FHV-LTM-IR, FHV-LTM-MC
*2. Always replace when a module is removed.
*3. It is considered a consumable item that will deteriorate. Please replace as needed.

Accessories

Item		Descriptions			
			LED	FLV Series	
			High-brightness LED	FL-BR/DR Series	
-	External Lights		Photometric Stereo Light	FL-PS Series	
			MDMC Light (Built-in lighting controller)	FL-MD Series	
				FLV-TCC/ATC	
	Lighting controller		High-brightness LED	FL-TCC/STC	
			For photometric Stereo Light	FL-TCC1PS	
A CONTRACTOR	Industrial Switching Hubs for EtherNet/IP and Ethernet	5 port	Current consumption: 0.07 A	W4S1-05D	

Lenses

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

			Recommended lens					
Resolution	Camera Model	Size of image element	Standard Lens	Telecentric Lens Vibrations and Sho Resistant Lens VS-MCA Series				
0.4 million-pixel	FHV7X-004	1/2.9" equivalent	SV-V Series	VS-TCH Series				
1.6 million-pixel	FHV7X-016	1/2.9" equivalent	SV-V Series		Non-telecentric Macro			
3.2 million-pixel	FHV7X-032	1/1.8" equivalent						
5 million-pixel	FHV7X-060	2/3" equivalent	SV-H Series					
6.3 million-pixel	FHV7X-063R	1/1.8" equivalent	SV-D Selles					
12 million-pixel	FHV7X-0120R	1/1.7" equivalent						

Recommended EtherCAT Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

Cable with Connectors

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6PUR8SS30CM-YF
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6PUR8SS50CM-YF
Standard RJ45 plugs type * 1 Wire Gauge and Number of Pairs: AWG26, 4-pair Cable		OMRON	1	XS6W-6PUR8SS100CM-YF
Cable Sheath material: PUR	*	OWRON	2	XS6W-6PUR8SS200CM-YF
Cable color: Yellow *2			3	XS6W-6PUR8SS300CM-YF
			5	XS6W-6PUR8SS500CM-YF
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)	-		0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1 Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Light blue	23	OMRON	XS5W-T421-CMD-K	
	*0		XS5W-T421-DMD-K	
		5		XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
			0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable * 3		OMRON	2	XS5W-T421-DM2-SS
M12/Smartclick Connectors Wire Gauge and Number of Pairs: AWG22, 2-pair Cable		OWINCON	3	XS5W-T421-EM2-SS
Cable color: Black			5	XS5W-T421-GM2-SS
			10	XS5W-T421-JM2-SS
			0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *3			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	23	OMRON	2	XS5W-T421-JMD-K XS5W-T421-BM2-SS XS5W-T421-CM2-SS XS5W-T421-DM2-SS XS5W-T421-EM2-SS XS5W-T421-GM2-SS XS5W-T421-GM2-SS XS5W-T421-JM2-SS XS5W-T421-BMC-SS XS5W-T421-CMC-SS
Rugged RJ45 plugs type		UNICON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

*1. Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the Industrial Ethernet Connectors Catalog (Cat. No. G019).

***2.** Cables colors are available in yellow, green, and blue. ***3.** For details, contact your OMRON representative.

Cables / Connectors

It	em	Recommended manufacturer	Model
Products for EtherCAT	Cable	Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 x 4P CP *1
(1000BASE-T/100BASE-TX) Wire gauge and number of pairs:	Cable	Kuramo Electric Co.	KETH-SB *1
AWG24, 4-pair cable	RJ45 Connector	Panduit Corporation	MPS588-C *1
	Cable	Kuramo Electric Co.	KETH-PSB-OMR *2
Products for EtherCAT (100BASE-TX/10BASE-T)	Cable	JMACS Japan Co., Ltd.	PNET/B *2
Wire gauge and number of pairs: AWG22, 2-pair cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 *2

***1.** We recommend you to use the above Cable and RJ45 Connector together.

*2. We recommend you to use the above Cable and RJ45 Assembly Connector together.

Touch Panel Monitor

Omron Model

Item	Screen size	Frame color	Model
	15.4 inch	Black	NYE2A-20F11-15WR1200
Touch Panel Monitor for FHV7 Smart Camera series	15.4 inch	4 inch Silver * NYE2A-20F11-15WR1300	NYE2A-20F11-15WR1300
	12.1 inch	Black	NYE2A-20F11-12WR1200
	12.1 inch	Silver *	NYE2A-20F11-12WR1300
High-Pressure Waterproof Attachment (PWA)	15.4 inch	-	NA-15WATW01
nigh-riessure waterproor Attachment (rwA)	15.4 inch – NA-15WATW01 12.1 inch – NA-12WATW01	NA-12WATW01	
Anti-reflection Sheets	15.4 inch	-	NA-15WKBA04
	12.1 inch	-	NA-12WKBA04

* The silver color is a European area limited model.

Advantech Model

Ask Advantech about the warranty period and coverage of this product.

Item	Model	Recommended manufacturer		
Touch Panel Monitor	PPC-310-OMR			
ARM VESA Standard (A-CLEVER) for PPC Series	PPC-ARM-A03			
Wall mount kit for PPC Series	PPC-174T-WL-MTE			
Stand for PPC Series	PPC-Stand-A1E	Find your local office on the Advantech website https://www.advantech.com/contact/		
ADP A/D 100-240V 90W 19V W/PFC	96PSA-A90W19OT-3			
Power cord 3P UL 10 A 125 V 1.8 m	1700001524	offices/		
Power cord 3P Europe (WS-010+083) 1.83 m	170203183C			
Power cord 3P/3P PSE 1.8 m	1700008921-11			
Power cord 3P CCC (China) 1.8 m	96CB-POWER-B-1.8M			

Automation Software Sysmac Studio The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI.

For details, refer to your local OMRON website and Sysmac Studio Catalog (Cat. No. P138).

Ratings and Specifications

Smart Camera

ltem		Model	FHV7X- M004-C												
		Standard	Yes												
	Operation Mode	Double speed multi-input	Yes												
	Wode	Non-stop adjustment mode	Yes												
	Parallel pr	ocessing	Yes												
Specifica	Possible N		256		64		36		25		19		10		
tions	captured in Possible N logging im Smart Can	o. of ages to	645		161		79		50		39		19		
		o. of scenes	128 *1												
	UI operatio			Operation ⁻	ΓοοΙ										
	Setup			e processi		na Flow ea	ditina.								
	Language				·	·	~	Chinese, G	erman, Fre	ench, Italia	n, Spanish	, Korean, \	/ietnamese	e, Polish	
		ge elements	1/2.9-incl equivaler	n	1/2.9-incl equivaler	h	1/1.8-incl equivaler	1		equivalent	1/1.8-incl equivaler	h	1/1.7-incl equivaler	h	
	Color/Mon		Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	
		ixels (H x V)	720 × 54		1440 × 1		2048 × 1		2448 × 2		3072 × 2		4000 × 3		
	Pixel size		6.9 × 6.9	μm	3.45 × 3.	45 µm	3.45 × 3.4	45 µm	3.45 × 3.4	45 µm	2.4 × 2.4	μm	1.85 × 1.	85 µm	
	Imaging ar (opposing	corner)		(6.3 mm)	5.0 × 3.8	(6.3 mm)	7.1 × 5.3	(8.9 mm)	8.5 × 7.1	(11.1 mm)		7.4 × 5.0 (8.9 mm) Rolling shutter		7.4 × 5.6 (9.3 mm)	
	Shutter sy	stem	Global St	Global Shutter (Global reset mode compatible)							e)				
Imaging	Imaging Shutter function	nction	Electronic	Electronic shutter: Shutter speed can be set from 1 μs to 100 ms.					Shutter s be set fro	Electronic shutter: Electronic shutter Shutter speed can be set from 55 µs to 100 ms. Electronic shutter Shutter speed can be set from 84 µs to 100 ms.		peed can om 84 µs			
	Partial function		4 to 540 l (4-line ind	lines crements)	4 to 1080 (4-line in) lines crements)	4 to 1536 (4-line inc	i lines crements)	4 to 2048 (4-line ind		4 to 2048 (4-line inc	lines crements)	4 to 3000 (4-line ind) lines crements)	
	Frame rate (image acquisition time)		430 fps (2	2.3 ms)	224 fps (4.5 ms)	55 fps (1	8.0 ms)	35 fps (28	3.0 ms)	59 fps (1	6.7 ms)	19 fps (2	5.0 ms)	
	Lens mou		C mount												
	Field of vie Installation				ording to t	he field of	view and ir	stallation o	distance						
	Serial		RS-232C × 1												
	Ethernet		Protocol: Non-procedure (TCP/UDP) I/F: 1000BASE-T × 1												
	EtherNet/II PROFINET			get/Etherne /e/Etherne	. ,	formanco	class A								
	EtherCAT						IV-SDU30	only suppo	orte)						
	Parallel I/C	•					10-00000	only suppo	5113.7						
External		Input signals	4 signals • STEP	NPN/PNP common 4 signals • STEP (Measurement trigger input) • DI 0 to 2 (Command input signal)											
Interface	Parallel I/O	Output signals	 5 signals ERROR (ON when there is an error) OR (Overall Judgement Result) BUSY (Processing in progress) READY (ON when Image input is allowed) STGOUT/SHTOUT (Strobe trigger signal/Shutter output signal) 												
	Encoder I/	F	Yes (Sma	art Camera	Data Unit	FHV-SDU	10 only su	oports.)							
	Monitor I/F	:	N/A												
	USB I/F		N/A												
	SD Card I/	F	microSD	card: SDH	C × 1										
Indicator I	amne	Main	PWR: Gr	een, RUN:	Green, LII	NK: Yellow	, BUSY: G	reen, OR: `	Yellow, ER	R: Red					
	Lamps	SD	SD ACCE	ESS: Yello	N										
Supply Vo	ltage		21.6 VDC	C to 26.4 V	DC (When	an I/O cat	le with 20	m is conne	ected, it is 2	24.0 VDC t	o 26.4 VD	C.)			
Current Co	onsumption			ing module											
TI		enes can be					oraian aa		n data tar						

***1.** The number of scenes can be increased up to 1,024 with the Conversion scene group data tool.

Item	Model	FHV7X- M004-C	FHV7X- C004-C	FHV7X- M016-C	FHV7X- C016-C	FHV7X- M032-C	FHV7X- C032-C	FHV7X- M050-C	FHV7X- C050-C	FHV7X- M063R-C	FHV7X- C063R-C	FHV7X- M120R-C	FHV7X- C120R-C
	Ambient temperature range	Operating	g: 0 to +40	°C, Storage	e: -25 to +6	5°C (with	no icing or	condensat	tion)				
	Ambient humidity range	Operating	g & Storag	e: 35 to 85	%RH (With	no conde	nsation)						
	Ambient atmosphere	No corros	sive gases										
Usage	Vibration tolerance	Sweep tir	ne: 8 minu	te/count, S	i0Hz, Half a Sweep cour HV-LEM-S	nt: 10 time	s ,			Y/Z, same as a	bove.)		
Environ ment	Shock resistance	Impact fo	rce: 150 m	/s², Test d	irection: 6	directions,	three time	each (up/c	lown, front	/behind, lef	ft/right)		
	Noise immunity	 Fast transient burst DC power Direct infusion: 2kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 300 ms, Application time: 1 min. I/O line Direct infusion: 1kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 300 ms, Application time: 1 min. 						,					
	Grounding	Class D g	grounding (100 Ω or l	ess ground	ling resista	nce) * 2						
	Dimensions	110 mm :	× 68.5 mm	× 55.5 mm	n (H × W ×	D)							
	Weight	Approx. 6	670 g										
External shape	Degree of protection	(except a	ing module connector n the abov	cap remov		ls: IEC605	29 - IP67						
	Case material	Aluminun	n die-castir	ng (ADC12	2)								
Accessor	ies	Conne C mou C mou Instruc Membe	ctor cap fo nt cap (mo nt cover (n tion sheet: ership regi	r an exterr unted on t nounted or 1 stration: 1	cable (mou nal lighting he body): 1 n the body) ation and I	(mounted) I : 1	on the bod	y): 1					

*2. Existing the third class grounding

Lens Modules

High-speed Lens Modules (Autofocus)

Item		FHV-LEM-H06	FHV-LEM-H19				
System		Liquid lens auto focus					
Installation dista	ance	102 to 650 mm 202 to 1050 mm					
	0.4 million pixels	64 x 40 mm to 505 x 276 mm	50 × 27 mm to 266 × 200 mm				
Horizontal field of view range *	1.6 million pixels	64 × 48 mm to 505 × 376 mm	50 × 37 mm to 266 × 200 mm				
	3.2 million pixels	92 × 68 mm to 731 × 539 mm	71 × 53 mm to 378 × 284 mm				
	6.3 million pixels	97 × 63 mm to 766 × 499 mm	74 × 49 mm to 394 × 264 mm				
Focal length *	•	6 mm	19 mm				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)					
Usage	Ambient atmosphere	No corrosive gases					
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times					
	Shock resistance	Impact force: 150 m/s ² , Test direction: 6 directions, three	ee time each (up/down, front/behind, left/right)				
	Dimension	50 mm × 41.1 mm × 37.1 mm (H × W × D)	50 mm × 41.1 mm × 36.3 mm (H × W × D)				
External shape	Weight	Approx. 25 g	·				
	Case material	Polycarbonate					
Accessories		Special cover for FHV-LEM-H: 1 Screws: M3 × 8 mm: 5 (including one spare piece) Instruction sheet : 1 Compliance sheet: 1					

*Refer to optical chart (P.52) for details.

Standard Lens Modules (Autofocus)

Item		FHV-LEM-S06	FHV-LEM-S09	FHV-LEM-S12	FHV-LEM-S16	FHV-LEM-S25				
System		Mechanical auto foc	us			188 to 2,000 mm 30 × 23 to 391 × 293 mm 43 × 33 to				
Focal length ran	ige * 1	59 to 1,000 mm	60 to 1,000 mm	60 to 1,000 mm	110 to 2,000 mm	188 to 2,000 mm				
	0.4 million pixels	39 × 29 to	24 × 18 to	17 × 13 to	27 × 20 to	30 × 23 to				
Horizontal field	1.6 million pixels	845 × 624 mm	543 × 407 mm	407 × 305 mm	614 × 461 mm	391 × 293 mm				
of view range	3.2 million pixels	57 × 42 to 1,234 × 905 mm	34 × 25 to 772 × 579 mm	24 × 18 to 579 × 434 mm	38 × 29 to 874 × 655 mm	43 × 33 to 556 × 417 mm				
	6.3 million pixels	50 × 39 to 1,293 × 836 mm	35 × 23 to 807 × 538 mm	25 × 17 to 606 × 404 mm	40 × 27 to 913 × 608 mm	45 × 30 to 581 × 387 mm				
Focal length		6 mm	9 mm	12 mm	16 mm	25 mm				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)								
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)								
Usage	Ambient atmosphere	No corrosive gases								
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.15 mm *2, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times								
	Shock resistance	Impact force: 150 m/	s ² , Test direction: 6 direction	ections, three time eac	h (up/down, front/behir	nd, left/right)				
	Dimension	50 mm × 41 mm × 3	1 mm (H × W × D)							
External shape	Weight	Approx. 50 g								
	Case material	Polycarbonate								
Accessories		 Special cover for Screws: M3 × 8 m Instruction sheet : Compliance sheet 	im: 5 (including one spa 1	are piece)						

***1.** Refer to optical chart (P.52) for details. ***2.** When the lens module is mounted to the product, the vibration tolerance is applied for the specifications of the smart camera.

Lighting Modules

Model		FHV-LTM-W	FHV-LTM-R	FHV-LTM-IR	FHV-LTM-MC				
Color		White	Red	Infrared light	Multi color				
Peak wave len	gth	-	Typ. 630 nm	Typ. 850 nm	R: Typ. 630 nm G: Typ. 525 nm B: Typ. 465 nm IR: Typ. 850 nm				
Light source		LED	LED	LED	LED				
Risk group		Group 2	Group 1	Group 1	R: Group 1 G: Group 2 B: Group 2 IR: Group 1				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)							
Isage	Ambient humidity range	Operating & Storage: 35 to	85%RH (With no condensa	tion)					
	Ambient atmosphere	No corrosive gases							
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times							
	Shock resistance	Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)							
Dimensions		52 mm × 91 mm × 77 mm	$(H \times W \times D)$						
Weight		270 g	270 g	270 g	270 g				
Material		Aluminum die-casting (AD	C12), polycarbonate						
Accessories		Waterproof packing (sm Waterproof packing (larg Light shielding sheet FH Lighting cover FHV-XCV Hexagonal wrench (leng Instruction sheet: 1 Compliance sheet: 1	ge) FHV-XWP-LTM: 1 V-XLS-LTM: 1 /: 1						

Optical Filters

Model		FHV-XDF	FHV-XPL	FHV-XPL-IR			
Filter type		Diffusion filter	Polarization filter	Polarization filter			
Wavelength		Visible to infrared	Visible	Visible to infrared			
Adapted lightir	ng module	FHV-LTM-W FHV-LTM-R FHV-LTM-IR FHV-LTM-MC	FHV-LTM-W FHV-LTM-R FHV-LTM-MC (Infrared light is not used.)	FHV-LTM-W FHV-LTM-R FHV-LTM-IR FHV-LTM-MC			
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)					
Usage	Vibration tolerance	No corrosive gases					
environment	Shock resistance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times					
	Vibration tolerance	Impact force: 150 m/s ² , Test direction	n: 6 directions, three time each (up/dow	wn, front/behind, left/right)			
Material	· ·	Aluminum (A6061), polycarbonate					
Weight		Approx. 70 g	Approx. 70 g	Approx. 70 g			

Waterproof Hoods

Model		FHV-XHD-S	FHV-XHD-L	FHV-XHD-LEM			
Suitable lens		3Z4S-LE SV-V series SV-0614V SV-0813V SV-1214V SV-1614V SV-2514V	3Z4S-LE SV-H series SV-0614H *1 SV-0814H *2 SV-1214H SV-1614H SV-2514H SV-3514H SV-3514H SV-5014H	FHV-LEM-S series FHV-LEM-S06 FHV-LEM-S09 FHV-LEM-S12 FHV-LEM-S16 FHV-LEM-S25 FHV-LEM-H series FHV-LEM-H06 FHV-LEM-H09			
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)					
Usage	Ambient atmosphere	No corrosive gases					
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times					
	Shock resistance	Impact force: 150 m/s ² , Test direction	n: 6 directions, three time each (up/do	wn, front/behind, left/right)			
Material	·	Aluminum (A6061), polycarbonate					
Weight		Approx. 220 g	Approx. 220 g	Approx. 220 g			
*1 This is not	available in EHV7X-D050 EH		·	·			

***1.** This is not available in FHV7X-□050, FHV7X-□063R, FHV7X-□120R. ***2.** This is not available in FHV7X-□050.

Smart Camera Data Unit

Item		Parallel interface	EtherCAT interface			
Model		FHV-SDU10	FHV-SDU30			
Input/output specifications	Parallel I/O	Input: 12 Output: 24 (NPN/PNP combined use)	Input: 1 Output: 2 (NPN/PNP combined use)			
	Encoder I/F	Yes (Included in Parallel Input)	None			
	EtherCAT communications	None	Yes (slave)			
Smart Camera Interface		Special cable to connect No. of connectable cameras: 1				
	Main	POWER: Green, ERROR: Red, RUN: Gree	n, BUSY: Green, CAMERA: Yellow, OR: Yellow			
Indicator	EtherCAT	None	ECAT RUN: Green, LINK/ACT IN: Green, LINK/ACT OUT: Green, ECAT ERROR: Red			
Power supply voltage		21.6 to 26.4 VDC (Note: 24.0 to 26.4 VDC when a data unit c	able with 20 m is connected.)			
Insulation resistance		Between DC terminal block and FG terminal: 0.5 M Ω (250V Megger)				
Current consumption		4.5 A or less				
	Ambient temperature range	Operating: 0 to +50°C, Storage: -25 to +65°C (with no icing or condensation)				
	Ambient humidity range	Operating and storage: 35 to 85%RH (with no condensation)				
	Ambient atmosphere	No corrosive gases				
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.1 mm, Vibration direction: X/Y/Z, Sweep time: 8 minutes, Sweep count: 10 times				
	Shock resistance	Impact force: 150 m/s ² , Test direction: 6 directions, Three times each (up/down, front/bel left/right)				
Usage environment	Noise immunity	 Fast transient burst DC power Direct infusion: 2 kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms / 0.75 ms, Period: 300 ms, Application time: 1 minut I/O line Coupling clamp: 1 kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms / 0.75 ms, Period: 300 ms, Application time: 1 minut 				
	Grounding	Class D grounding (100 Ω or less grounding * Existing the third class grounding	g resistance)			
	Dimensions	H (90 mm) × W (93 mm) × D (65 mm)	H (90 mm) × W (124 mm) × D (65 mm)			
-	Weight	Approx. 250 g	Approx. 325 g			
External shape	Degree of protection	IEC60529 - IP20				
	Case material	PC+ABS, PC				
Accessories		Instruction sheet: 1 Compliance sheet: 1				

I/O cables Bending Resistance Cables

Item		FHV- VDB2 2M	FHV- VDLB2 2M	FHV- VDB2 3M	FHV- VDLB2 3M	FHV- VDB2 5M	FHV- VDLB2 5M	FHV- VDB2 10M	FHV- VDLB2 10M	FHV- VDB2 20M	FHV- VDLB2 20M
Cable length		2 m 3 m 5 m 10 m 20 m					20 m				
Connector typ	De						Straight connector	Right angle connector			
Cable type		Bending res	sistance cabl	e		L	r.	L	I.	r.	
Ci-c	Power line	AWG21									
Size	Others	AWG26									
Outer diamete	er	8.8±0.3 mm	ı dia.								
Min. bending	radius	Fixed use: 4	40 mm, Slidir	ng use: 70 m	m						
	Input signals	4 signals: S	TEP, DI 0 to	2							
Input/Output signals	Output signals	5 signals: E	RROR, OR,	BUSY, REA	DY, STGOUT	/SHTOUT					
Signals	RS-232C	2 signals: T	ransmission	data, Recep	tion data						
	Ambient temperature range	Operating: ·	-10 to +70°C	, Storage: -2	5 to +85°C (v	vith no icing o	or condensat	ion)			
	Ambient humidity range	Operating 8	& Storage: 0 t	to 93%RH (V	Vith no conde	ensation)					
Usage environment	Ambient atmosphere	No corrosiv	e gases								
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times						ount,			
	Shock resistance	Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material	·	Mold part: N	ylon, PVC, S	Sheath part:	PVC						
Weight		Approx. 250) g	Approx. 37	Эg	Approx. 590) g	Approx. 1,1	70 g	Approx. 2,3	10 g

Super Bending Resistance Cables

ltem		FHV-VDBX2 5M	FHV-VDLBX2 5M	FHV-VDBX2 10M	FHV-VDLBX2 10M				
Cable length		5 m		10 m					
Connector ty	pe	Straight connector	Right angle connector	Straight connector	Right angle connector				
Cable type		Super bending resistance cab	le						
0:	Power line	AWG19							
Size	Others	AWG26							
Outer diamet	er	7.2+0.7 mm dia.							
Min. bending	radius	44 mm							
Input/Output	Input signals	1 signal: STEP							
signals	Output signals	3 signals: OR, READY, STGO	3 signals: OR, READY, STGOUT/SHTOUT						
	Ambient temperature range	Operating: -10 to +70°C, Storage: -25 to +85°C (with no icing or condensation)							
	Ambient humidity range	Operating & Storage: 0 to 93%	6RH (With no condensation)						
Usage environment	Ambient atmosphere	No corrosive gases							
	Vibration tolerance	Oscillation frequency: 10 to 15 Sweep count: 10 times	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times						
Shock resistance Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material	·	Mold part: Nylon, PVC, Sheath part: PVC							
Weight		Approx. 420 g		Approx. 790 g					

Ethernet Cables Bending Resistance Cables

Item		FHV- VNB2 2M	FHV- VNLB2 2M	FHV- VNB2 3M	FHV- VNLB2 3M	FHV- VNB2 5M	FHV- VNLB2 5M	FHV- VNB2 10M	FHV- VNLB2 10M	FHV- VNB2 20M	FHV- VNLB2 20M
Cable length		2 m 3 m 5 m 10 m 20 m									
Connector typ	pe	Straight connector							Rightangle connector		
Cable type		Bending res	sistance cabl	e							
Outer diameter	ər	6.7±0.3 mm	ı dia.								
Min. bending	radius	Fixed use: 35 mm, Sliding use: 50 mm									
	Ambient temperature range	Operating: -	-10 to +70°C	, Storage: -2	5 to +85°C (v	vith no icing o	or condensat	ion)			
	Ambient humidity range	Operating 8	Storage: 01	to 93%RH (V	/ith no conde	ensation)					
Usage environment	Ambient atmosphere	No corrosiv	e gases								
	Vibration tolerance		Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times						ount,		
	Shock resistance	Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material		Mold part: PVC, Sheath part: PVC									
Weight		Approx. 140) g	Approx. 200) g	Approx. 310) g	Approx. 590) g	Approx. 1,1	50 g

Super Bending Resistance Cables

Item		FHV-VNBX2 5M FHV-VNLBX2 5M FHV-VNBX2 10M FHV					
Cable length							
Connector typ	pe	Straight connector	Straight connector Right angle connector Straight connector R				
Cable type		Super bending resistance cabl	e		1		
Outer diamete	er	6.6+0.7 mm dia.					
Min. bending	radius	40 mm					
	or condensation)						
	Ambient humidity range	Operating & Storage: 0 to 93%	RH (With no condensation)				
Usage environment	Ambient atmosphere	No corrosive gases					
	Vibration tolerance	Oscillation frequency: 10 to 15 Sweep count: 10 times	0 Hz, Half amplitude: 0.35 mm,	Vibration direction: X/Y/Z, Swe	ep time: 8 minute/count,		
Shock resistance Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)							
Material	·	Mold part: PVC, Sheath part: F	PVC				
Weight Approx. 390 g Approx. 730 g							

External Light Junction Cables for MDMC Light

Item		FHV-VFLX-GD			
Cable length		0.1 m			
Outer diameter	er	4.0±0.1 mm dia.			
Min. bending	radius	15 mm			
	Ambient temperature range Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)				
	Ambient humidity range	Operating & Storage: 0 to 93%RH (With no condensation)			
Usage environment	Ambient atmosphere	No corrosive gases			
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times			
Shock resistance Impact		Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)			
Material Shell part: Zin		ell part: Zinc alloy and Brass, Sheath part: Heat-resistant oilproof polyvinyl chloride			
Weight		Approx. 30 g			

Smart Camera Data Unit Cable

Bending Resistance Cables

Item		FHV- VUB2 2M	FHV- VULB2 2M	FHV- VUB2 3M	FHV- VULB2 3M	FHV- VUB2 5M	FHV- VULB2 5M	FHV- VUB2 10M	FHV- VULB2 10M	FHV- VUB2 20M	FHV- VULB2 20M
Cable length		2 m		3 m		5 m		10 m		20 m	
Connector type		Straight connector	Right angle connector	Straight connector	Right angle connector	Straight connector	Right angle connector	Straight connector	Right angle connector	Straight connector	Right angle connector
Cable type		Bending re	sistance cab	le							
Outer diameter	ər	7.8±0.3 mn	n dia.								
Min. bending	radius	Fixed use: 40 mm, Sliding use: 65 mm									
	Ambient temperature range	Operating:	-10 to +70°C	C, Storage: -2	25 to +85°C	(with no icin	g or condens	sation)			
	Ambient humidity range	Operating 8	& Storage: 0	to 93%RH (With no con	densation)					
Usage environment	Ambient atmosphere	No corrosiv	e gases								
chrinonnent	Vibration tolerance		Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/o Sweep count: 10 times					e/count,			
	Shock resistance	Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material		Mold part: I	Mold part: PVC, Sheath part: PVC								
Weight		Approx. 20	0 g	Approx. 29	0 g	Approx. 47	0 g	Approx. 90	0 g	Approx. 1,7	'80 g

Super Bending Resistance Cables

Item		FHV-VUBX2 5M	FHV-VUBX2 5M FHV-VULBX2 5M FHV-VUBX2 10M					
Cable length	le length 5 m 10 m							
Connector typ	pe	Straight connector Right angle connector Straight connector Right angle connector						
Cable type		Super bending resistance ca	ble		<u>.</u>			
Outer diamete	er	7.5+0.6 mm dia.						
Min. bending	radius	47 mm						
	Ambient temperature range	Operating: -10 to +70°C, Sto	Operating: -10 to +70°C, Storage: -25 to +85°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 0 to 93%RH (With no condensation)						
Usage environment	Ambient atmosphere	No corrosive gases						
	Vibration tolerance	Oscillation frequency: 10 to 1 Sweep count: 10 times	50 Hz, Half amplitude: 0.35 m	m, Vibration direction: X/Y/Z,	Sweep time: 8 minute/count,			
Shock resistance Impact force: 150 m/s ² , Test direction: 6 directions, three time each (up/down, front/behind, left/right)								
Material	Mold part: PVC, Sheath part: PVC							
Weight Approx. 490 g Approx. 920 g								

Touch panel monitor

OMRON Model

12WR1300						
19.2 to 28.8 VDC (24 VDC ±20%)						
r 100 minutes each in X,Y, and						
Silver *						
340 × 244 × 69 mm						
Panel mount, VESA mount						
Instruction sheet, Power and IO connector, Mounting Clamps						

* The silver color is a European area limited model.

Advantech Model

	Model	PPC-310-OMR
	Display Type	10.4" TFT LCD (LED backlight)
	Resolution	1,024 × 768
LCD	Luminance	350 cd/m ²
LCD	Contrast Ratio	1,000
	Backlight Lifetime	30,000 hr (min.)
	Touch Type	Capacitive
External Interface	Ethernet	10/100/1,000/2,500 Mbps Ethernet × 2
External interface	USB I/F	USB 2.0 × 2, USB 3.0 × 2, TypeC × 1
Dewer Consumption	Input Voltage	12 to 30 VDC
Power Consumption	Power Consumption	35 W
	Ambient Temperature Range	Operating: 0 to 50°C Storage: -20 to 60°C
	Ambient Humidity Range	10% to 95% at 40°C (With no condensation)
Environment	Vibration	Operating Random Vibration Test 5 to 500 Hz, 2 Grms, follow IEC 60068-2-64
	Shock	Operating 10 G peak acceleration (11 ms duration), follow IEC 60068-2-27
	EMC	CE, FCC Class B, BSMI, UKCA, VCCI
	Safety	CB, CCC, UL, UKCA
Dimensions		272 × 217 × 50 mm
Weight		3.1 kg
Front Panel Protectio	n	IP66 compliant
Mounting		Panel mount, VESA mount, Wall mount
Accessories		Instruction sheet, Connector for power supply, Mounting screws and brackets for panel mount

FHV7 Series EtherCAT Communications Specifications

Item		Specifications				
Communications standard		IEC61158 Type 12				
Physical layer		100 BASE-TX (IEEE802.3)				
Modulation		Base band				
Baud rate		100 Mbps				
Topology		Depends on the specifications of the EtherCAT master.				
Transmission Media		Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)				
Transmission Distance		Distance between nodes: 100 m or less				
Node address setting		00 to 99				
External connection terminals	5	RJ45 × 2 (shielded) IN: EtherCAT input data, OUT: EtherCAT output data				
Sand/reasive DDO date sizes	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *				
Send/receive PDO data sizes	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *				
Mailbox data size	Input	512 bytes				
Output		512 bytes				
Mailbox		Emergency messages, SDO requests, and SDO information				
Refreshing methods		I/O-synchronized refreshing (DC)				

* This depends on the upper limit of the master.

Version Information

FHV7 Series and Programming Devices

Use the latest version of Sysmac Studio Standard Edition/Vision Edition.

Version of FHV7 Series	Corresponding version of Sysmac Studio Standard Edition/Vision Edition				
Version 6.55/6.60	Supported by version 1.59 * or higher.				
Version 6.51 or higher	Supported by version 1.53 or higher.				
Version 6.41 or higher	Supported by version 1.44 or higher.				
Version 6.30 or higher	Supported by version 1.29 or higher.				

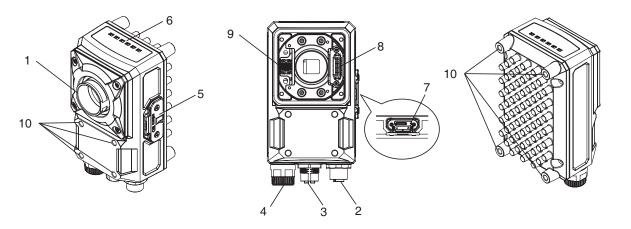
* Sysmac Studio Version 1.59 will be supported soon.

Recommended Operational Environment for Remote Operation Tool

Name	Description	
CPU	Intel Pentium Processor (SSE2 or higher)	
os	 Windows 7 Professional (32/64-bit) or Enterprise (32/64-bit) or Ultimate (32/64-bit) Windows 10 Pro (32/64-bit) or Enterprise (32/64-bit) Windows 11 Pro (64bit) or Enterprise (64bit) 	
Memory	2GB (3GB or more recommended)	
Hard disk space	2GB or more	
Display	Resolution: 1280 x 1240 dots or more Color: True Color (32-bit)	
Network	10BASE-T (100BASE-TX recommended)	

Using the FH/FHV Launcher requires Microsoft .NET Framework 3.5 installed.

Parts and Names



No.	Name		Description			
1	Imaging unit		Captures images.			
2	Connector for I/O cab cable	le/Smart camera data unit	Use this connector when connecting the smart camera with its power supply or an external device using an I/O cable. Moreover, use this when connecting the smart camera with its data unit using its data unit cable. Dedicated I/O cable: FHV-VD Dedicated smart camera data unit cable: FHV-VU			
3	Connector for Etherne	et cable	Use this connector when connecting the smart camera with a personal compute and so on using an Ethernet cable. Dedicated Ethernet cable: FHV-VN			
4	Connector for external lighting		Use this connector when connecting an external lighting and the external lighting controller. Connectable external lighting controller: FL-TCC and FLV-TCC Connectable external light: FL-MD MC			
5	Connector to attach microSD card		Use this connector to attach a microSD card. Do not extract/insert the microSD card during processing. Otherwise, measurement time may be influenced or data may be broken.			
		PWR (Green)	Lights while power is supplied.			
		RUN (Green)	Lights when switching to the layout in which the RUN signal output is set ON.			
6		LINK (Yellow)	Lights when connected with Ethernet equipment and blinks during communication.			
	Operation indicator	BUSY (Green)	Lights while processing is in progress.			
		OR (Yellow)	Lights when the overall judgment output signal is ON.			
		ERR (Red)	Lights when an error occurs.			
7		SD ACCESS (Yellow)	Lights when accessing to the microSD card.			
8	Connector for lighting module (White)		Use this connector when mounting the lighting module.			
9	Connector for lens me	odule (Black)	Use this connector when mounting the lens module.			
10	Mounting screw holes	;	Recommended tightening torque: 2.3N·m			

Processing Items

Group	lcon		Processing Item	Group	lcon		Processing Item		
	-	Search	Used to identify the shapes and calculate the position of measurement objects.			Scan Edge Position	Measure peak/bottom edge position of workpieces ac- cording to the color change in separated measurement area.		
	å	Search II	Even if the Search processing item cannot detect a model, the Search II can stably detect it by creating the optimal model according to the size and rotation of the measurement object.		₽	Scan Edge Width	Measure max/min/average width of workpieces ac- cording to the color change in separated measure- ment area.		
		Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.		Q	Circular Scan Edge Position	Measure center axis, diameter and radius of circular workpieces.		
	***	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.	Measurement	Q	Circular Scan Edge Width	Measure center axis, width and thickness of ring work- pieces.		
Measurement	, m	Shape Search III	Robust detection of positions is possible at high-speed and with high precision incorporating environmental fluctuations, such as differences in individual shapes of the workpieces, pose fluctuations, noise superimpo- sition and shielding.			Intersection	Calculate approximate lines from the edge information on two sides of a square workpiece to measure the an- gle formed at the intersection of the two lines.		
					&	Color Data	Used for detecting presence and mixed varieties of products by using color average and deviation.		
	8	Classification	Used when various kinds of products on the assembly line need to be sorted and identified.			Gravity and Area	Used to measure area, center of gravity of workpices by extracting the color to be measured.		
	-	Edge Position	Measure position of measurement objects according to the color change in measurement area.			Labeling	Used to measure number, area and gravity of work- pieces by extracting registered color.		
·			Detect edges by color change in measurement area. Used for calculating number of pins of IC and connectors.		×	Precise Defect	Check the defect on the object. Parameters for ex- traction defect can be set precisely.		

Group	lcon		Processing Item
		Fine Matching	Difference can be detected by overlapping and compar- ing (matching) registered fine images with input images.
	ABC	Character Inspect	Recognize character according correlation search with model image registered in [Model Dictionary].
_	Date 08-02-1	Date Verification	Reading character string is verified with internal date.
	A	Model Dictionary	Register character pattern as dictionary. The pattern is used in [Character Inspection].
/leasurement		2DCode II *1	Recognize 2D code and display where the code qual- ity is poor.
neasurement -		2DCode *2	Recognize 2D code and display where the code qual- ity is poor.
		Barcode *3	Recognize barcode, verify and output decoded char- acters.
_	OCR	OCR	Recognize and read characters in images as charac- ter information.
_	OCR	OCR User Dictionary	Register dictionary data to use for OCR.
		Glue Bead Inspection	You can inspect coating of a specified color for gaps or runoffs along the coating path.
_	De	Camera Image Input FHV	To input images from cameras. And set up the condi- tions to input images from cameras. (For FHV only)
_	-	Camera Image Input HDR	Create high-dynamic range images by acquiring sev- eral images with different conditions.
	1	Photometric Stereo Image Input	Capture images under different illumination directions using a photometric stereo light.
nput Image		Measurement Image Switching	To switch the images used for measurement. Not input images from camera again.
-	비행 비행 비행 비행	Multi-trigger Imaging	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert the Multi- trigger Imaging to the top of the flow.
	년 1월 1월	Multi-trigger Imaging Task	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert this pro- cessing item to the top of the processing which re- quires imaging for multiple times.
	5	Position Compensation	Used when positions are differed. Correct measurement is performed by correcting position of input images.
	M	Filtering	Used for processing images input from cameras in or- der to make them easier to be measured.
		Background Suppression	To enhance contrast of images by extracting color in specified brightness.
	-	Brightness Correct Filter	Track brightness change of entire screen and remove gradual brightness change such as uneven brightness.
-		Color Gray Filter	Color image is converted into monochrome images to emphasize specific color.
		Extract Color Filter	Convert color image to color extracted image or binary image.
Compensate mage		Anti Color Shading	To remove the irregular color/pattern by uniformizing max.2 specified colors.
		Stripes Removal Filter II	Remove the background pattern of vertical, horizontal and diagonal stripes.
		Polar Transformation	Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.
		Trapezoidal Correction	Rectify the trapezoidal deformed image.
-	-	Image Subtraction	The registered model image and measurement image are compared and only the different pixels are extract- ed and converted to an image.
-		Advanced filter	Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.
	ABC	Calculation	Used when using the judge results and measured values of Procltem which are registered in processing units.
	*	Line Regression	Used for calculating regression line from plural mea- surement coodinate.
-	Ŏ	Circle Regression	Used for calculating regression circle from plural mea- surement coordinate.
F	G	Precise Calibration	Used for calibration corresponding to trapezoidal dis- tortion and lens distortion.
Support neasurement		Trend Monitor	Used for displaying the information about results on the monitor, facilitating to avoid NG and analyze causes.
F	2 5	Image Logging	Used for saving the measurement images to the mem- ory and USB memory.
-	∭ →	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.
F	\$	Elapsed Time	Used for calculating the elapsed time since the mea- surement trigger input.
-	X	Wait	Processing is stopped only at the set time. The stand- by time is set by the unit of [ms].

Build in the service of the	Group	lcon		Processing Item
Branelize more tasks and processed in parallel to shoten the measurement time. This processing time is placed at the top of processing to be performed in parallel. Branelize Parallelize Task Parallelize Task Parallelize Task Parallelize Task Branelize Statistics Used when you need to calculate an average of multiple to whoten the measurement time. This processing time is placed multiple to the performed in parallelize Task Branelize Statistics Used when you need to calculate an average of multiple to whoten the measurement time. Statistics Branelize Position Data The specified position angle is calculated from the measurement time. Statistics Branelize Vision Master This processing time automatically calculates the entire axis movement amount of the control equipment necessary for calibration. Branelize Movement Multi The axis movement that is required to match the measured position angle is calculated. Branelize Movement Multi The axis movement that are required to match the measured position angle is calculated. Branelize Camera Calibration The axis movement that is required to match the measured position angle is calculated. Branelize Scene The axis movement that are required to match the measured position angle is calculated. Branelize	0.0up			
Brazileliza Task more tasks and processed in parallel to shorten the measurement time. This processing to be performed in parallel to shorten the measurement time. This processing to be performed in parallel to shorten the task measurement time. This processing to be performed in parallel to shorten the measurement time. This processing terms are not performed in parallel to shorten the diverse processing to be performed in parallel to shorten the measurement time. This processing terms are not performed in parallel to shorten the measurement time transmitter the specified position angle is calculated from the measurement time as the diverse data related to stages. Support Reference Calib Calibration data and distortion compensation data held under other processing item automatically calculates the enter Calibration Support Robot Data Sets and stores data related to stages. Support Vision Master This processing item automatically calculates the enter calibration. Support Movement The axis movement that is required to match the measured position angles to the corresponding reference position angles to the correspond			Parallelize	more tasks and processed in parallel to shorten the measurement time. This processing item is placed at the top of processing to be performed in parallel.
Subsidies ple measurement results. - Subsidies Reference Calib Data Calibration data and distribution compensation data held under other processing items can be referenced. Subsidies Position Data The specified position angle is calculated from the measured positions. Subsidies Stage Data Sets and stores data related to stages. Subsidies Robot Data The specified position angle is calculated from the measured positions. Subsidies Robot Data Sets and stores data related to robots. Subsidies Norment Vision Master Calibration The processing item automatically calculates the en- tre exis movement amount of the control equipment acculated. Subsidies Norement Single Position The axis movements that are required to match the mea- sured position angles to the reference position angle is calculated. Subsidies Convert Position The axis movements that are required to match the measured position angles are calculated. Subsidies Scene The specified scene is copied to the current scene. System frommation Conditional Execution (If) The measurement flow is divided according to the comparison result obtained using the set expressions and conditions. Select Execution (If) Conditional Execution (If) Execution (If) proce		000	Parallelize Task	more tasks and processed in parallel to shorten the measurement time. This processing item is placed im- mediately before processing to be performed in paral-
Participant Data held under other processing items can be referenced. Image: Support Position Data The specified position angle is calculated from the measured positions. Image: Stage Data Sets and stores data related to stages. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Sets and stores data related to robots. Image: Stage Data Convert Position The axis movement that is required to match the measured position angles to the corresponding reference position angles to the corresponding reference position angles are calculated. Image: Stage Data Sets and stores data required to match the measured position angles are calculated. Image: System Camera The specified scene is copied to the current scene. Obtain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller. Image: System Conditional The rescription result obtained using the set expressions and conditions. Image: System Condi			Statistics	
Support measurement Calculation measured positions. Support measurement Stage Data Sets and stores data related to stages. Support measurement Noto Data Sets and stores data related to robots. Image: Support measurement Vision Master Calibration This processing item automatically calculates the en- tite axis movement anount of the control equipment necessary for calibration. Image: Support Convert Position Data The axis movement hat is required to match the measured position angles to the corresponding refer- ence position angles are calculated. Image: Camera Calibration By setting the camera calibration, the measurement result can be converted and output as actual dimen- sions. Image: Camera Calibration Sets and stores data related to condition. Image: Conditional Execution (ft) The specified scene is copied to the current scene. Image: Conditional Execution (ft) The procitem must be set up as the last processing and conditions. Image: Conditional Execution (ft) The acte processes are repeated until the loop count reaches the specified number, and then the next pro- cess starts. Image: Conditional Execution (ft) Insert between the Loop processing item. The measurement flow is divided according to the comparison result obtai				
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Data is calculated. Image: Single Position The axis movement that is required to match the measured position angle is to the corresponding reference position angles to the construct scene. Image: Scene The system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller. Image: Conditional Execution (ff) The measurement flow is divided according to the comparison result obtained using the set expressions and conditions. Image: Conditional Execution (ff) Conditional Execution (ff) Insert between the Loop processing item. The measurement flow is divided according to the comparison result obtained using the conditions. Image: Conditional Execution (ff) Select Execution (Select) <th< td=""><td>measurement</td><td>¢,</td><td></td><td>tire axis movement amount of the control equipment</td></th<>	measurement	¢,		tire axis movement amount of the control equipment
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Image: System information information space and I/O input signal status) of the Sensor Controller. Information information space and I/O input signal status) of the Sensor Controller. Image: This Procision information End This Procision information Image: This Procision information Conditional Execution (If) The measurement flow is divided according to the comparison result obtained using the set expressions and conditions. Image: The set processes are repeated until the loop count reaches the specified number, and then the next process starts. Insert between the Loop processing item and End Loop processing item. The measurement flow is divided according to the comparison result obtained using the conditions. The loop count reaches the specified number. Image: Select Execution (Select) Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions. Image: Select Execution (Case) Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions. Image: Result Output (I/O) Output data to the external devices such as a programmable controller or a PC via PLC Link, Fieldbus interface (EtherCAT *4, EtherNet/IP (other than message communication), PROFINET). Output result Result Output (Message) Output data to the external devices such as a programmable controller or a PC with non-procedure mode via Etherenet or RS-232C. This processing item allows you to save		-	Scene	The specified scene is copied to the current scene.
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Image: New York New York New York To the external devices such as a programmable controller or a PC via Parallel interface *5. Image: Display result Image: Display Last NG Image Used for displaying the texts or the figures in the camera image. Image: Display Last NG Image Display the last NG images. Display Image	Output result			grammable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.
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Display result image Display uterast No infrages.		OK	Result Display	
	Display result	NG		Display the last NG images.
		6		

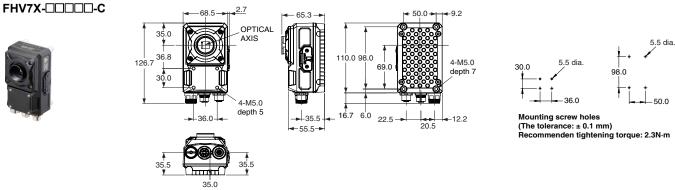
2D Codes that can be read : Data Matrix (ECC200) 2D Codes that can be read : Data Matrix (ECC200), QR Code Bar Codes that can be read : JAN/EAN/UPC (including add-on codes), Code 39, Codabar (NW-7), ITF (Interleaved 2 of 5), Code 93, Code 128, GS1-128, GS1 DataBar (RSS-14 / RSS Limited / RSS Expanded), Pharmacode The FHV-SDU30 EtherCAT Interface is required for EtherCAT connection. The FHV-SDU10 Parallel Interface is required for Parallel I/O connection.

(Unit: mm)

Dimensions

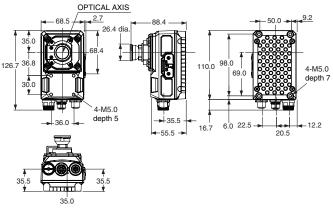
Smart Cameras

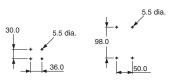
C Mount Models



All-in-one Models with Lens Module High-speed Lens Modules FHV7X-DDDD-H06



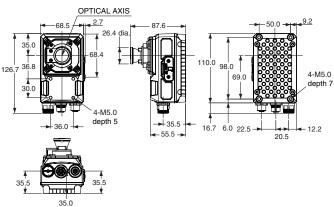


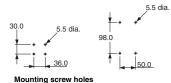


Mounting screw holes (The tolerance: ± 0.1 mm) Recommenden tightening torque: 2.3N·m

FHV7X-000-H19

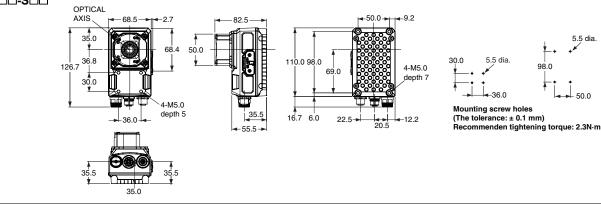






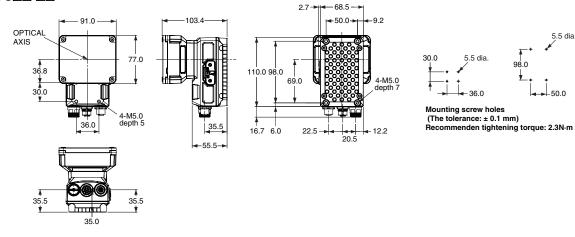
(The tolerance: ± 0.1 mm) Recommenden tightening torque: 2.3N·m

Standard Lens Modules FHV7X-



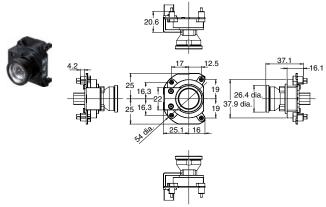
All-in-one Models with Lens and Lighting Modules FHV7X-0000-H00-00/ FHV7X-0000-S00-00



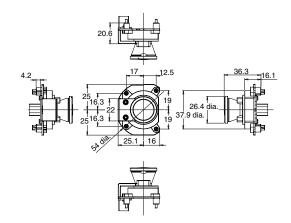


Lens Modules

High-speed Lens Modules FHV-LEM-H06







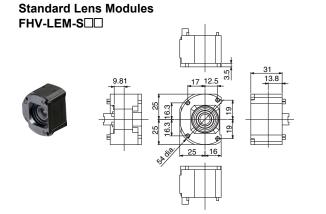
5.5 dia.

50.0

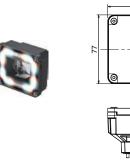
98.0

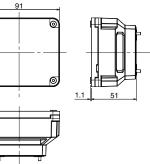
36.0

Lighting Modules



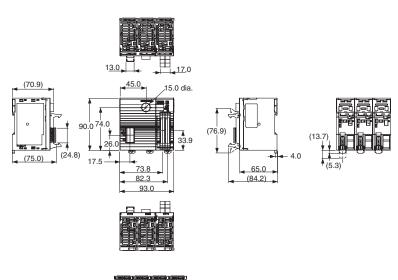
FHV-LTM-



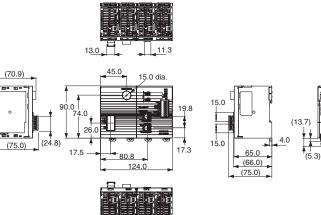


Smart Camera Data Unit



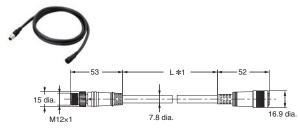


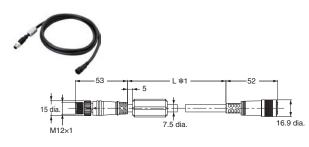
FHV-SDU30



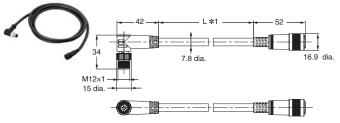


Bending Resistance Cables (Straight) FHV-VUB2 □M



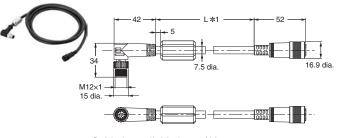


Bending Resistance Cables (Right angle) FHV-VULB2 □M



* Cable is available in 2m/3m/5m/10m/20m.

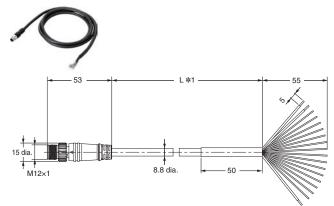
Super Bending Resistance Cables (Right angle) FHV-VULBX2 □M



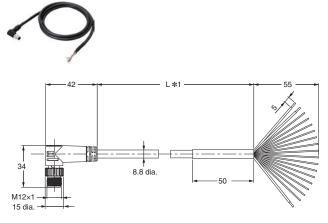


Cables

I/O cable (Bend resistant, straight) FHV-VDB2 ⊡M

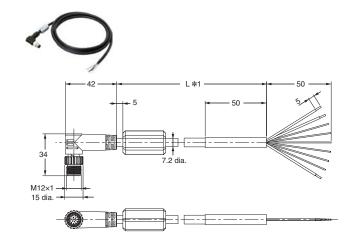


I/O cable (Bend resistant, right angle) FHV-VDLB2 □M



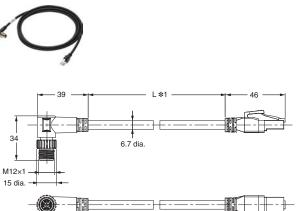
* Cable is available in 2m/3m/5m/10m/20m.

I/O cable (Super bend resistant, right angle) FHV-VDLBX2 □M



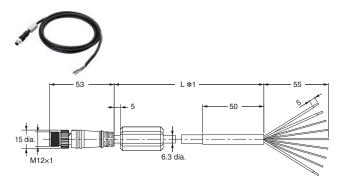
* Cable is available in 5m/10m.

Ethernet cable (Bend resistant, right angle) FHV-VNLB2 □M

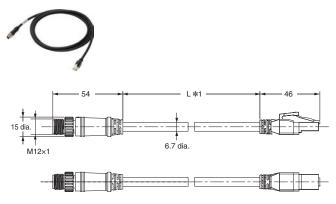


* Cable is available in 2m/3m/5m/10m/20m.

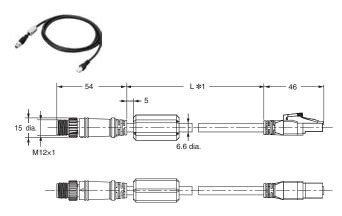
I/O cable (Super bend resistant, straight) FHV-VDBX2 □M



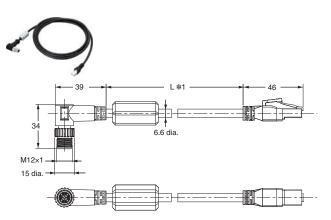
Ethernet cable (Bend resistant, straight) FHV-VNB2 □M



Ethernet cable (Super bend resistant, straight) FHV-VNBX2 □M

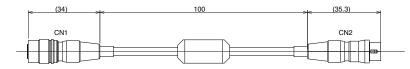


Ethernet cable (Super bend resistant, right angle) FHV-VNLBX2 IM



* Cable is available in 5m/10m.

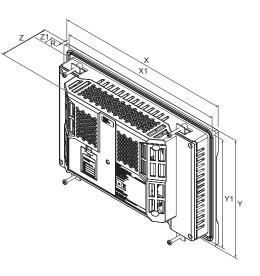
External Light Junction Cables for MDMC Light FHV-VFLX-GD



Optical Filters Light Cover Polarization Filter, Diffusion Filter FHV-XDF/-XPL/-XPL-IR FHV-XDF/-XPL/-XPL-IR FHV-XCV Image: Constraint of the state of the

Touch Panel Monitor OMRON Model NYE2A-20F11-00WR1000

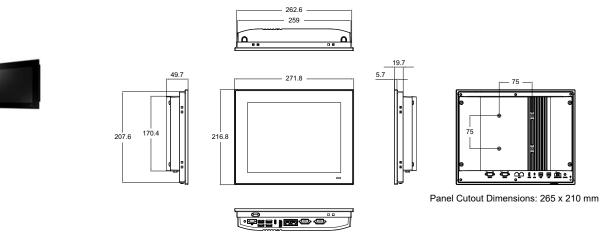




Screen size	Dimensions				Panel cutout dimensions		
Screen Size	X	Y	Z	R	X1	Y1	Z1 * 1
15.4 inch 4	120 mm	291 mm	69 mm	6.0 mm	392 ⁻⁰	268 ⁻⁰ +1 mm	1.6 to 6.0 mm
12.1 inch 3	340 mm	244 mm	69 mm	6.0 mm	310 ⁻⁰ mm	221 ⁻⁰ mm	1.0 10 0.0 11111

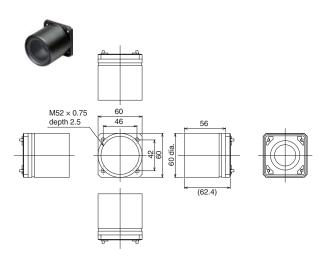
*1. The minimum panel thickness depends on the panel material.

Advantech Model PPC-310-OMR

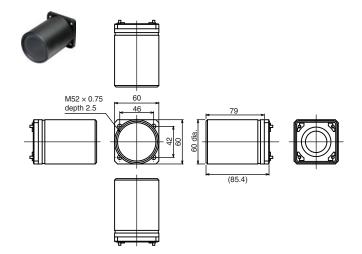


Waterproof Hoods

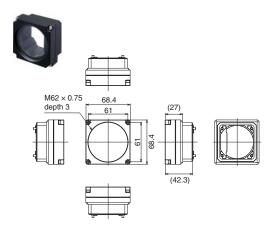
for C-mount Lens (Short) FHV-XHD-S



for C-mount Lens (Long) FHV-XHD-L



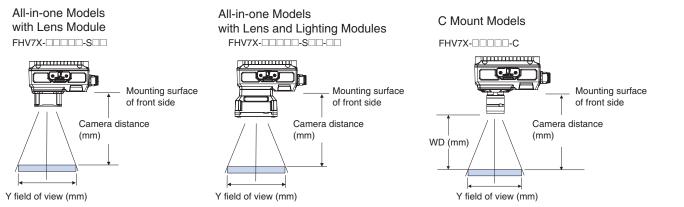
for Lens Modules FHV-XHD-LEM



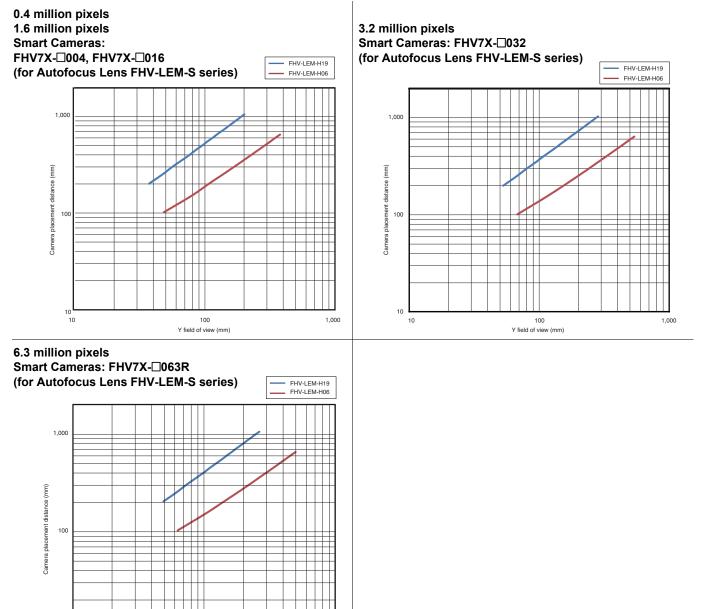
Meaning of Optical Chart

How-to View the Optical Chart

The X axis of the optical chart shows the field of vision (mm). The Y axis of the optical chart shows the camera installation distance (mm). The lengths of the fields of view given in the optical charts are the lengths of the Y axis.



Lens Modules: High-speed Lens Modules (Autofocus)



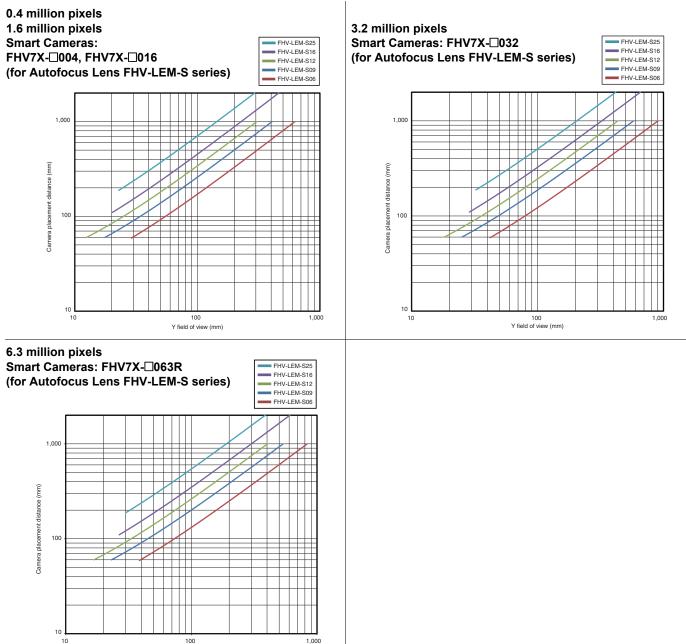
1,000

100

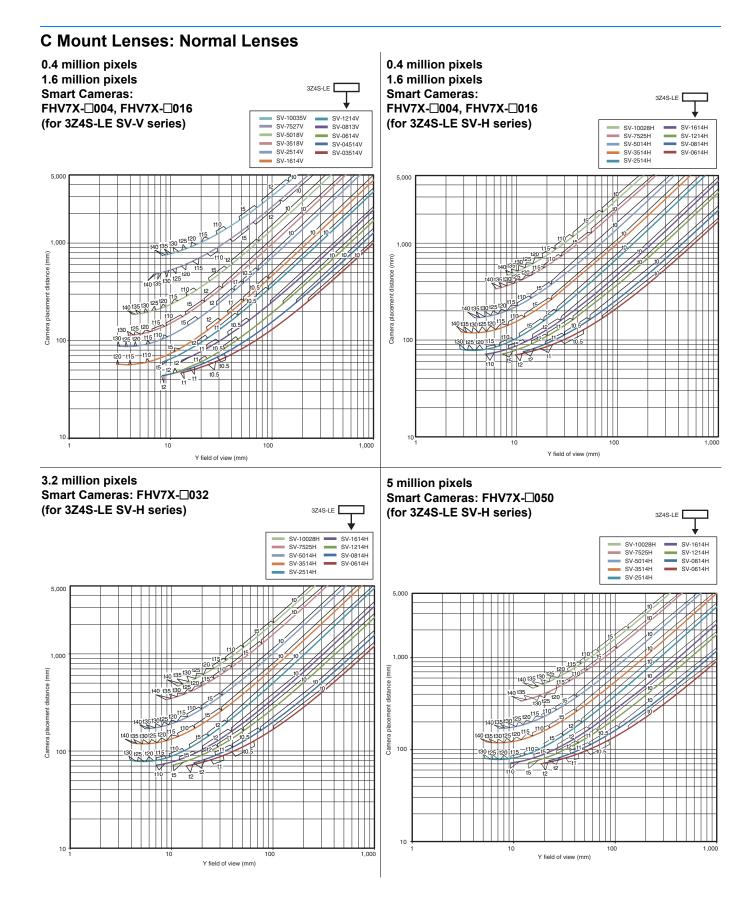
Y field of view (mm)

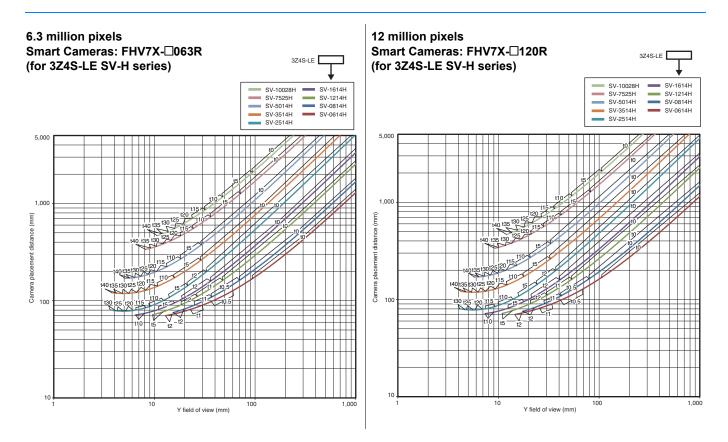
10 L

Lens Modules: Standard Lens Modules (Autofocus)



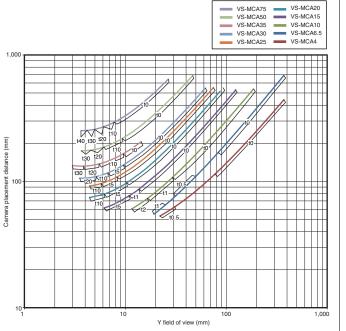
100 Y field of view (mm)

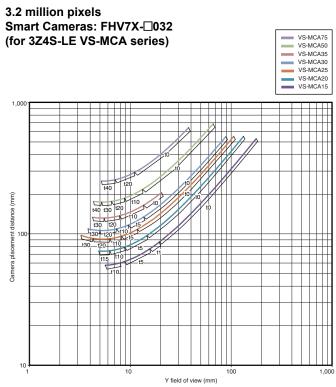


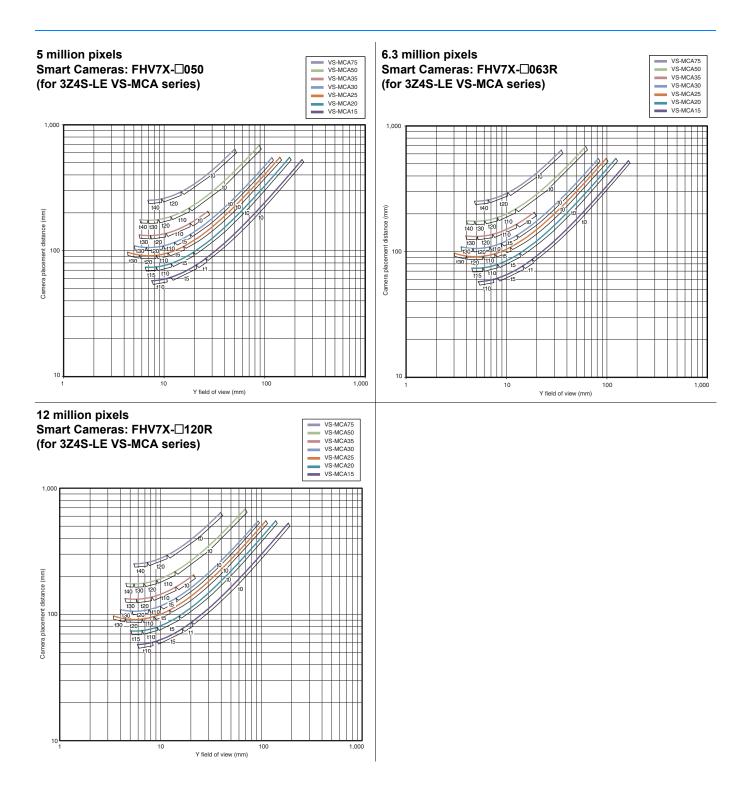


C Mount Lenses: Vibration/Shock-resistance Lens

400,000 pixels 1.6 million pixels Smart Cameras: FHV7X-□004, FHV7X-□016 (for 3Z4S-LE VS-MCA series)







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Related Manuals/Catalog

Cat. No.	Series	Manual
Z365	FH/FHV7	Vision System FH/FHV Series User's Manual
Z341	FH/FHV7	Vision System FH/FHV Series Processing Item Function Reference Manual
Z342	FH/FHV7	Vision System FH/FHV Series User's Manual for Communications Settings
Z408	FHV7	Smart Camera FHV Series Setup Manual
Q198	FLV/FL	FLV/FL Vision Accessory CATALOG

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