

# The flexibility meets ever-changing needs







Find out about Awards



# Ultimate flexibility to fit ever-changing production scene

···· P.4

# Nearly-infinite combination to fit any production scenes

#### Modular structure

The FHV7 Smart Camera allows you to flexibly combine a lens, light and image element, which are the important modules that determine the performance of a smart camera. You can integrate multiple vision sensors installed at your production line into this FHV7 Smart Camera, which can be customized to meet your inspection and measurement needs. By managing inventory of cameras based on modules, you can significantly reduce costs.



#### 

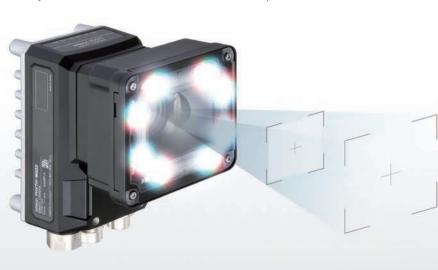
P.6

# Single camera for inspecting various products

#### Multi-color Light, Autofocus Lens, 12 Mpix

Like human eyes, the FHV7 Smart Camera with the multi-color light, autofocus lens and 12 mega pixels for wider areas stably measures objects in different colors and sizes on the same production line. The illuminating colors and lens focuses can be adjusted by parameters, so the mechanism for replacing lights and moving cameras is no longer necessary. This feature greatly reduces the time required for design and adjustment and the number of machine components.







# Raising production quality without sacrificing cycle time

#### Best-in-class speed \*1

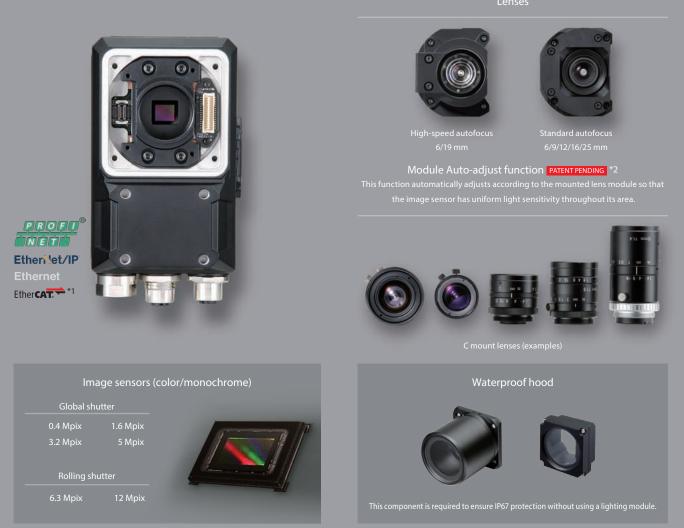
The inspection time can be reduced to 1/4 \*<sup>2</sup> of that required for existing models. This FHV7 Smart Camera enables you to keep the same cycle time even after you upgrade resolution or add inspection points.

\*1. Based on Omron investigation in October 2018.

\*2. Sample comparison to inspection time using vision sensors installed in customer's machine. Based on Omron investigation in October 2018.

## Nearly-infinite combination to fit any production

#### Smart Camera



\*1. The FHV-SDU30 EtherCAT<sup>®</sup> Interface is required for EtherCAT connection. \*2. "Patent pending" means that we applied for a patent in Japan, and "Patent

patent in Japan. (As of April 2019)

#### IP67 structure

Maintains IP67 waterproof structure even after module replacement, allowing use in wet conditions.



#### Captive screws

Captive screws are used in the modules. The screws do not drop on products.



#### 

### scenes

The FHV7 Smart Camera provides several options for components, allowing you to freely combine the lens and light with the camera and easily adjust the optical conditions to specific products. The footprint of the camera is not affected by module replacement. Even if a sudden change occurs in the product specification, the system can be ready after minimum rearrangement.

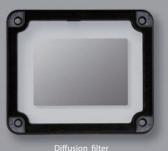
n all-in-one models with lens modules and light modules are also available

#### Modules

Lights











Polarization filter (infrared and visible light

#### Easy addition of external lights

By connecting the lighting controller, you can, from FHV7's setting window, easily adjust the light emission intensity and set light emissions to synchronize with the release of the shutter.



#### Easy filter replacement

The light cover and optical filter are replaceable, so you don't need to prepare a protection cover against dirt.



Dirty cover filters can be removed separately for replacement

# Single camera for inspecting various products



#### Multi-color Light Accommodates color variations

Multi-color light provides a quick solution to the issue of measuring different colors. For example, objects with variously colored packages on a production line are properly measured with the light that changes its illumination color to fit each object. When the product design is changed or a new models is added, you can simply change a parameter instead of replacing or fine-tuning lights. The production line is always ready for a wider variety of product.

#### Autofocus Lens Accommodates size variations

The autofocus lens covers a focal length range from 59 mm to 2,000 mm<sup>\*1</sup>. Even when products in different sizes are produced, the focus range can be changed easily by parameters. <sup>\*2</sup> This feature eliminates mechanical operation for changeover during product replacement, leading to a simpler system with higher productivity.

\*1. Differs depending on the lens type. See the optical chart on page 52 for details.
\*2. Set focuses for different product heights in advance and switch between them when you perform a changeover.



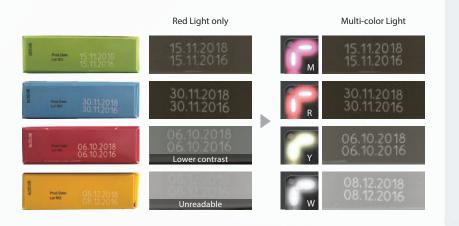
# Best-in-class resolution<sup>\*3</sup>: 12 megapixels

The image sensor with a 12 megapixels enables highprecision inspections for wider areas. This eliminates the need for installing multiple cameras or a mechanism to move a camera to capture different inspection points on different models on the same production line.

\*3. Based on Omron investigation in October 2018.

#### When inspecting products of different colors

As a product has more color options, some of the colors may cause low contrast under a single color illumination. The multi-color illumination allows switching colors for different product color options, ensuring stable inspections.



Working distance 90mm→100mm

#### When inspecting products of different sizes

When inspecting products such as plastic bottles that come in different sizes, you can perform a changeover only by switching the setting of the autofocus lens. The autofocus lens does not need the mechanism for moving the camera.





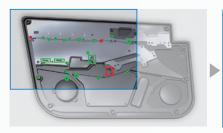
Always in focus even when the focal length changes





#### Expanding the range of parts inspection

Accurate and extensive inspection of parts mounting points on different automobile models is enabled without moving cameras. 5 Mpix



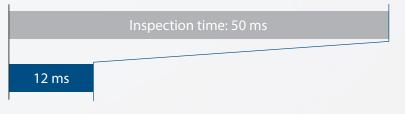




# Raising production quality without sacrificing cycle time

#### Inspection time reduced to 1/4<sup>\*1</sup>

#### Time required for external inspection of cans<sup>\*1</sup>



The inspection time can be reduced to  $1/4^{*1}$  of that required for existing sensors. You can carry out more precise, detailed quality inspection while keeping the same cycle time.

# Clear images facilitate inspection

Precise inspection with high-resolution images is possible while keeping the same cycle time as before. The FHV7 Smart Camera raises production quality with its ability to detect tiny tears or scratches on labels, which could not be previously detected.

#### 0.4 Mpix



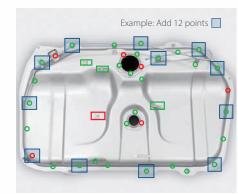


1.6 Mpix

Inspection time: 25 ms 24 ms

Shorter inspection time even when the number of pixels is increased

# More inspection points



Green: Inspection passed, Red: Inspection failed

#### 

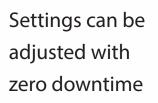


Best-in-class speed \*2 Image capture: Maximum speed 2.3 ms

Distributed processing across 2 cores

High-speed algorithm

The FHV7 Smart Camera provides an optimal solution for a problem of longer cycle times caused by inspection points added to raise production quality. You don't need to divide the field of view into several parts and assign them to multiple cameras or install a high-speed vision system.



Core1

nspe

Adjust-

ments

Measured values may change gradually due to workpiece variation or changes in external circumstance. Even in such cases, distributed processing across 2 cores allows you to perform cause analysis and setting adjustments as you make measurements. You can eliminate downtime and visual inspection of uninspected items.

downtime or

ost losse

settings from the next

trigger

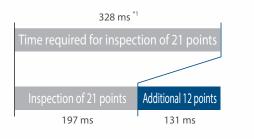
Reflect setting changes

00000

Tests performed

Settings changed

Use simulation software



\*1. Sample comparison to inspection time using vision sensors installed in customer's machine. Based on Omron investigation in October 2018 \*2. Based on Omron investigation in October 2018.

NG analyzed

## Traceability and serial number management

The FHV7 Smart Camera is suitable for applications in which inspection results and images are managed by product serial numbers.

#### Stable reading regardless of printing quality

#### 2D Code II delivers powerful code reading

The dedicated algorithm for stable 2D code reading under adverse conditions is implemented. Data based on the print quality specifications can be output, which contributes to stable printing.

Print Quality Grading Function

· ISO/IEC 15415

· ISO/IEC TR29158

Changing ambient brightness



Chips due to reflection



Low contrast





After processing/washing

Waterdrops and dirt Scratched damage

₩	1.1.11.11.11.11
Variations in start	Uneven line spacing
positions	

Poor printing quality in

high-speed line

ethali...le





Molding variations of forged object

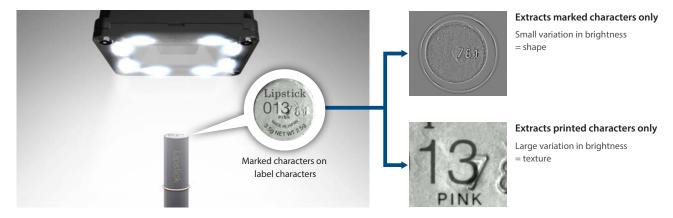
#### Stable reading of difficult-to-read characters (OCR)

Printed characters can be too close to each other, and characters can be printed on curved surfaces. Even in these cases, stable reading is possible. Also plus signs can be read.



#### Photometric stereo light extracts marked characters NEW

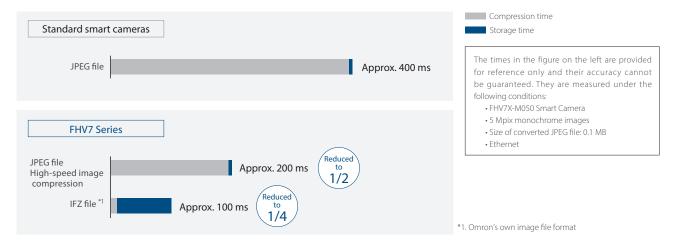
Our unique lighting algorithm separates an image into shapes and textures. Marked characters can be reliably read from the image containing only shapes which are separated from printed characters and patterns. This function is available when the FHV-LTM-W/R/IR Lighting Module (single color) or FL-PS Photometric Stereo Light is connected.



#### **Evidence management**

#### High-speed image storage and image compression

Image data is so large that conventional controllers could not store all images due to limited storage time and storage capacity. The FHV7 Smart Camera has algorithms and hardware that can save images in Omron formats and compress image data at high speed, enabling all images to be stored to meet increasing needs in quality control.



#### Images are saved even during measurements

Distributed processing across 2 cores allows the CPU to perform parallel processing of measurements and image logging. With connection to a high-speed, large-capacity NAS, all images on the high-speed line can be saved, which was previously difficult. \*2 Trend analysis of all saved images quickly isolates errors and facilitates countermeasures.

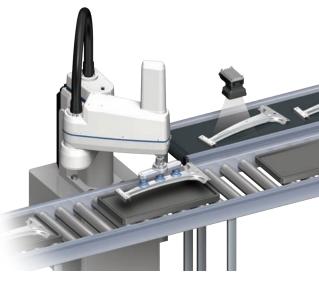
- \*2. All images can be saved under the following conditions:
  - One 0.4 Mpix camera
  - Measurement time of 30 ms
  - JPEG file
- Images can be saved continuously for approx.
   380 days when a 3 TB NAS is used
   (based on 8 hours of operation a day)

Standard smart cameras         Priority on measurement       Image input1       Measurement       Image input2       Measurement       Image input2       Measurement       Interruption       Cordinally, not all images cordinally, n			
Priority on measurement processing       Image input 1       Measurement inage input 2       Measurement inage input 3       Measurement inage input 3       Measurement inage input 3       Since logging was not possible during measurement, the user had to choose either measurement or logging. Accordingly, not all images could be saved or image input 1       Measurement inage input 3       Measurement inage input 4       Measurement inage input 5       Accordingly, not all images could be saved or image input 1       Measurement inage input 3       Measurement inage input 4       Measurement inage input 3	Standard smart cameras		
processing       Image logging       Image logging <th>1</th> <th>1 1 1</th> <th>Issue</th>	1	1 1 1	Issue
FHV7 Series         FHV7 Series         Solution         Image input1       Measurement         Image input2       Measurement         Image input2       Measurement         Image input3       Measurement         Image input3       Measurement         Image logging are processed in parallel.		Image input 2 Measurement Image input 3 Measurement	
Priority on image logging       Image input 1       Measurement       Image input 2       Measurement       Accordingly, not all images could be saved or image input triggers had to be delayed depending on the measurement trigger intervals.         FHV7 Series       Solution         Measurement       Image input 2       Measurement       Solution         Measurement       Image input 3       Measurement       Measurement       Measurement         Image input 1       Measurement       Image input 3       Measurement       Measurement	processing		either measurement or logging.
Priority on image logging       Image input 1       Measurement       Image input 2       Measurement       depending on the measurement trigger intervals.         FHV7 Series       Image input 1       Measurement       Image input 3       Measurement       Solution         Image input 1       Measurement       Image input 3       Measurement       Measurement       Measurement			
FHV7 Series       FHV7 Series       Solution       Measurement     Image input 3       Measurement     Measurement       Image input 1     Measurement       Image input 2     Measurement       Image input 3     Measurement	Priority on image logging Image input 1 Measurement		
Image input 1         Measurement         Image input 3         Measurement         Measurement           Image input 1         Measurement         Image input 3         Measurement		Image logging 1 Image logging 2	interveis.
Image input 1         Measurement         Image input 3         Measurement         Measurement           Image input 1         Measurement         Image input 3         Measurement			
Image input 1         Measurement         Image input 3         Measurement         Measurement           Image input 1         Measurement         Image input 3         Measurement			
Image input 1         Measurement         Image input 3         Measurement         Measurement           Image input 1         Measurement         Image input 3         Measurement	FHV7 Series		
Image input 1         Measurement         Image input 3         Measurement         Measurement           Image input 1         Measurement         Image input 3         Measurement			Solution
processed in parallel.	Image input 1 Measurement	Image input 2 Measurement Image input 3 Measurement	
As a result, you can save all images.		Image logging 1	processed in parallel.
Allimator and and			As a result, you can save all images.
		All Illiages ale saveu	
	1		
All images are saved	Image input 1 Measurement	Image logging 1	Measurement and image logging are processed in parallel.
	I	1 1	

Application Examples

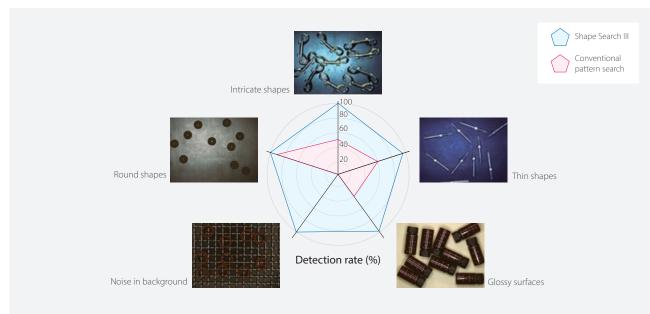
## Pick and place

The FHV7 Smart Camera can be combined with robots for picking and assembling applications.



#### Shape Search III stably detects all types of objects

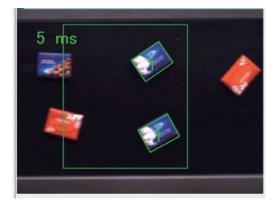
Stable position detection is performed regardless of shape, material, or background.



#### Sorting mixed models

Different types of the searched objects can be sorted.





#### Think & See, the core technology of Shape Search III

"Think & See" is Omron's powerful core technology for image sensing. Omron is continuously developing technologies to measure, detect, or identify the positions, orientations, shapes, materials, colors, status, or attributes of things, people, vehicles, or other objects faster, more precisely, and more easily than the human eye under various conditions.

Think &See



#### **OMRON** [ 13

#### Easy output to major robot manufacturers' devices

The dialog boxes for the FHV7 Smart Camera and the programs for various vendors' robots greatly reduce the set-up time for robot applications. Refer to the system configuration diagram (P. 21) for connection details.







Place

#### 3-step easy setting

Verified robot communication programs and flowcharts required for robot applications are provided. You don't need to design communications and create a flowchart to set up a robot application.

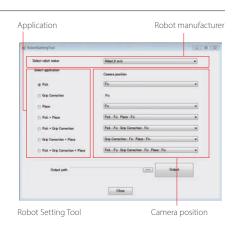
#### STEP 1

Obtain robot program and flowchart

#### Just a few clicks in Robot Setting Tool

Select 3 items to obtain the communication program and flowchart you need.

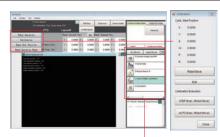
You can download the Robot Setting Tool from the following URL: http://www.ia.omron.com/fhv



STEP **2** Calibrate

#### Move robot for calibration from the FHV7 Series

The obtained flowchart can be used to move the robot for calibration from the FHV7 Smart Camera. There is no need to create a program for robot calibration.



Flowchart Move robot

STEP **3** Check operations

#### Set up and check application from the FHV7 Series

Set the coordinates of the robot and check robot operations using the dialog boxes.



Set the coordinates of the robot

operations

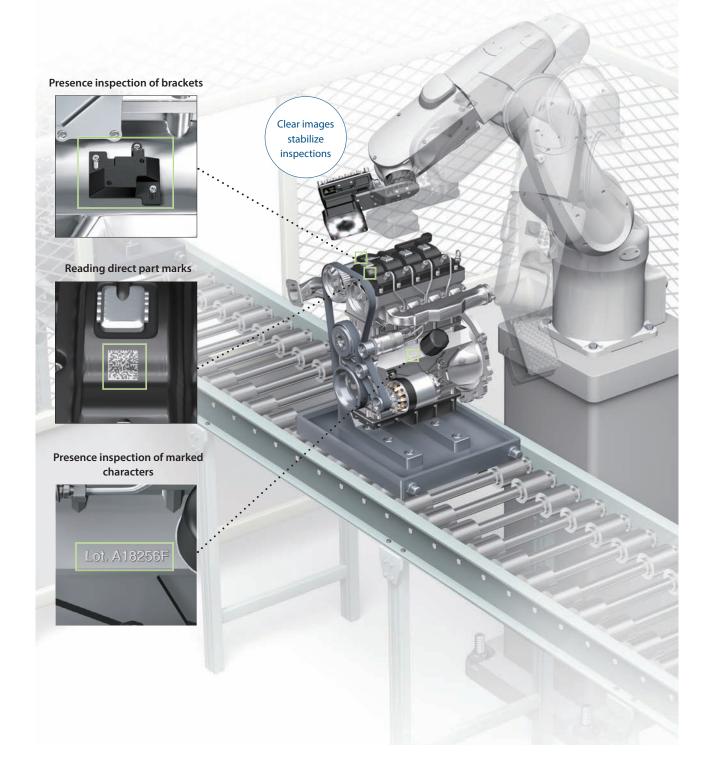
### Flexible multipoint inspection using robots

The FHV7 Smart Camera can be installed on robot arms to inspect objects from multiple directions.

#### Vision inspection suited to each location

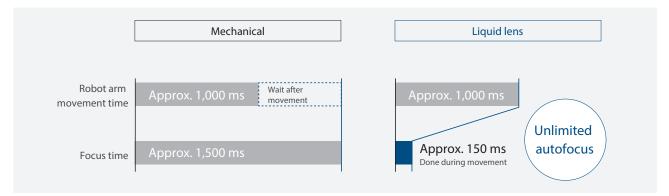
The FHV7 Smart Camera, which is moved to each inspection point, adjusts field of view, precision, and focus to match the location.

External inspection by the human eye can be replaced with automated inspection using robots.



#### Ultra-high-speed, long-life lens module PATENT PENDING \*1

New high-speed lens modules using a liquid lens have been added to the lineup. Advanced control of the liquid lens enables the lens to focus about 10 times faster than a mechanical focus lens, allowing settings to be changed during movement of the robot arm.\*<sup>2</sup> General mechanical focus mechanisms break due to deterioration of the drive mechanism or motor when they perform autofocus tens of thousands of times. The liquid lens provides unlimited autofocus and long life.



Note: The above times are when the focus value is changed from minimum to maximum. These times are provided for reference only and are not guaranteed. \*1. "Patent pending" means that we applied for a patent in Japan, and "Patented" means that we obtained a patent in Japan. (As of April 2019) \*2. Set focuses for different product heights in advance and switch between them.

#### Much less maintenance Super-flexible cable

The new cable offers approximately 10 times the bending resistance of conventional FHV7 flexible cables. High bending resistance significantly reduces the frequency of replacing the cables on robot arms.



#### Reduces halation from metallic or glossy surfaces

The High Dynamic Range (HDR) function minimizes the influence of changes in lighting conditions and light reflection. This enables stable inspections even for materials that are difficult to light evenly, such as metal parts or glossy films, or in locations subject to external light interference. Original image



Halation

#### Halation-reduced image



Stable detection for metallic surfaces subject to gloss and inconsistent lighting

## Filtering to emphasize difficult-to-find defects

Image input & filtering



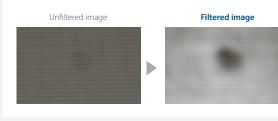
#### Stripe Removal Filter II 🖳

The stripped pattern is filtered out so that only required aspects are shown clearly. Vertical, horizontal, and diagonal stripes can be removed.



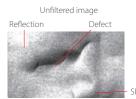
#### Even Emphasis Unevenness 🍖

This filter removes background pattern and enhances low-contrast unevenness.

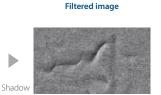


#### Brightness Correct Filter

This filter cuts out uneven lighting and changes in brightness caused by workpiece surface irregularities to make characteristic features stand out clearly.



The wavy inconsistencies are judged as defects.



Uneven areas are removed so that only the defect appears in the inspection.

Anti Color Shading 📳 PATENTED



Specific shades that hide defects are removed so that tiny scratches and dirt can be precisely detected. This advanced filtering was achieved through the Real Color Sensing technology.



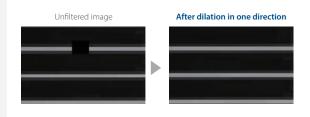
#### Emphasis Line Defect/Emphasis Circle Defect 둯

These filters enhance defects in high background noise or scratches on embossed surfaces.



#### Custom Filter 🐚

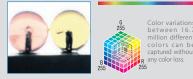
You can set the mask coefficients as required for these filters. The mask size can be up to 21 x 21. You can flexibly set smoothing, edge extraction, dilation, and erosion for the image.



Real Color Sensing PATENTED

Real-color processing is an image processing technology that performs high-speed processing of full-color images with a total of 16.7 million colors (256 tones per RGB channel). This means that image processing can be performed with the same color information that is visible to the human eye, and stable measurements can be performed under lighting that closely resembles natural light.

#### **Real Color Sensing**



The camera image is processed as-is without any loss of quality. This enables even the slightest of color differences to be captured with high accuracy



Captured images are converted to a 256-shade monochrome image and processed. This enables more stable inspection compared to binary level processing, but slight changes in color cannot be detected with this method.

#### Color segmentation processing



Captured images are converted to a black and white two-color image and processed. This reduces the amount of data and enables high-speed processing.

#### **OMRON** [ 17

## Processing items for various types of inspections

Inspection & measurement



#### Precise Defect 🔉

#### Detection of dirt on paper cups

This processing item is used to detect scratches and dirt on paper cups and molded plastics, as well as oil stains on metal surfaces. Real Color Sensing makes it possible to detect dirt in various colors.

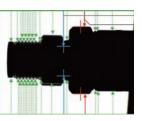




#### Scan Edge Position and Scan Edge Width

#### Inspection of groove depth of metal shafts

The maximum and minimum widths within the region are measured simultaneously. This processing item is very useful especially for the measurement of groove depths of metal shafts.



#### Labeling 🌆

#### Hole counting

The number of labels with the specified color and size is counted. Also, the area and center of gravity of the specified labels are measured.



#### Character Inspection

#### Label printing inspection

Characters are recognized by pattern search, and this enables special fonts and non-alphanumeric characters to be inspected. Automatically extracting a model and selecting an index from the list help you easily set up your dictionary. Using the user dictionary, the Character Inspection performs pattern search to recognize characters. Auto model extraction (Special fonts can be read)



Index selection from list





2 times faster and higher detection\*

#### Cable arrangement inspection

Just register a model, and the cable arrangement inspection is completed in one go. Repeating color detection is not necessary.



\* Compared with Search under our test conditions in April 2019.

#### Fine Matching 🚹

#### Inspection for label rips

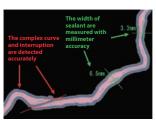
The registered reference image is compared against the input image and tiny differences are detected at high speed. Scratches on the intricate patterns and unexpected dirt in the color are precisely detected.



#### Glue Bead Inspection 🎢

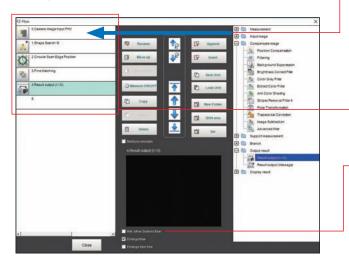
#### Path and width inspection

Just define the start and end points of the object to evaluate sealing numerically. This minimizes inconsistencies in inspection. This method enables accurate inspection of complex curves and interruptions.



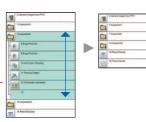
## Easy-to-use system with high functionality

#### Easy measurement flow creation



#### Drag and drop

Just drag and drop pre-installed processing items from the processing item list to the flowchart to build a measurement flow.



Complex and long processes can be grouped into folders.

#### Copy & paste processing items from other scenes

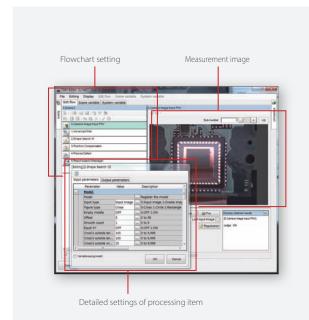
1.Scen	e 1	
1.Scen	e 1	^
2.Scen	e 2	
3.Scen	e 3	
4.Scen	e 4	
5.Scen	e 5	
6.Scen	e 6	
7.Scen	e 7	
8.Scene 8		~
4-4		
	3.Edge Position	

You can set up a new flow menu by combining different processing items copied from other scenes. When reusing the setting of other scenes, you don't need to make adjustments.

#### Simple setting with menus

#### Total Design Management Editor

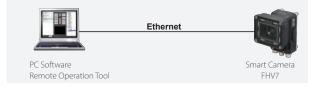
The design interface allows you to design complex measurement processes while managing variables. This simple GUI manages complicated branching processes and data sharing across measurement scenes and eliminates the need to switch screens.



#### Setting and operating from a computer

Use a dedicated software to create measurement flows and measurement conditions. The software can also be used for remote monitoring and control via a network.

You can download the software for free after purchasing the product and signing up online. For details, see the member registration sheet attached to the FHV7 Smart Camera.



#### Operation via touch panel monitor

The touch panel monitor with pre-installed software for the FHV7 Smart Camera can be used as an easy-to-install operator interface.



Touch Panel Monitor OMRON Model NYE Series Advantech Model PPC-310-OMR\*

\* Ask Advantech about the warranty period and coverage of this product. https://www.advantech.com/contact/offices/

#### Customizable user interface prevents incorrect operation

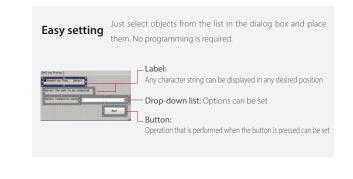
The processing item setting window includes parameters for initial setting and for daily adjustments. To prevent incorrect operation, you can customize the adjustment window to show only parameters that are required for your daily operation.

Example 1: Show only necessary parameters

elegection Type Detect	
Select parts to be mapeched	
Selectors	

Example 2: Show a wizard





#### Easy machine control design

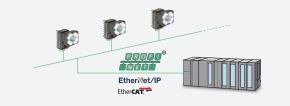
Connecting Sysmac devices via EtherCAT and using the integrated development environment Sysmac Studio allow you to design machine operation as you want.



#### Easy connection to field networks

#### EtherCAT \*, EtherNet/IP, PROFINET

The FHV7 Smart Camera includes communication interfaces for compatibility with a wide range of network protocols used at production sites. This helps reduce the design work required for data communications between the camera and a PLC.



#### Easy setting of output items

Just select variables to output measurement results.

0 0 Integer 123					
	No.	Offset	Data Type	Data	Value
	0	0	Integer	123	
	1	4	Double	123.456	
2 12 String ABCDE 3	2	12	String	ABCDE	

## Product lineup

The product lineup includes general-use Smart Cameras and high-speed, high-accuracy vision systems. You can choose the right one according to your requirements for speed and accuracy of each process. Both FH Series and FHV7 Series have the common user interface and operating procedures, so it is possible to share the same image inspection method across the production line. This reduces the time for operator training. The compatibility of setting data enables you to upgrade hardware easily when speed and accuracy enhancement is needed.

		For various types of inspections Smart Camera FHV7 Series		For processes requiring high speed and high resolution Vision System FH Series			
					cije		<b>)</b> 7-2
			FHV7X		FH-205	0	FH-5050
	Performance *1		*		**		***
	No. of cameras		1		8		8
Hardware Grade	Resolution	0.4 <sub>Mpix</sub>	<b>1.6</b> Mpix <b>6.3</b>	3.2 Mpix 12 Mpix	0.4 <sub>Mpix</sub> 5 <sub>Mpix</sub>	1.6 <sub>Мріх</sub> 12 <sub>Мріх</sub>	3.2 <sub>Mpix</sub> 20.4
One Software	Screens	Mpix Mpix Main screen		Measurement flow setting screen        Output     Description     Descript		nent condition	
	Image logging format		JPEG	BMF	DIFZ		
	Setting data			Compa	tible *2		

\*1.  $\star$ : The more starts, the higher the performance.

<sup>\*2.</sup> Settings for the common functions can be shared between series.

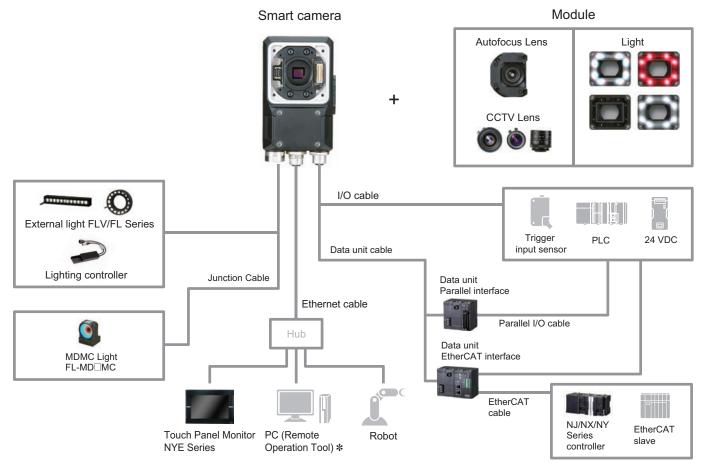
# Smart Camera FHV7 Series

# Ultimate flexibility to fit ever-changing production scene

- Modular structure for a wide range of applications
- · Responding to changes of objects like human eyes
- · Raising quality standard without sacrificing cycle time



#### System Configuration



\* After purchasing the product, you can register as a member to download this for free. For details, see the member registration sheet included with the FHV7 Smart Camera.

#### **Model Selection**

To select a model of Smart Camera, use the WEB Selector.

http://www.ia.omron.com/fhv\_select\_e

**Note:** With certain module types, the operation of some combinations cannot be guaranteed. Use the Web Selector to select the correct combination of image sensor, lens, resolution, and light.

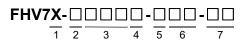


#### **FHV7 Series**

#### **Model Number Structure**

#### FHV7 Series Model Number Legend

Use this legend when determining the product specifications from the model number. When ordering, use a model number from the table in *Ordering Information*.



No.	Classification	Code	Meaning
1	Controller specification	Х	64-bit OS model
2	Imaga appaga	М	Monochrome
2	Image sensors	С	Color
		004	0.4 million pixels
		016	1.6 million pixels
3	Resolution	032	3.2 million pixels
3	Resolution	050	5 million pixels
		063	6.3 million pixels
		120	12 million pixels
	Obutton turne	-	Global shutter
4	Shutter type	R	Rolling shutter
		С	C mount
5	Lens	Н	High-speed lens module (autofocus)
		s	Standard lens module (autofocus)

No.	Classification	Code	Meaning
	Freedlawsth	06	6 mm
		09	9 mm
6		12	12 mm
0	Focal length	16	16 mm
		19	19 mm
		25	25 mm
		R	Red
7	Light color	W	White
7		IR	IR
		MC	Multi color

#### Configuration

For the Smart Camera FHV7 series, there are five configurations below by module combinations.

Smart	t camera	Lens	Internal lighting	Protective structure	Integrated model	Appearance	Configuration
0.4 million pixels FHV7X004 1.6 million pixels FHV7X016 3.2 million pixels FHV7X032		C mount lens 3Z4SLE		IP40	FHV7X-		C mount lens/IP40
5 million pixels 6.3 million pixels 12 million pixels	FHV7X-050- FHV7X-063R- FHV7X-0120R-	SVV 3Z4SLE SVH	N/A	IP67 Waterproof Hoods required FHV-XHD-S FHV-XHD-L	N/A	ব্	C mount lens/IP67
			N/A	IP40	FHV7XH FHV7XS		Lens module/IP40
1.6 million pixelsFHV7X-II3.2 million pixelsFHV7X-II	FHV7X004 FHV7X016 FHV7X032 FHV7X063R	HV7X-004-0 FHV lens module HV7X-016-0 FHV-LEM-H0 HV7X-0032-0 EHV-LEM SO		IP67 Waterproof Hoods required FHV-XHD-LEM	N/A		Lens module/IP67
		F	FHV-LTM-🗆	IP67	FHV7X H FHV7X S		Lens module /Internal lighing - IP67

#### **Ordering Information**

#### Smart Cameras C Mount Models

Item	Resolution	Мо	del
item	Resolution	Color	Monochrome
	0.4 million pixels	FHV7X-C004-C	FHV7X-M004-C
21	1.6 million pixels	FHV7X-C016-C	FHV7X-M016-C
	3.2 million pixels	FHV7X-C032-C	FHV7X-M032-C
	5 million pixels	FHV7X-C050-C	FHV7X-M050-C
	6.3 million pixels	FHV7X-C063R-C	FHV7X-M063R-C
~ <del>.</del>	12 million pixels	FHV7X-C120R-C	FHV7X-M120R-C

#### **Lens Modules**

Item		Focal length	Model
	High-speed lens module	6 mm	FHV-LEM-H06
<u>C</u>	(Autofocus)	19 mm	FHV-LEM-H19
	Standard lens module (Autofocus)	6 mm	FHV-LEM-S06
		9 mm	FHV-LEM-S09
		12 mm	FHV-LEM-S12
		16 mm	FHV-LEM-S16
		25 mm	FHV-LEM-S25

 For the focal length and horizontal field of view, refer to specifications (P.33) and optical charts of the lens module (P.52).
 Note: Refer to the *Vision Accessory Catalog* (Cat No. Q198) for details on C-mount lenses.

#### **Lighting Modules**

ltem	Light color	Model
	Multi color	FHV-LTM-MC
	Red	FHV-LTM-R
0	White	FHV-LTM-W
	IR	FHV-LTM-IR

#### **FHV7 Series**

Item	Resolution	Lens	Focal length	1	Model
item	Resolution	Lens	Focal length	Color	Monochrome
		High-speed lens module	6 mm	FHV7X-C004-H06	FHV7X-M004-H06
		(autofocus)	19 mm	FHV7X-C004-H19	FHV7X-M004-H19
			6 mm	FHV7X-C004-S06	FHV7X-M004-S06
	0.4 million pixels		9 mm	FHV7X-C004-S09	FHV7X-M004-S09
		Standard lens module (autofocus)	12 mm	FHV7X-C004-S12	FHV7X-M004-S12
		(44(6)6643)	16 mm	FHV7X-C004-S16	FHV7X-M004-S16
			25 mm	FHV7X-C004-S25	FHV7X-M004-S25
		High-speed lens module	6 mm	FHV7X-C016-H06	FHV7X-M016-H06
		(autofocus)	19 mm	FHV7X-C016-H19	FHV7X-M016-H19
			6 mm	FHV7X-C016-S06	FHV7X-M016-S06
	1.6 million pixels	Standard lens module (autofocus)	9 mm	FHV7X-C016-S09	FHV7X-M016-S09
			12 mm	FHV7X-C016-S12	FHV7X-M016-S12
			16 mm	FHV7X-C016-S16	FHV7X-M016-S16
3 7			25 mm	FHV7X-C016-S25	FHV7X-M016-S25
We la		High-speed lens module (autofocus)	6 mm	FHV7X-C032-H06	FHV7X-M032-H06
			19 mm	FHV7X-C032-H19	FHV7X-M032-H19
The second second			6 mm	FHV7X-C032-S06	FHV7X-M032-S06
	3.2 million pixels		9 mm	FHV7X-C032-S09	FHV7X-M032-S09
		Standard lens module (autofocus)	12 mm	FHV7X-C032-S12	FHV7X-M032-S12
		(uutoroodo)	16 mm	FHV7X-C032-S16	FHV7X-M032-S16
			25 mm	FHV7X-C032-S25	FHV7X-M032-S25
		High-speed lens module	6 mm	FHV7X-C063R-H06	FHV7X-M063R-H0
		(autofocus)	19 mm	FHV7X-C063R-H19	FHV7X-M063R-H1
			6 mm	FHV7X-C063R-S06	FHV7X-M063R-S0
	6.3 million pixels		9 mm	FHV7X-C063R-S09	FHV7X-M063R-S0
		Standard lens module (autofocus)	12 mm	FHV7X-C063R-S12	FHV7X-M063R-S1
			16 mm	FHV7X-C063R-S16	FHV7X-M063R-S1
			25 mm	FHV7X-C063R-S25	FHV7X-M063R-S2

#### All-in-one Models with Lens Module

\* For the focal length and horizontal field of view, refer to specifications (P.33) and optical charts of the lens module (P.52).

#### All-in-one Models with Lens and Lighting Modules

Item F	Resolution	Lens	Focal length	Light color		odel
		Long	i oouriongili	Light color	Color	Monochrome
				Multi color	FHV7X-C004-H06-MC	FHV7X-M004-H06-M
			6 mm	Red		FHV7X-M004-H06-R
			0 mm	White	FHV7X-C004-H06-W	FHV7X-M004-H06-W
		High-speed		IR		FHV7X-M004-H06-IF
		lens module (autofocus)		Multi color	FHV7X-C004-H19-MC	FHV7X-M004-H19-M
		()		Red		FHV7X-M004-H19-R
			19 mm	White	FHV7X-C004-H19-W	FHV7X-M004-H19-W
				IR		FHV7X-M004-H19-IF
				Multi color	FHV7X-C004-S06-MC	FHV7X-M004-S06-M
				Red		FHV7X-M004-S06-R
			6 mm	White	FHV7X-C004-S06-W	FHV7X-M004-S06-W
				IR		FHV7X-M004-S06-IF
				Multi color	FHV7X-C004-S09-MC	FHV7X-M004-S09-M
					FHV/X-C004-S09-WC	
0.4	million pixels		9 mm	Red		FHV7X-M004-S09-R
				White	FHV7X-C004-S09-W	FHV7X-M004-S09-W
				IR		FHV7X-M004-S09-IF
		o		Multi color	FHV7X-C004-S12-MC	FHV7X-M004-S12-N
		Standard lens module	12 mm	Red		FHV7X-M004-S12-R
		(autofocus)	12	White	FHV7X-C004-S12-W	FHV7X-M004-S12-W
				IR		FHV7X-M004-S12-IF
				Multi color	FHV7X-C004-S16-MC	FHV7X-M004-S16-N
			10	Red		FHV7X-M004-S16-R
			16 mm	White	FHV7X-C004-S16-W	FHV7X-M004-S16-V
				IR		FHV7X-M004-S16-IF
			25 mm	Multi color	FHV7X-C004-S25-MC	FHV7X-M004-S25-N
				Red		FHV7X-M004-S25-R
	P			White	FHV7X-C004-S25-W	FHV7X-M004-S25-W
				IR		FHV7X-M004-S25-IF
				Multi color		FHV7X-M004-325-II
			6 mm		FHV7X-C016-H06-MC	
				Red		FHV7X-M016-H06-F
		High-speed		White	FHV7X-C016-H06-W	FHV7X-M016-H06-V
		lens module		IR		FHV7X-M016-H06-I
		(autofocus)		Multi color	FHV7X-C016-H19-MC	FHV7X-M016-H19-N
			19 mm	Red		FHV7X-M016-H19-R
			19 mm	White	FHV7X-C016-H19-W	FHV7X-M016-H19-V
				IR		FHV7X-M016-H19-I
				Multi color	FHV7X-C016-S06-MC	FHV7X-M016-S06-N
			<b>•</b>	Red		FHV7X-M016-S06-R
			6 mm	White	FHV7X-C016-S06-W	FHV7X-M016-S06-W
				IR		FHV7X-M016-S06-IF
				Multi color	FHV7X-C016-S09-MC	FHV7X-M016-S09-N
				Red		FHV7X-M016-S09-R
1.6	million pixels		9 mm	White	FHV7X-C016-S09-W	FHV7X-M016-S09-W
				IR		FHV7X-M016-S09-IF
					 FHV7X-C016-S12-MC	
		Standard		Multi color		FHV7X-M016-S12-M
		lens module	12 mm	Red		FHV7X-M016-S12-R
		(autofocus)		White	FHV7X-C016-S12-W	FHV7X-M016-S12-W
				IR		FHV7X-M016-S12-IF
				Multi color	FHV7X-C016-S16-MC	FHV7X-M016-S16-M
			16 mm	Red		FHV7X-M016-S16-R
			10 11111	White	FHV7X-C016-S16-W	FHV7X-M016-S16-V
				IR		FHV7X-M016-S16-IF
				Multi color	FHV7X-C016-S25-MC	FHV7X-M016-S25-M
				Red		FHV7X-M016-S25-R
			25 mm	White	FHV7X-C016-S25-W	FHV7X-M016-S25-W
			1	IR		FHV7X-M016-S25-I

#### **FHV7 Series**

Item	Resolution	Lens	Focal length	Light color	Color	Monochrome
				Multi color	FHV7X-C032-H06-MC	FHV7X-M032-H06-MC
			6	Red		FHV7X-M032-H06-R
			6 mm	White	FHV7X-C032-H06-W	FHV7X-M032-H06-W
		High-speed		IR		FHV7X-M032-H06-IR
		lens module (autofocus)		Multi color	FHV7X-C032-H19-MC	FHV7X-M032-H19-MC
		(autolocus)		Red		FHV7X-M032-H19-R
			19 mm	White	FHV7X-C032-H19-W	FHV7X-M032-H19-W
				IR		FHV7X-M032-H19-IR
				Multi color	FHV7X-C032-S06-MC	FHV7X-M032-S06-MC
				Red		FHV7X-M032-S06-R
			6 mm	White	FHV7X-C032-S06-W	FHV7X-M032-S06-W
				IR	111177-0032-000-11	FHV7X-M032-S06-IR
					 FUN/7X C022 C00 MC	
				Multi color	FHV7X-C032-S09-MC	FHV7X-M032-S09-MC
	3.2 million pixels		9 mm	Red		FHV7X-M032-S09-R
				White	FHV7X-C032-S09-W	FHV7X-M032-S09-W
				IR		FHV7X-M032-S09-IR
		Standard		Multi color	FHV7X-C032-S12-MC	FHV7X-M032-S12-MC
		lens module	12 mm	Red		FHV7X-M032-S12-R
		(autofocus)		White	FHV7X-C032-S12-W	FHV7X-M032-S12-W
				IR		FHV7X-M032-S12-IR
			16 mm	Multi color	FHV7X-C032-S16-MC	FHV7X-M032-S16-MC
				Red		FHV7X-M032-S16-R
				White	FHV7X-C032-S16-W	FHV7X-M032-S16-W
				IR		FHV7X-M032-S16-IR
				Multi color	FHV7X-C032-S25-MC	FHV7X-M032-S25-MC
			25 mm	Red		FHV7X-M032-S25-R
The second s				White	FHV7X-C032-S25-W	FHV7X-M032-S25-W
I IIIII K				IR		FHV7X-M032-S25-IR
				Multi color	FHV7X-C063R-H06-MC	FHV7X-M063R-H06-M
				Red		FHV7X-M063R-H06-R
ALC: NOT			6 mm	White	FHV7X-C063R-H06-W	FHV7X-M063R-H06-W
		High-speed		IR		FHV7X-M063R-H06-IR
		lens module		Multi color	FHV7X-C063R-H19-MC	FHV7X-M063R-H19-M
		(autolocus)	autofocus)	Red		FHV7X-M063R-H19-R
			19 mm	White	FHV7X-C063R-H19-W	FHV7X-M063R-H19-W
				IR		FHV7X-M063R-H19-IR
				Multi color		
					FHV7X-C063R-S06-MC	FHV7X-M063R-S06-M
			6 mm	Red		FHV7X-M063R-S06-R
				White	FHV7X-C063R-S06-W	FHV7X-M063R-S06-W
				IR		FHV7X-M063R-S06-IR
				Multi color	FHV7X-C063R-S09-MC	FHV7X-M063R-S09-M0
	6.3 million pixels		9 mm	Red		FHV7X-M063R-S09-R
	F			White	FHV7X-C063R-S09-W	FHV7X-M063R-S09-W
				IR		FHV7X-M063R-S09-IR
		o		Multi color	FHV7X-C063R-S12-MC	FHV7X-M063R-S12-M0
		Standard lens module	12 mm	Red		FHV7X-M063R-S12-R
		(autofocus)	12 11111	White	FHV7X-C063R-S12-W	FHV7X-M063R-S12-W
				IR		FHV7X-M063R-S12-IR
				Multi color	FHV7X-C063R-S16-MC	FHV7X-M063R-S16-M0
			40 -	Red		FHV7X-M063R-S16-R
			16 mm	White	FHV7X-C063R-S16-W	FHV7X-M063R-S16-W
				IR		FHV7X-M063R-S16-IR
				Multi color	FHV7X-C063R-S25-MC	FHV7X-M063R-S25-M0
				Red		FHV7X-M063R-S25-R
			25 mm	White	FHV7X-C063R-S25-W	FHV7X-M063R-S25-W
			1			

\* For the focal length and horizontal field of view, refer to specifications (P.33) and optical charts of the lens module (P.52)

#### **Optical Filters**

tem				
Polarization Filter	For visible light	FHV-XPL		
Polarization Filter	For both infrared light and visible light	FHV-XPL-IR		
Diffusion Filter	FHV-XDF			

Waterproof Hoods Required to ensure IP67 protection without using a lighting module.

Item	Model
Waterproof Hood for Lens Modules	FHV-XHD-LEM
Waterproof Hood for C-mount Lens (Short) *1	FHV-XHD-S
Waterproof Hood for C-mount Lens (Long) *2	FHV-XHD-L

\*1. Can be used with the following lenses. 3Z4S-LE SV-0614V, 3Z4S-LE SV-0813V, 3Z4S-LE SV-1214V, 3Z4S-LE SV-1614V, 3Z4S-LE SV-2514V
\*2. Can be used with the following lenses. 3Z4S-LE SV-0614H, 3Z4S-LE SV-0814H, 3Z4S-LE SV-1214H, 3Z4S-LE SV-1614H, 3Z4S-LE SV-2514H, 3Z4S-LE SV-3514H, 3Z4S-LE SV-5014H

#### **FHV7 Series**

#### Cables

	Item	Cable length	Model
		2m	FHV-VDB2 2M
		3m	FHV-VDB2 3M
	I/O Cable (Bend Resistant) <b>*</b> 1	5m	FHV-VDB2 5M
		10m	FHV-VDB2 10M
1		20m	FHV-VDB2 20M
		2m	FHV-VDLB2 2M
		3m	FHV-VDLB2 3M
	I/O Cable (Bend Resistant, Right-angle) *1	5m	FHV-VDLB2 5M
		10m	FHV-VDLB2 10M
1		20m	FHV-VDLB2 20M
$\bigcirc$		5m	FHV-VDBX2 5M
~ 9	I/O Cable (Super Bend Resistant) *1	10m	FHV-VDBX2 10M
	I/O Cable (Super Bend Resistant, Right-angle) *1	5m	FHV-VDLBX2 5M
	I/O Cable (Super Bend Resistant, Right-angle) *1	10m	FHV-VDLBX2 10M
$\overline{O}$		2m	FHV-VNB2 2M
	Ethernet Cable (Bend Resistant)	3m	FHV-VNB2 3M
		5m	FHV-VNB2 5M
		10m	FHV-VNB2 10M
		20m	FHV-VNB2 20M
		2m	FHV-VNLB2 2M
		3m	FHV-VNLB2 3M
	Ethernet Cable (Bend Resistant, Right-angle)	5m	FHV-VNLB2 5M
		10m	FHV-VNLB2 10M
2		20m	FHV-VNLB2 20M
$\bigcirc$	Ethernet Cable (Super Bend resistant)	5m	FHV-VNBX2 5M
		10m	FHV-VNBX2 10M
		5m	FHV-VNLBX2 5M
	Ethernet Cable (Super Bend resistant, Right-angle)	10m	FHV-VNLBX2 10M
and a	External Light Conversion Cable for MDMC Light/ Photometric Stereo Light	0.1m	FHV-VFLX-GD

\*1. The FHV-VDB2/VDLB2/VDBX2/VDLBX2 I/O Cable cannot be connected when the smart camera data unit is used. Use the FHV-VUB2/VULB2/VULB2/VULBX2 Smart Camera Data Unit Cable.

#### Smart Camera Data Unit

Item	Model
Paralle linterface	FHV-SDU10
EtherCAT interface	FHV-SDU30

#### **Smart Camera Data Unit Cable**

	Item		Cable length	Model
			2m	FHV-VUB2 2M
		-	3m	FHV-VUB2 3M
	Smart Camera data unit cable(	3end resistant) <b>*</b> 1	5m	FHV-VUB2 5M
		-	10m	FHV-VUB2 10M
•		-	20m	FHV-VUB2 20M
			2m	FHV-VULB2 2M
		-	3m	FHV-VULB2 3M
	Smart Camera data unit cable(	3end resistant, Right-angle) <b>≭</b> 1	5m	FHV-VULB2 5M
		-	10m	FHV-VULB2 10M
		-	20m	FHV-VULB2 20M
	Smart Comora data unit cable//	Survey Dand resistant) 44	5m	FHV-VUBX2 5M
	Smart Camera data unit cable(Super Bend resistant) *1			FHV-VUBX2 10M
	Smart Camera data unit cable(S	Super Bend resistant, Right-angle)	5m	FHV-VULBX2 5M
	*1		10m	FHV-VULBX2 10M
			2m	XW2Z-S013-2
7	Parallel I/O Cable	-	5m	XW2Z-S013-5
~			0.5m	XW2Z-050EE
		-	1m	XW2Z-100EE
	Parallel I/O Cable for Connecto		1.5m	XW2Z-150EE
	Connector-Terminal Block Conv (Terminal Blocks Recommende	version Units can be connected d Products: OMRON XW2R-[]34G-T)	2m	XW2Z-200EE
•			3m	XW2Z-300EE
		-	5m	XW2Z-500EE
~	Connector-Terminal Block	Phillips screw		XW2R-J34GD-T
ADDING TO A	Conversion Units, General-	Slotted screw (rise up)		XW2R-E34GD-T
and the	purpose devices *2	Push-in spring		XW2R-P34GD-T

\*1. The FHV-VDB2/VDLB2/VDBX2/VDLBX2 I/O Cable cannot be connected when this cable is used.

**\*2.** Refer to the XW2R datasheet for details.

#### **FHV7 Series**

#### Accessories

	Item		Model
	Base Mount for Smart Cameras and Light	Base Mount for Smart Cameras and Lighting Controllers	
	Base Mount for Lighting Controllers		FHV-XMT-7-TCC
	Light Cover (for replacement) <b>*</b> 1		FHV-XCV
0	Weterproof Cap (for replacement)	Vaterproof Cap (for replacement) for Light Connecter	
		for Camera	FHV-XWP-CAM
$\bigcirc$	Waterproof Packing <b>*</b> 2 (for replacement, 5 pcs)	for Lighting Module	FHV-XWP-LTM
$\bigcirc$		for Waterproof Hood	FHV-XWP-HD-SL
	Light-shielding for Lighting Module (for rep	placement, 3 pcs) *3	FHV-XLS-LTM
	Cover for High-speed Lens Module (for replacement, cover 1pcs, screws 5 pc	Cover for High-speed Lens Module (for replacement, cover 1pcs, screws 5 pcs (including one spare piece))	
	Cover for Standard Lens Module (for replacement, cover 1pcs, screws 5 pc	Cover for Standard Lens Module (for replacement, cover 1pcs, screws 5 pcs (including one spare piece))	
Q	Cover for C-mount Lens (for replacement, cover 1pcs, screws 5 pc	Cover for C-mount Lens (for replacement, cover 1pcs, screws 5 pcs (including one spare piece))	
	Screw for microSD card cover (for replace	ement, 10 pcs)	FHV-XSCR-MSD

\*1. Adapted lighting module FHV-LTM-W, FHV-LTM-R, FHV-LTM-IR, FHV-LTM-MC
\*2. Always replace when a module is removed.
\*3. It is considered a consumable item that will deteriorate. Please replace as needed.

#### Accessories

Item		Descriptions		Model
			LED	FLV Series
	– External Lights		High-brightness LED	FL-BR/DR Series
			Photometric Stereo Light	FL-PS Series
			MDMC Light (Built-in lighting controller)	FL-MD Series
			LED	FLV-TCC/ATC
	Lighting controller		High-brightness LED	FL-TCC/STC
				FL-TCC1PS
A CONTRACTOR	Industrial Switching Hubs for EtherNet/IP and Ethernet	5 port	Current consumption: 0.07 A	W4S1-05D

#### Lenses

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

			Recommended lens			
Resolution	Camera Model	Size of image element	Standard Lens	Telecentric Lens	Vibrations and Shocks Resistant Lens	
0.4 million-pixel	FHV7X-004	1/2.9" equivalent	SV-V Series			
1.6 million-pixel	FHV7X-016	1/2.9" equivalent	SV-V Series		VS-MCA Series Non-telecentric Macro	
3.2 million-pixel	FHV7X-032	1/1.8" equivalent		VS-TCH Series		
5 million-pixel	FHV7X-060	2/3" equivalent	SV-H Series	V3-TCH Selles	VS-MC Series	
6.3 million-pixel	FHV7X-063R	1/1.8" equivalent	SV-D Selles			
12 million-pixel	FHV7X-0120R	1/1.7" equivalent				

#### **Recommended EtherCAT Communications Cables**

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

#### **Cable with Connectors**

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6PUR8SS30CM-YF
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6PUR8SS50CM-YF
Standard RJ45 plugs type <b>*</b> 1 Wire Gauge and Number of Pairs: AWG26, 4-pair Cable		OMRON	1	XS6W-6PUR8SS100CM-YF
Cable Sheath material: PUR	*	OWRON	2	XS6W-6PUR8SS200CM-YF
Cable color: Yellow *2			3	XS6W-6PUR8SS300CM-YF
			5	XS6W-6PUR8SS500CM-YF
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45) Rugged RJ45 plugs type <b>*</b> 1 Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Light blue	-	OMRON	0.5	XS5W-T421-BMD-K
			1	XS5W-T421-CMD-K
			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
		OMRON	0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable <b>*</b> 3			2	XS5W-T421-DM2-SS
M12/Smartclick Connectors Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			3	XS5W-T421-EM2-SS
Cable color: Black			5	XS5W-T421-GM2-SS
			10	XS5W-T421-JM2-SS
			0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *3			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	23	OMRON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type		UNICON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

\*1. Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the Industrial Ethernet Connectors Catalog (Cat. No. G019).

**\*2.** Cables colors are available in yellow, green, and blue. **\*3.** For details, contact your OMRON representative.

#### **Cables / Connectors**

It	em	Recommended manufacturer	Model
Products for EtherCAT	Cable	Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 x 4P CP *1
(1000BASE-T/100BASE-TX) Wire gauge and number of pairs:	Cable	Kuramo Electric Co.	KETH-SB *1
AWG24, 4-pair cable	RJ45 Connector	Panduit Corporation	MPS588-C <b>*1</b>
	Cable	Kuramo Electric Co.	KETH-PSB-OMR <b>*2</b>
Products for EtherCAT	Cable	JMACS Japan Co., Ltd.	PNET/B <b>*2</b>
(100BASE-TX/10BASE-T) Wire gauge and number of pairs: AWG22, 2-pair cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 <b>*2</b>

**\*1.** We recommend you to use the above Cable and RJ45 Connector together.

\*2. We recommend you to use the above Cable and RJ45 Assembly Connector together.

#### **Touch Panel Monitor**

#### **Omron Model**

	Item	Screen size	Frame color	Model
		15.4 inch	Black	NYE2A-20F11-15WR1200
A REAL PROPERTY.	Touch Panel Monitor for FHV7 Smart Camera series	15.4 inch	Silver *	NYE2A-20F11-15WR1300
	Touch Panel Monitor for FHV7 Smart Camera series	12.1 inch	Black	NYE2A-20F11-12WR1200
		12.1 inch	Silver *	NYE2A-20F11-12WR1300
	Llick Drocours Waterstoof Attackment (DMA)	15.4 inch	-	NA-15WATW01
	High-Pressure Waterproof Attachment (PWA)	12.1 inch	-	NA-12WATW01
	Anti-reflection Sheets	15.4 inch	-	NA-15WKBA04
		12.1 inch	_	NA-12WKBA04

\* The silver color is a European area limited model.

#### Advantech Model

Ask Advantech about the warranty period and coverage of this product.

	Item	Model	Recommended manufacturer
	Touch Panel Monitor	PPC-310-OMR	
	ARM VESA Standard (A-CLEVER) for PPC Series	PPC-ARM-A03	
	Wall mount kit for PPC Series	PPC-174T-WL-MTE	
	Stand for PPC Series	PPC-Stand-A1E	Find your local office on the Advantech
	ADP A/D 100-240V 90W 19V W/PFC	96PSA-A90W19OT-3	website https://www.advantech.com/contact/
	Power cord 3P UL 10 A 125 V 1.8 m	1700001524	offices/
	Power cord 3P Europe (WS-010+083) 1.83 m	170203183C	
	Power cord 3P/3P PSE 1.8 m	1700008921-11	
	Power cord 3P CCC (China) 1.8 m	96CB-POWER-B-1.8M	

Automation Software Sysmac Studio The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI.

For details, refer to your local OMRON website and Sysmac Studio Catalog (Cat. No. P138).

#### **Ratings and Specifications**

#### Smart Camera

ltem		Model	FHV7X- M004-C	FHV7X- C004-C	FHV7X- M016-C	FHV7X- C016-C	FHV7X- M032-C	FHV7X- C032-C	FHV7X- M050-C	FHV7X- C050-C	FHV7X- M063R-C	FHV7X- C063R-C	FHV7X- M120R-C	FHV7X- C120R-C
		Standard	Yes											1
	Operation Mode	Double speed multi-input	Yes											
	Wode	Non-stop adjustment mode	Yes	Yes										
	Parallel pr	ocessing	Yes											
Specifica	Possible N		256		64		36		25		19		10	
tions	captured in Possible N logging im Smart Can	o. of ages to	645		161		79		50		39		19	
		o. of scenes	128 *1											
	UI operatio	on	Remote (	Operation <sup>-</sup>	Гооі									
	Setup			e processi		ng Flow e	diting.							
	Language		Japanese	e, English,	Simplified	Chinese, T	raditional	Chinese, G	erman, Fre	ench, Italia	n, Spanish	, Korean, \	/ietnamese	e, Polish
	CMOS Ima	ge elements	1/2.9-incl equivaler		1/2.9-inclean equivaler		1/1.8-incl equivaler		2/3-inch e	equivalent	1/1.8-incl equivaler		1/1.7-incl equivaler	
	Color/Mon		Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color	Monoch rome	Color
	Pixel size	ixels (H x V)	720 × 54		1440 × 1		2048 × 1		2448 × 2		3072 × 2		4000 × 3	
	Imaging ar		6.9 × 6.9	μm	3.45 × 3.	45 µm	3.45 × 3.4	45 µm	3.45 × 3.4	45 µm	2.4 × 2.4	μm	1.85 × 1.	35 µm
	(opposing	corner)								7.4 × 5.0 (8.9 mm) 7.4 × 5.6 (9.3 mm Rolling shutter		(9.3 mm)		
	Shutter sy	stem	Global Si	Global Shutter (Global reset mode compatible)								*)		
Imaging Sh	Shutter function		Electronic	Electronic shutter: Shutter speed can be set from 1 $\mu s$ to 100 ms.					Electronic shutter:Electronic shutterShutter speed can be set from 55 µs to 100 ms.Shutter speed a be set from 84 to 100 ms.		peed can om 84 µs			
	Partial function		4 to 540 l (4-line ind	lines crements)	4 to 1080 (4-line in	) lines crements)	4 to 1536 (4-line inc	i lines crements)	4 to 2048 (4-line ind		4 to 2048 (4-line inc	lines crements)	4 to 3000 (4-line inc	) lines crements)
	Frame rate (image acquisition time)		430 fps (2	2.3 ms)	224 fps (	4.5 ms)	55 fps (1	8.0 ms)	35 fps (28	3.0 ms)	59 fps (1	6.7 ms)	19 fps (2	5.0 ms)
	Lens mou		C mount											
	Field of vie Installation		Selecting	a lens aco	cording to t	he field of	view and ir	stallation o	distance					
	Serial		RS-232C	× 1										
	Ethernet		I/F: 1000	Non-proce BASE-T ×	1	P/UDP)								
	EtherNet/II		Yes (Target/Ethernet port) Yes (Slave/Ethernet port), Conformance class A											
	PROFINET													
	EtherCAT Parallel I/C	<u> </u>		<sup>o</sup> common	Camera D	ala Unil Fr	IV-SDU30	only suppo	ons.)					
External	Faraner //C	Input signals	4 signals • STEP											
Interface	Parallel I/O	Output signals	5 signals • ERROR (ON when there is an error) • OR (Overall Judgement Result) • BUSY (Processing in progress) • READY (ON when Image input is allowed) • STGOUT/SHTOUT (Strobe trigger signal/Shutter output signal)											
	Encoder I/	F	Yes (Sma	Yes (Smart Camera Data Unit FHV-SDU10 only supports.)										
	Monitor I/F	:	N/A											
	USB I/F		N/A											
	SD Card I/	F	microSD	card: SDH	C × 1									
Indicator L	amne	Main	PWR: Gr	een, RUN:	Green, LII	NK: Yellow	, BUSY: G	reen, OR: `	Yellow, ER	R: Red				
	Lamps	SD	SD ACCE	ESS: Yello	N									
Supply Vo	ltage		21.6 VDC	C to 26.4 V	DC (When	an I/O cat	le with 20	m is conne	ected, it is 2	24.0 VDC t	o 26.4 VD	C.)		
Current Co	onsumption			ing module										
		enes can be					oraion on		n data tar					

**\*1.** The number of scenes can be increased up to 1,024 with the Conversion scene group data tool.

#### **FHV7 Series**

Item	Model	FHV7X- M004-C	FHV7X- C004-C	FHV7X- M016-C	FHV7X- C016-C	FHV7X- M032-C	FHV7X- C032-C	FHV7X- M050-C	FHV7X- C050-C	FHV7X- M063R-C	FHV7X- C063R-C	FHV7X- M120R-C	FHV7X- C120R-C
	Ambient temperature range	Operating	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)										
	Ambient humidity range	Operating	g & Storag	e: 35 to 85	%RH (With	no conde	nsation)						
	Ambient atmosphere	No corros	sive gases										
Usage	Vibration tolerance	Sweep tir	ne: 8 minu	te/count, S	i0Hz, Half a Sweep cour HV-LEM-S	nt: 10 time	s ,			Y/Z, same as a	bove.)		
Environ ment	Shock resistance	Impact fo	rce: 150 m	/s², Test d	irection: 6	directions,	three time	each (up/c	lown, front	/behind, lef	ft/right)		
	Noise immunity       Fast transient burst         • DC power       Direct infusion: 2kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 3         Application time: 1 min.       • I/O line         Direct infusion: 1kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 3         Application time: 1 min.         • I/O line         Direct infusion: 1kV, Pulse rising: 5 ns, Pulse width: 50 ns, Burst continuation time: 15 ms/0.75 ms, Period: 3							,					
	Grounding	Class D g	grounding (	100 Ω or l	ess ground	ling resista	nce) <b>*</b> 2						
	Dimensions	110 mm :	× 68.5 mm	× 55.5 mm	n (H × W ×	D)							
	Weight	Approx. 6	670 g										
External shape	Degree of protection	(except a	ing module connector n the abov	cap remov		ls: IEC605	29 - IP67						
	Case material	Aluminun	n die-castir	ng (ADC12	2)								
Accessor	ies	Conne     C mou     C mou     Instruc     Membe	ctor cap fo nt cap (mo nt cover (n tion sheet: ership regi	r an exterr unted on t nounted or 1 stration: 1	cable (mou nal lighting he body): 1 n the body) ation and I	(mounted) I : 1	on the bod	y): 1					

\*2. Existing the third class grounding

#### **Lens Modules**

#### High-speed Lens Modules (Autofocus)

Item		FHV-LEM-H06 FHV-LEM-H19						
System	vstem Liquid lens auto focus							
Installation dista	ance	102 to 650 mm	202 to 1050 mm					
	0.4 million pixels	64 × 48 mm to 505 × 376 mm	50 × 37 mm to 266 × 200 mm					
Horizontal field	1.6 million pixels	04 × 46 mm to 505 × 576 mm	50 × 37 mm to 200 × 200 mm					
of view range 🗱	3.2 million pixels	92 × 68 mm to 731 × 539 mm	71 × 53 mm to 378 × 284 mm					
	6.3 million pixels	97 × 63 mm to 766 × 499 mm	74 × 49 mm to 394 × 264 mm					
Focal length *		6 mm	19 mm					
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)						
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)						
Usage	Ambient atmosphere	No corrosive gases						
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times						
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)						
	Dimension	50 mm × 41.1 mm × 37.1 mm (H × W × D)	50 mm × 41.1 mm × 36.3 mm (H × W × D)					
External shape	Weight	Approx. 25 g						
	Case material	Polycarbonate						
Accessories		Special cover for FHV-LEM-H: 1     Screws: M3 × 8 mm: 5 (including one spare piece)     Instruction sheet : 1     Compliance sheet: 1						

\*Refer to optical chart (P.52) for details.

#### **Standard Lens Modules (Autofocus)**

Item		FHV-LEM-S06	FHV-LEM-S09	FHV-LEM-S12	FHV-LEM-S16	FHV-LEM-S25				
System		Mechanical auto focus								
Focal length ran	ige <b>*</b> 1	59 to 1,000 mm	60 to 1,000 mm	60 to 1,000 mm	110 to 2,000 mm	188 to 2,000 mm				
	0.4 million pixels	39 × 29 to	24 × 18 to	17 × 13 to	27 × 20 to	30 × 23 to				
Horizontal field	1.6 million pixels	845 × 624 mm	543 × 407 mm	407 × 305 mm	614 × 461 mm	391 × 293 mm				
of view range	3.2 million pixels	57 × 42 to 1,234 × 905 mm	34 × 25 to 772 × 579 mm	24 × 18 to 579 × 434 mm	38 × 29 to 874 × 655 mm	43 × 33 to 556 × 417 mm				
	6.3 million pixels	50 × 39 to 1,293 × 836 mm	35 × 23 to 807 × 538 mm	25 × 17 to 606 × 404 mm	40 × 27 to 913 × 608 mm	45 × 30 to 581 × 387 mm				
Focal length		6 mm	9 mm	12 mm	16 mm	25 mm				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)								
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)								
Usage	Ambient atmosphere	No corrosive gases								
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.15 mm <b>*</b> 2, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times								
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)								
	Dimension	50 mm × 41 mm × 31 mm (H × W × D)								
External shape	Weight	Approx. 50 g								
	Case material	Polycarbonate								
Accessories		Special cover for FHV-LEM-S: 1     Screws: M3 × 8 mm: 5 (including one spare piece)     Instruction sheet : 1     Compliance sheet: 1								

**\*1.** Refer to optical chart (P.52) for details. **\*2.** When the lens module is mounted to the product, the vibration tolerance is applied for the specifications of the smart camera.

#### **Lighting Modules**

Model		FHV-LTM-W	FHV-LTM-R	FHV-LTM-IR	FHV-LTM-MC				
Color		White	Red	Infrared light	Multi color				
Peak wave len	gth	-	Typ. 630 nm	Typ. 850 nm	R: Typ. 630 nm G: Typ. 525 nm B: Typ. 465 nm IR: Typ. 850 nm				
Light source		LED	LED	LED	LED				
Risk group		Group 2	Group 1	Group 1	R: Group 1 G: Group 2 B: Group 2 IR: Group 1				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)							
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)							
Usage	Ambient atmosphere	No corrosive gases							
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times							
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)							
Dimensions		52 mm × 91 mm × 77 mm (H × W × D)							
Weight		270 g	270 g	270 g	270 g				
Material		Aluminum die-casting (AD	C12), polycarbonate						
Accessories		Waterproof packing (small) FHV-XWP-CAM:1     Waterproof packing (large) FHV-XWP-LTM: 1     Light shielding sheet FHV-XLS-LTM: 1     Lighting cover FHV-XCV: 1     Hexagonal wrench (length: 60 mm): 1     Instruction sheet: 1     Compliance sheet: 1							

#### **Optical Filters**

Model		FHV-XDF	FHV-XPL	FHV-XPL-IR				
Filter type Diffusion filter Polarization filter Polarization filter								
Wavelength		Visible to infrared	Visible	Visible to infrared				
Adapted lightir	ng module	FHV-LTM-W FHV-LTM-R FHV-LTM-IR FHV-LTM-MC	FHV-LTM-W FHV-LTM-R FHV-LTM-MC (Infrared light is not used.)	FHV-LTM-W FHV-LTM-R FHV-LTM-IR FHV-LTM-MC				
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)						
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)						
Usage	Vibration tolerance	No corrosive gases						
environment	Shock resistance	Oscillation frequency: 10 to 150Hz, H Sweep time: 8 minute/count, Sweep	lalf amplitude: 0.35 mm, Vibration dire count: 10 times	ection: X/Y/Z,				
	Vibration tolerance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)						
Material	· ·	Aluminum (A6061), polycarbonate						
Weight		Approx. 70 g	Approx. 70 g	Approx. 70 g				

#### Waterproof Hoods

Model		FHV-XHD-S	FHV-XHD-L	FHV-XHD-LEM			
Suitable lens		3Z4S-LE SV-V series SV-0614V SV-0813V SV-1214V SV-1614V SV-2514V	3Z4S-LE SV-H series SV-0614H *1 SV-0814H *2 SV-1214H SV-1614H SV-2514H SV-3514H SV-3514H SV-5014H	FHV-LEM-S series FHV-LEM-S06 FHV-LEM-S09 FHV-LEM-S12 FHV-LEM-S16 FHV-LEM-S25 FHV-LEM-H series FHV-LEM-H06 FHV-LEM-H09			
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 35 to 85%RH (With no condensation)					
Usage	Ambient atmosphere	No corrosive gases					
environment	Vibration tolerance	Oscillation frequency: 10 to 150Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times					
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)					
Material		Aluminum (A6061), polycarbonate					
Weight		Approx. 220 g	Approx. 220 g	Approx. 220 g			
*1 This is not	available in EHV7X-D050 EH		·	·			

**\*1.** This is not available in FHV7X-□050, FHV7X-□063R, FHV7X-□120R. **\*2.** This is not available in FHV7X-□050.

## Smart Camera Data Unit

Item		Parallel interface	EtherCAT interface			
Model		FHV-SDU10	FHV-SDU30			
Input/output specifications	Parallel I/O	Input: 12 Output: 24 (NPN/PNP combined use)	Input: 1 Output: 2 (NPN/PNP combined use)			
	Encoder I/F	Yes (Included in Parallel Input)	None			
	EtherCAT communications	None	Yes (slave)			
Smart Camera Interface		Special cable to connect No. of connectable cameras: 1				
	Main	POWER: Green, ERROR: Red, RUN: Gree	n, BUSY: Green, CAMERA: Yellow, OR: Yellow			
Indicator	EtherCAT	None	ECAT RUN: Green, LINK/ACT IN: Green, LINK/ACT OUT: Green, ECAT ERROR: Red			
Power supply voltage		21.6 to 26.4 VDC (Note: 24.0 to 26.4 VDC when a data unit c	able with 20 m is connected.)			
Insulation resistance		Between DC terminal block and FG termina	al: 0.5 MΩ (250V Megger)			
Current consumption		4.5 A or less				
	Ambient temperature range	Operating: 0 to +50°C, Storage: -25 to +65°C (with no icing or condensation)				
	Ambient humidity range	Operating and storage: 35 to 85%RH (with no condensation)				
	Ambient atmosphere	No corrosive gases				
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.1 mm, Vibration direction: X/Y/Z, Sweep time: 8 minutes, Sweep count: 10 times				
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, Three times each (up/down, front/beh left/right)				
Usage environment	Noise immunity	<ul> <li>I/O line Coupling clamp: 1 kV, Pulse rising: 5 ns,</li> </ul>	, Period: 300 ms, Application time: 1 minute			
	Grounding	Class D grounding (100 Ω or less grounding resistance) * Existing the third class grounding				
	Dimensions	H (90 mm) × W (93 mm) × D (65 mm)	H (90 mm) × W (124 mm) × D (65 mm)			
-	Weight	Approx. 250 g	Approx. 325 g			
External shape	Degree of protection	IEC60529 - IP20				
	Case material	PC+ABS, PC				
Accessories		Instruction sheet: 1     Compliance sheet: 1				

## I/O cables Bending Resistance Cables

Item		FHV- VDB2 2M	FHV- VDLB2 2M	FHV- VDB2 3M	FHV- VDLB2 3M	FHV- VDB2 5M	FHV- VDLB2 5M	FHV- VDB2 10M	FHV- VDLB2 10M	FHV- VDB2 20M	FHV- VDLB2 20M
Cable length		2 m 3 m 5 m 10 m 20 m									
Connector typ	De								Right angle connector		
Cable type		Bending res	sistance cabl	e		L	r.	L	I.	r.	
Ci-c	Power line	AWG21									
Size	Others	AWG26									
Outer diamete	er	8.8±0.3 mm	ı dia.								
Min. bending	radius	Fixed use: 4	40 mm, Slidir	ng use: 70 m	m						
	Input signals	4 signals: S	TEP, DI 0 to	2							
Input/Output signals	Output signals	5 signals: ERROR, OR, BUSY, READY, STGOUT/SHTOUT									
Signals	RS-232C	2 signals: T	ransmission	data, Recep	tion data						
	Ambient temperature range	Operating: ·	-10 to +70°C	, Storage: -2	5 to +85°C (v	vith no icing o	or condensat	ion)			
	Ambient humidity range	Operating 8	& Storage: 0 t	to 93%RH (V	Vith no conde	ensation)					
Usage environment	Ambient atmosphere	No corrosiv	e gases								
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times							ount,		
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material	·	Mold part: N	ylon, PVC, S	Sheath part:	PVC						
Weight		Approx. 250	) g	Approx. 37	Эg	Approx. 590	) g	Approx. 1,1	70 g	Approx. 2,3	10 g

## Super Bending Resistance Cables

ltem		FHV-VDBX2 5M	FHV-VDLBX2 5M	FHV-VDBX2 10M	FHV-VDLBX2 10M				
Cable length		5 m		10 m					
Connector ty	ector type Straight connector Right angle connector Straight connector Right angle								
Cable type		Super bending resistance cab	le						
0:	Power line	AWG19							
Size	Others	AWG26							
Outer diamet	er	7.2+0.7 mm dia.							
Min. bending	radius	44 mm							
Input/Output	Input signals	1 signal: STEP	1 signal: STEP						
signals	Output signals	3 signals: OR, READY, STGOUT/SHTOUT							
	Ambient temperature range	Operating: -10 to +70°C, Stora	age: -25 to +85°C (with no icing	or condensation)					
	Ambient humidity range	Operating & Storage: 0 to 93%	6RH (With no condensation)						
Usage environment	Ambient atmosphere	No corrosive gases							
	Vibration tolerance Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/ Sweep count: 10 times								
	Shock resistance Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)								
Material	·	Mold part: Nylon, PVC, Sheath	h part: PVC						
Weight		Approx. 420 g Approx. 790 g							

## Ethernet Cables Bending Resistance Cables

Item		FHV- VNB2 2M								FHV- VNLB2 20M	
Cable length		2 m	2 m 3 m 5 m 10 m 20 m								
Connector typ	pe	Straight connector								Rightangle connector	
Cable type		Bending res	Bending resistance cable								
Outer diameter	ər	6.7±0.3 mm	ı dia.								
Min. bending	radius	Fixed use: 3	Fixed use: 35 mm, Sliding use: 50 mm								
	Ambient temperature range	Operating: -	-10 to +70°C	, Storage: -2	5 to +85°C (v	vith no icing o	or condensat	ion)			
	Ambient humidity range	Operating 8	Storage: 01	to 93%RH (V	/ith no conde	ensation)					
Usage environment	Ambient atmosphere	No corrosiv	e gases								
	Vibration tolerance		Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times							ount,	
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material	·	Mold part: PVC, Sheath part: PVC									
Weight	Approx. 140 g         Approx. 200 g         Approx. 310 g         Approx. 590 g         Approx. 1,150 g						50 g				

## Super Bending Resistance Cables

Item		FHV-VNBX2 5M	FHV-VNLBX2 5M	FHV-VNBX2 10M	FHV-VNLBX2 10M		
Cable length		10 m					
Connector typ	pe	Straight connector	Straight connector Right angle connector Straight connector				
Cable type Super bending resistance cable							
Outer diamete	er	6.6+0.7 mm dia.					
Min. bending	radius	40 mm					
	Ambient temperature range	Operating: -10 to +70°C, Storage: -25 to +85°C (with no icing or condensation)					
	Ambient humidity range	Operating & Storage: 0 to 93%	RH (With no condensation)				
Usage environment	Ambient atmosphere	No corrosive gases					
	Vibration tolerance	Oscillation frequency: 10 to 15 Sweep count: 10 times	0 Hz, Half amplitude: 0.35 mm,	Vibration direction: X/Y/Z, Swe	ep time: 8 minute/count,		
	Shock resistance	stance Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)					
Material	·	Mold part: PVC, Sheath part: PVC					
Weight Approx. 390 g Approx. 730 g							

## External Light Junction Cables for MDMC Light

Item		FHV-VFLX-GD			
Cable length		0.1 m			
Outer diameter	er	4.0±0.1 mm dia.			
Min. bending	radius	15 mm			
	Ambient temperature range	Operating: 0 to +40°C, Storage: -25 to +65°C (with no icing or condensation)			
	Ambient humidity range	Operating & Storage: 0 to 93%RH (With no condensation)			
Usage environment	Ambient atmosphere	No corrosive gases			
	Vibration tolerance	Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/count, Sweep count: 10 times			
Shock resistance		Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)			
Material Shell par		Shell part: Zinc alloy and Brass, Sheath part: Heat-resistant oilproof polyvinyl chloride			
Weight		Approx. 30 g			

# Smart Camera Data Unit Cable

## **Bending Resistance Cables**

Item		FHV- VUB2 2M							FHV- VULB2 20M		
Cable length		2 m 3 m 5 m 10 m 20 m						20 m			
Connector typ	pe	Straight connector							Right angle connector		
Cable type		Bending re	sistance cab	le							
Outer diameter	ər	7.8±0.3 mn	n dia.								
Min. bending	radius	Fixed use:	40 mm, Slidi	ng use: 65 r	nm						
	Ambient temperature range	Operating:	-10 to +70°C	C, Storage: -	25 to +85°C	(with no icin	g or condens	sation)			
	Ambient humidity range	Operating 8	& Storage: 0	to 93%RH (	With no con	densation)					
Usage environment	Ambient atmosphere	No corrosiv	e gases								
chrinonnent	Vibration tolerance	ration tolerance Oscillation frequency: 10 to 150 Hz, Half amplitude: 0.35 mm, Vibration direction: X/Y/Z, Sweep time: 8 minute/cr Sweep count: 10 times					e/count,				
	Shock resistance	Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)									
Material Mold part: PVC, Sheath part: PVC											
Weight         Approx. 200 g         Approx. 290 g         Approx. 470 g         Approx. 900 g         Ap					Approx. 1,7	'80 g					

## Super Bending Resistance Cables

Item		FHV-VUBX2 5M	FHV-VULBX2 5M	FHV-VUBX2 10M	FHV-VULBX2 10M			
Cable length	ble length 5 m 10 m							
Connector typ	pe	Straight connector	Straight connector Right angle connector Straight connector					
Cable type		Super bending resistance cable						
Outer diamete	er	7.5+0.6 mm dia.						
Min. bending	radius	47 mm	47 mm					
	Ambient temperature range	Operating: -10 to +70°C, Sto	rage: -25 to +85°C (with no icir	ng or condensation)				
	Ambient humidity range	Operating & Storage: 0 to 93	%RH (With no condensation)					
Usage environment	Ambient atmosphere	No corrosive gases						
	Vibration tolerance	Oscillation frequency: 10 to 1 Sweep count: 10 times	50 Hz, Half amplitude: 0.35 m	m, Vibration direction: X/Y/Z,	Sweep time: 8 minute/count,			
	Shock resistance	sistance Impact force: 150 m/s <sup>2</sup> , Test direction: 6 directions, three time each (up/down, front/behind, left/right)						
Material	·	Mold part: PVC, Sheath part: PVC						
Weight	Approx. 920 g							

# Touch panel monitor

## OMRON Model

Display device Screen size Resolution	TFT LCD							
	45 Alizabaa							
Decelution	15.4 inches 12.1 inches							
resolution	1,280 × 800		·					
Backlight Life	50,000 hours min.							
Fouch panel	Analog resistive membrai	ne type						
Ethernet ports	10/100/1000Mbps Ethern	et × 2						
JSB ports	USB 2.0 × 2, USB 3.0 × 1							
Serial port	RS-232C × 1							
CFast Card slot	1							
Allowable power supply /oltage range	19.2 to 28.8 VDC (24 VDC ±20%)							
Power consumption	60 W							
Ambient temperature	Operating: 0 to +50°C Storage: -20 to +60°C (with no icing or condense	ation)						
Ambient humidity	10 to 90% (With no condensation)							
/ibration resistance (during operation)	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with 3.5 mm half amplitude and 8.4 to 150 Hz with 9.8 m/s <sup>2</sup> for 100 minutes each in X,Y, and Z directions							
Shock resistance (during operation)								
	Black	Silver *	Black	Silver *				
	420 × 291 × 69 mm		340 × 244 × 69 mm					
	Approx. 3.2 kg Approx. 2.4 kg							
	IP65		·					
	Panel mount, VESA mount							
	Instruction sheet, Power and IO connector, Mounting Clamps							
	thernet ports ISB ports Serial port Fast Card slot Ulowable power supply oltage range Power consumption Combinent temperature Combinent humidity Vibration resistance (during peration) Schock resistance (during	ithernet ports       10/100/1000Mbps Ethern         ISB ports       USB 2.0 × 2, USB 3.0 × 1         iserial port       RS-232C × 1         Fast Card slot       1         illowable power supply oltage range       19.2 to 28.8 VDC (24 VD)         iower consumption       60 W         wmbient temperature       Operating: 0 to +50°C Storage: -20 to +60°C (with no icing or condensation)         ibration resistance (during peration)       Conforms to IEC 60068-2 5 to 8.4 Hz with 3.5 mm h Z directions         ibrock resistance (during peration)       Conforms to IEC 60028-2 147 m/s² 3 times each in         Black       420 × 291 × 69 mm         Approx. 3.2 kg       IP65         Panel mount, VESA mount Instruction sheet, Power at	ithernet ports       10/100/1000Mbps Ethernet × 2         ISB ports       USB 2.0 × 2, USB 3.0 × 1         iserial port       RS-232C × 1         Fast Card slot       1         illowable power supply oltage range       19.2 to 28.8 VDC (24 VDC ±20%)         iower consumption       60 W         wmbient temperature       Operating: 0 to +50°C Storage: -20 to +60°C (with no icing or condensation)         inbient humidity       10 to 90% (With no condensation)         ibration resistance (during peration)       Conforms to IEC 60068-2-6. 5 to 8.4 Hz with 3.5 mm half amplitude and 8.4 to 15 Z directions         ibrock resistance (during peration)       Conforms to IEC 60028-2-27. 147 m/s² 3 times each in X, Y, and Z directions         Black       Silver *         420 × 291 × 69 mm       Approx. 3.2 kg         IP65       Panel mount, VESA mount         Instruction sheet, Power and IO connector, Mountir	ithernet ports       10/100/1000Mbps Ethernet × 2         ISB ports       USB 2.0 × 2, USB 3.0 × 1         ierial port       RS-232C × 1         :Fast Card slot       1         .llowable power supply oltage range       19.2 to 28.8 VDC (24 VDC ±20%)         rower consumption       60 W         Operating: 0 to +50°C Storage: -20 to +60°C (with no icing or condensation)         umbient temperature       Operating: 0 to +50°C Storage: -20 to +60°C (with no condensation)         umbient numidity       10 to 90% (With no condensation)         Conforms to IEC 60068-2-6. 5 to 8.4 Hz with 3.5 mm half amplitude and 8.4 to 150 Hz with 9.8 m/s² for 100 Z directions         ibock resistance (during peration)       Conforms to IEC 60028-2-27. 147 m/s² 3 times each in X, Y, and Z directions         Black       Silver *       Black         420 × 291 × 69 mm       340 × 244 × 69 mm         Approx. 3.2 kg       Approx. 2.4 kg         IP65       Panel mount, VESA mount         Instruction sheet, Power and IO connector, Mounting Clamps				

\*The silver color is a European area limited model.

#### Advantech Model

	Model	PPC-310-OMR
	Display Type	10.4" TFT LCD (LED backlight)
	Resolution	1,024 × 768
LCD	Luminance	350 cd/m <sup>2</sup>
LCD	Contrast Ratio	1,000
	Backlight Lifetime	30,000 hr (min.)
	Touch Type	Capacitive
External Interface	Ethernet	10/100/1,000/2,500 Mbps Ethernet × 2
External interface	USB I/F	USB 2.0 × 2, USB 3.0 × 2, TypeC × 1
Power Consumption	Input Voltage	12 to 30 VDC
Power Consumption	Power Consumption	35 W
	Ambient Temperature Range	Operating: 0 to 50°C Storage: -20 to 60°C
	Ambient Humidity Range	10% to 95% at 40°C (With no condensation)
Environment	Vibration	Operating Random Vibration Test 5 to 500 Hz, 2 Grms, follow IEC 60068-2-64
	Shock	Operating 10 G peak acceleration (11 ms duration), follow IEC 60068-2-27
	EMC	CE, FCC Class B, BSMI, UKCA, VCCI
	Safety	CB, CCC, UL, UKCA
Dimensions		272 × 217 × 50 mm
Weight		3.1 kg
Front Panel Protectio	n	IP66 compliant
Mounting		Panel mount, VESA mount, Wall mount
Accessories		Instruction sheet, Connector for power supply, Mounting screws and brackets for panel mount

# FHV7 Series EtherCAT Communications Specifications

Item		Specifications					
Communications standard		IEC61158 Type 12					
Physical layer		100 BASE-TX (IEEE802.3)					
Modulation		Base band					
Baud rate		100 Mbps					
Topology		Depends on the specifications of the EtherCAT master.					
Transmission Media		wisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)					
Transmission Distance		Distance between nodes: 100 m or less					
Node address setting		00 to 99					
External connection terminals	5	$RJ45 \times 2$ (shielded) IN: EtherCAT input data, OUT: EtherCAT output data					
Sand/reasive DDO date sizes	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *					
Send/receive PDO data sizes	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *					
Mailbox data size	Input	512 bytes					
Malibox data size Output		512 bytes					
Mailbox		Emergency messages, SDO requests, and SDO information					
Refreshing methods		I/O-synchronized refreshing (DC)					

\* This depends on the upper limit of the master.

# **Version Information**

## FHV7 Series and Programming Devices

Use the latest version of Sysmac Studio Standard Edition/Vision Edition.

Version of FHV7 Series	Corresponding version of Sysmac Studio Standard Edition/Vision Edition				
Version 6.55/6.60	Supported by version 1.59 <b>*</b> or higher.				
Version 6.51 or higher	Supported by version 1.53 or higher.				
Version 6.41 or higher	Supported by version 1.44 or higher.				
Version 6.30 or higher	Supported by version 1.29 or higher.				

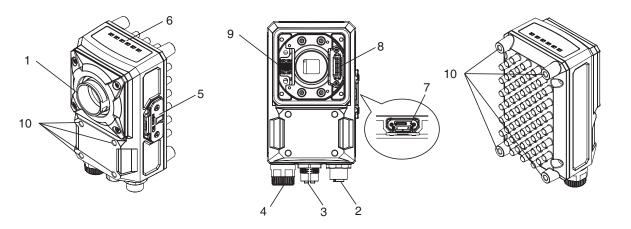
\* Sysmac Studio Version 1.59 will be supported soon.

# **Recommended Operational Environment for Remote Operation Tool**

Name	Description	
CPU	Intel Pentium Processor (SSE2 or higher)	
os	<ul> <li>Windows 7 Professional (32/64-bit) or Enterprise (32/64-bit) or Ultimate (32/64-bit)</li> <li>Windows 10 Pro (32/64-bit) or Enterprise (32/64-bit)</li> <li>Windows 11 Pro (64bit) or Enterprise (64bit)</li> </ul>	
Memory	2GB (3GB or more recommended)	
Hard disk space	2GB or more	
Display	Resolution: 1280 x 1240 dots or more Color: True Color (32-bit)	
Network	10BASE-T (100BASE-TX recommended)	

Using the FH/FHV Launcher requires Microsoft .NET Framework 3.5 installed.

# Parts and Names



No.	Name		Description			
1	Imaging unit		Captures images.			
2	Connector for I/O cab cable	le/Smart camera data unit	Use this connector when connecting the smart camera with its power supply or an external device using an I/O cable. Moreover, use this when connecting the smart camera with its data unit using its data unit cable. Dedicated I/O cable: FHV-VD Dedicated smart camera data unit cable: FHV-VU			
3	Connector for Etherne	et cable	Use this connector when connecting the smart camera with a personal compute and so on using an Ethernet cable. Dedicated Ethernet cable: FHV-VN			
4	Connector for external lighting		Use this connector when connecting an external lighting and the external lighting controller. Connectable external lighting controller: FL-TCC and FLV-TCC Connectable external light: FL-MD MC			
5	Connector to attach microSD card		Use this connector to attach a microSD card. Do not extract/insert the microSD card during processing. Otherwise, measurement time may be influenced or data may be broken.			
		PWR (Green)	Lights while power is supplied.			
		RUN (Green)	Lights when switching to the layout in which the RUN signal output is set ON.			
6		LINK (Yellow)	Lights when connected with Ethernet equipment and blinks during communication.			
	Operation indicator	BUSY (Green)	Lights while processing is in progress.			
		OR (Yellow)	Lights when the overall judgment output signal is ON.			
		ERR (Red)	Lights when an error occurs.			
7		SD ACCESS (Yellow)	Lights when accessing to the microSD card.			
8	Connector for lighting module (White)		Use this connector when mounting the lighting module.			
9	Connector for lens me	odule (Black)	Use this connector when mounting the lens module.			
10	Mounting screw holes	;	Recommended tightening torque: 2.3N·m			

# **Processing Items**

Group	lcon		Processing Item	Group	lcon		Processing Item		
	-	Search	Used to identify the shapes and calculate the position of measurement objects.			Scan Edge Position	Measure peak/bottom edge position of workpieces ac- cording to the color change in separated measurement area.		
	å	Search II	Even if the Search processing item cannot detect a model, the Search II can stably detect it by creating the optimal model according to the size and rotation of the measurement object.		₽	Scan Edge Width	Measure max/min/average width of workpieces ac- cording to the color change in separated measure- ment area.		
		Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.		Q	Circular Scan Edge Position	Measure center axis, diameter and radius of circular workpieces.		
	***	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.	Measurement	Q	Circular Scan Edge Width	Measure center axis, width and thickness of ring work- pieces.		
Measurement	, m	Shape Search III	Robust detection of positions is possible at high-speed and with high precision incorporating environmental fluctuations, such as differences in individual shapes of the workpieces, pose fluctuations, noise superimpo- sition and shielding.			Intersection	Calculate approximate lines from the edge information on two sides of a square workpiece to measure the an- gle formed at the intersection of the two lines.		
					&	Color Data	Used for detecting presence and mixed varieties of products by using color average and deviation.		
	8	Classification	Used when various kinds of products on the assembly line need to be sorted and identified.			Gravity and Area	Used to measure area, center of gravity of workpices by extracting the color to be measured.		
	-	Edge Position	Measure position of measurement objects according to the color change in measurement area.			Labeling	Used to measure number, area and gravity of work- pieces by extracting registered color.		
·			Detect edges by color change in measurement area. Used for calculating number of pins of IC and connectors.		×	Precise Defect	Check the defect on the object. Parameters for ex- traction defect can be set precisely.		

Group	lcon		Processing Item
		Fine Matching	Difference can be detected by overlapping and compar- ing (matching) registered fine images with input images.
	ABC	Character Inspect	Recognize character according correlation search with model image registered in [Model Dictionary].
_	Date 08-02-1	Date Verification	Reading character string is verified with internal date.
	A	Model Dictionary	Register character pattern as dictionary. The pattern is used in [Character Inspection].
/leasurement		2DCode II *1	Recognize 2D code and display where the code qual- ity is poor.
neasurement -		2DCode *2	Recognize 2D code and display where the code qual- ity is poor.
		Barcode *3	Recognize barcode, verify and output decoded char- acters.
_	OCR	OCR	Recognize and read characters in images as charac- ter information.
_	OCR	OCR User Dictionary	Register dictionary data to use for OCR.
		Glue Bead Inspection	You can inspect coating of a specified color for gaps or runoffs along the coating path.
_	De	Camera Image Input FHV	To input images from cameras. And set up the condi- tions to input images from cameras. (For FHV only)
_	-	Camera Image Input HDR	Create high-dynamic range images by acquiring sev- eral images with different conditions.
	<b>1</b>	Photometric Stereo Image Input	Capture images under different illumination directions using a photometric stereo light.
nput Image		Measurement Image Switching	To switch the images used for measurement. Not input images from camera again.
-	비행 비행 비행 비행	Multi-trigger Imaging	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert the Multi- trigger Imaging to the top of the flow.
	년 1월 1월	Multi-trigger Imaging Task	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert this pro- cessing item to the top of the processing which re- quires imaging for multiple times.
	5	Position Compensation	Used when positions are differed. Correct measurement is performed by correcting position of input images.
	M	Filtering	Used for processing images input from cameras in or- der to make them easier to be measured.
		Background Suppression	To enhance contrast of images by extracting color in specified brightness.
	-	Brightness Correct Filter	Track brightness change of entire screen and remove gradual brightness change such as uneven brightness.
-		Color Gray Filter	Color image is converted into monochrome images to emphasize specific color.
		Extract Color Filter	Convert color image to color extracted image or binary image.
Compensate mage		Anti Color Shading	To remove the irregular color/pattern by uniformizing max.2 specified colors.
		Stripes Removal Filter II	Remove the background pattern of vertical, horizontal and diagonal stripes.
		Polar Transformation	Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.
		Trapezoidal Correction	Rectify the trapezoidal deformed image.
-	-	Image Subtraction	The registered model image and measurement image are compared and only the different pixels are extract- ed and converted to an image.
-		Advanced filter	Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.
		Calculation	Used when using the judge results and measured values of Procltem which are registered in processing units.
	*	Line Regression	Used for calculating regression line from plural mea- surement coodinate.
-	Ŏ	Circle Regression	Used for calculating regression circle from plural mea- surement coordinate.
F	<b>G</b>	Precise Calibration	Used for calibration corresponding to trapezoidal dis- tortion and lens distortion.
Support neasurement		Trend Monitor	Used for displaying the information about results on the monitor, facilitating to avoid NG and analyze causes.
F	<b>2</b> 5	Image Logging	Used for saving the measurement images to the mem- ory and USB memory.
-	<b>∭</b> →	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.
F	<b>\$</b>	Elapsed Time	Used for calculating the elapsed time since the mea- surement trigger input.
-	X	Wait	Processing is stopped only at the set time. The stand- by time is set by the unit of [ms].

Build in the service of the	Group	lcon		Processing Item
Branelize         more tasks and processed in parallel to shoten the measurement time. This processing time is placed at the top of processing to be performed in parallel.           Branelize         Parallelize Task         Parallelize Task           Parallelize Task         Parallelize Task           Branelize         Statistics         Used when you need to calculate an average of multiple to whoten the measurement time. This processing time is placed multiple to the performed in parallelize Task           Branelize         Statistics         Used when you need to calculate an average of multiple to whoten the measurement time. Statistics           Branelize         Position Data         The specified position angle is calculated from the measurement time and the performed in parallelize to the reference.           Branelize         Vision Master         This processing time automatically calculates the entire axis movement than is required to match the measured position angle is calculated.           Branelize         Movement Multi         The axis movement that is required to match the measured position angle is calculated.           Branelize         Movement Multi         The axis movement that are required to match the measured position angle is calculated.           Branelize         Scene         The axis movement that are required to match the measured position angle is calculated.           Branelize         Scene         The axis movement that is required to match the measured position angles calculated.           Bra	0.0up			
Braneleize Task         more tasks and processed in parallel to shorten the measurement time. This processing text parallel to shorten the measurement time. This processing text parallel to shorten the measurement time. This processing text parallel to shorten the measurement time. This processing text parallel to shorten the measurement time.           Support         Statistics         Used when you need to calculate an average of multiple measurement time traults.           Support         Reference Calib         Calibration data and distortion compensation data held under other processing item scan be referenced.           Support         Position Data         Sets and stores data related to stages.           Support         This processing item automatically calculates the entre calibration.           Image:         Vision Master         This processing item automatically calculates the entre calibration.           Image:         Vision Master         The position angle is the cortrol equipment necessary for calibration is calculated.           Image:         Movement Multities and manufacter the specified axis movement is calculated.           Image:         Camera         By setting the camera calibration, the measurement is calculated.           Image:         Camera         By setting the camera calibration, the measurement is reacilvated and conditions.           Image:         Camera         By setting the camera calibration, the measurement is reacilvated according to the corresponding reference position angles to the corresponding reference position ang			Parallelize	more tasks and processed in parallel to shorten the measurement time. This processing item is placed at the top of processing to be performed in parallel.
Subsidies         ple measurement results.         -           Subsidies         Reference Calib Data         Calibration data and distribution compensation data held under other processing items can be referenced.           Subsidies         Position Data         The specified position angle is calculated from the measured positions.           Subsidies         Stage Data         Sets and stores data related to stages.           Subsidies         Robot Data         The specified position angle is calculated from the measured positions.           Subsidies         Robot Data         Sets and stores data related to robots.           Subsidies         Norment Vision Master Calibration         The processing item automatically calculates the en- tre exis movement amount of the control equipment acculated.           Subsidies         Norement Single Position         The axis movements that are required to match the mea- sured position angles to the reference position angle is calculated.           Subsidies         Convert Position         The axis movements that are required to match the measured position angles are calculated.           Subsidies         Scene         The specified scene is copied to the current scene.           System frommation         Conditional Execution (If)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Select Execution (If)         Conditional Execution (If)         Execution (If) proce		<b>000</b>	Parallelize Task	more tasks and processed in parallel to shorten the measurement time. This processing item is placed im- mediately before processing to be performed in paral-
Participant         Data         held under other processing items can be referenced.           Image: Support         Position Data         The specified position angle is calculated from the measured positions.           Image: Stage Data         Sets and stores data related to stages.         Image: Stage Data         Sets and stores data related to robots.           Image: Stage Data         Sets and stores data related to robots.         Image: Stage Data         Sets and stores data related to robots.           Image: Stage Data         Sets and stores data related to robots.         Image: Stage Data         Sets and stores data related to robots.           Image: Stage Data         Sets and stores data related to robots.         Image: Stage Data         Sets and stores data related to robots.           Image: Stage Data         Convert Position         The axis movement that is required to match the measured position angles to the corresponding reference position angles to the corresponding reference position angles are calculated.         Image: Stage Data         Sets and stores data required to match the measured position angles are calculated.           Image: System         Camera         The specified scene is copied to the current scene.         Obtain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller.           Image: System         Conditional         The rescription result obtained using the set expressions and conditions.           Image: System         Condi			Statistics	
Support measurement         Calculation         measured positions.           Support measurement         Stage Data         Sets and stores data related to stages.           Support measurement         Noto Data         Sets and stores data related to robots.           Image: Support measurement         Vision Master Calibration         This processing item automatically calculates the en- tite axis movement anount of the control equipment necessary for calibration.           Image: Support         Convert Position Data         The axis movement hat is required to match the measured position angles to the corresponding refer- ence position angles are calculated.           Image: Camera Calibration         By setting the camera calibration, the measurement result can be converted and output as actual dimen- sions.           Image: Camera Calibration         Sets and stores data related to condition.           Image: Conditional Execution (ft)         The specified scene is copied to the current scene.           Image: Conditional Execution (ft)         The procitem must be set up as the last processing and conditions.           Image: Conditional Execution (ft)         The acte processes are repeated until the loop count reaches the specified number, and then the next pro- cess starts.           Image: Conditional Execution (ft)         Insert between the Loop processing item. The measurement flow is divided according to the comparison result obtai				
Support measurement         Image: Construction of the control equipment recessary for calibration         Sets and stores data related to robots.           Image: Calibration Calibration Calibration Data         This processing item automatically calculates the en- tre axis movement amount of the control equipment necessary for calibration.         The position angle after the specified axis movement is calculated.           Image: Convert Position Data         Movement Multi Data         The axis movement that is required to match the mea- sured position angles to the corresponding refer- ence position angles to the corresponding refer- ence position angles are calculated.           Image: Calibration         By setting the camera calibration, the measurement calibration         By setting the camera calibration, the measurement result can be converted and output as actual dimen- sions.           Image: Calibration         Scene         The specified scene is copied to the current scene.           Image: Conditional Information         Data system information (e.g., memory and disk space and 10 input signal status) of the Sensor Con- troller.           Image: Conditional Into of a branch.         Image: Conditional Execution (file)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditional Execution (file)           Image: Conditional Execution (Else)         Insert between the Conditional Execution (file)         Insert between the Conditional Execution (file)           Image: Conditional Execution (Else)         Select Execution (Calibration         Select Executio		$\mathbf{X}$		
Support         Image: Calibration         This processing item automatically calculates the entire axis movement amount of the control equipment necessary for calibration.           Image: Calibration         Image: Convert Position         The position angle after the specified axis movement is calculated.           Image: Convert Position         The axis movement that is required to match the measured position angles are calculated.           Image: Convert Position         The axis movement that are required to match the measured position angles are calculated.           Image: Convert Position         The axis movements that are required to match the measured position angles are calculated.           Image: Convert Position         The axis movements that are required to match the measured position angles are calculated.           Image: Convert Position         The axis movement that is required to match the measured position angles are calculated.           Image: Convert Position         By setting the camera calibration, the measurement result can be converted and output as actual dimensions.           Image: Conditional Execution (If)         Conditional Execution (If)           Image: Conditional Execution (If)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: Conditional Execution (If)         Conditional Execution (If)         Insert between the Conditional Execution (If) processing item. The measurement flow is divided according to the comparison result obtained using the set expressions.		+/	Stage Data	Sets and stores data related to stages.
Vision Master Calibration         This processing item automatically calculates the eh- tire axis movement amount of the control equipment necessary for calibration.           Image: Convert Position Data         The position angle after the specified axis movement is calculated.           Image: Convert Position Data         The axis movement that is required to match the mea- sured position angle is the reference position angle is calculated.           Image: Convert Position Display result         The axis movement that are required to match the measured position angles to the corresponding refer- ence position angles are calculated.           Image: Convert Position Display result         Camera Camera Calibration         By setting the camera calibration, the measurement result can be converted and output as actual dimen- sions.           Image: Conditional Execution (If)         Distain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Con- troller.           Image: Conditional Execution (If)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: Conditional Execution (If)         Inser tetween the Conditional Execution (If) process- ing item and End If processing item. The measurement flow is divided according to the comparison result ob- tained using the conditions.           Image: Conditional Execution (If)         Inser tetween the Loop processing item. Det obpe for the conditions.           Image: Conditional Execution (If)         Inser tetween the Loop processing item. Dato bo before the loop court reaches the specified n		₽ <b>0</b>	Robot Data	Sets and stores data related to robots.
Data         is calculated.           Image: Single Position         The axis movement that is required to match the measured position angle is to the corresponding reference position angles to the construct scene.           Image: Scene         The system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller.           Image: Conditional Execution (ff)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: Conditional Execution (ff)         Conditional Execution (ff)         Insert between the Loop processing item. The measurement flow is divided according to the comparison result obtained using the conditions.           Image: Conditional Execution (ff)         Select Execution (Select) <th< td=""><td>measurement</td><td>¢,</td><td></td><td>tire axis movement amount of the control equipment</td></th<>	measurement	¢,		tire axis movement amount of the control equipment
Immovement Number         Survey position         Survey p		ţ		
Image: Project Sector         Comparison of the sector Sector         Sector		-+/		sured position angle to the reference position angle is
Calibration         result can be converted and output as actual dimensions.           Calibration         result can be converted and output as actual dimensions.           Scene         The specified scene is copied to the current scene.           Obtain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller.           Image: System information (f)         Obtain system information (e.g., memory and disk space and I/O input signal status) of the Sensor Controller.           Image: Scene         End         This Procitem must be set up as the last processing unit of a branch.           Image: Scene Conditional Execution (ff)         Conditional Execution (ff)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: Conditional Execution (Else)         Insert between the Conditional Execution (ff) processing item. The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: Loop         The set processing item. Used to stop the loop before the loop count reaches the specified number.           Image: Select Execution (Select)         Select Execution (Case)         Output data to the external devices such as a programmable controller or a PC via PLC Link, Fieldbus interface (EtherCAT *4, EtherNet/IP (other than message communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a programmable controller or a PC via PLC Link, Fieldbus		##		measured position angles to the corresponding refer-
Image: System Information         Obtain system information (e.g., memory and disk space and 1/0 input signal status) of the Sensor Controller.           Image: System Information         This ProcItem must be set up as the last processing unit of a branch.           Image: System Information (e.g., memory and disk space and 1/0 input signal status) of the Sensor Controller.         This ProcItem must be set up as the last processing unit of a branch.           Image: System Information (e.g., memory and disk space and 1/0 input signal status) of the Sensor Controller.         The ProcItem must be set up as the last processing unit of a branch.           Image: System Information (e.g., memory and disk space and 1/0 input signal status) of the Sensor Controller.         The set up control of a branch.           Image: System Information (f)         Conditional Execution (f)         The set processing item. The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: Sensor Controller and the next process starts.         Image: Sensor Controller and the next process starts.           Image: Sensor Controller and the next process starts.         Image: Sensor Controller and the next process starts.           Image: Sensor Controller and the next processing item. Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Select Execution (Select)         Used to set conditions further measurement flow is divided according to the comparison result obtained using the conditions given by expressions.				result can be converted and output as actual dimen-
Image: System information information         space and I/O input signal status) of the Sensor Controller.           Information information         space and I/O input signal status) of the Sensor Controller.           Image: This Procision information         End         This Procision information           Image: This Procision information         Conditional Execution (If)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Image: The set processes are repeated until the loop count reaches the specified number, and then the next process starts.         Insert between the Loop processing item and End Loop processing item. The measurement flow is divided according to the comparison result obtained using the conditions. The loop count reaches the specified number.           Image: Select Execution (Select)         Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Select Execution (Case)         Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Result Output (I/O)         Output data to the external devices such as a programmable controller or a PC via PLC Link, Fieldbus interface (EtherCAT *4, EtherNet/IP (other than message communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a programmable controller or a PC with non-procedure mode via Etherenet or RS-232C. This processing item allows you to save		-	Scene	The specified scene is copied to the current scene.
Branch         Conditional Execution (If)         The measurement flow is divided according to the comparison result obtained using the set expressions and conditions.           Branch         Conditional Execution (Else)         Insert between the Conditional Execution (If) process- igne made Table (If) processing item. The measurement flow is divided according to the comparison result ob- tained using the set expressions and conditions.           Branch         Conditional Execution (Else)         Insert between the Loop processing item. The measurement flow is divided according to the comparison result ob- tained using the set expressions and conditions.           Branch         Coop Suspension         Insert between the Loop processing item and End Loop processing item. Used to stop the loop before the loop count reaches the specified number.           Select Execution (Select)         Select Execution (Case)         Used to set conditions. The measurement flow is divide daccording to the comparison result obtained using the condition given by expressions.           Output tresult         Result Output (I/ O)         Result Output (I/ O)         Output data to the external devices such as a pro- grammable controller or a PC via PLC Link, Fieldbus interface (EtherCAT ¥4, Etherket/IP (other than mes- sage communication), PROFINET).           Output tresult         Result Output (Message)         Output data to the external devices such as a pro- grammable controller or a PC via PLC Link, Fieldbus interface (EtherCAT ¥4, Etherket/IP (other than mes- sage communication), PROFINET).           Display Last NG Image         Result Display         Output measureme		Ø		space and I/O input signal status) of the Sensor Con-
Branch         Conditional Execution (if)         comparison result obtained using the set expressions and conditions.           Branch         Conditional Execution (Else)         Insert between the Conditional Execution (If) process- ing item and End If processing item. The measurement is divided according to the comparison result ob- tained using the set expressions and conditions.           Branch         Coop         The set processes are repeated until the loop count reaches the specified number, and then the next pro- cess starts.           Image: Comparison result obtained using the set expressions and conditions.         The set processes are repeated until the loop count reaches the specified number, and then the next pro- cess starts.           Image: Comparison result obtained using the comparison result obtained using the conditions given by expressions.         Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Comparison result obtained using the controller or a PC via PLC Link, Fieldbus interface (EtherCAT ¥4, EtherNet/IP (Ufer than mes- sage communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a pro- grammable controller or a PC via PLC Link, Fieldbus interface (EtherCAT ¥4, EtherNet/IP (Ufer than mes- sage communication), PROFINET).           Output tresult         Result Output (Message)         Output data to the external devices such as a pro- grammable controller or a PC via the comparison result to the external devices such as a pro- grammable controller or a PC with non-procedure allows you to		\$ <b>*</b>	End	
Branch         Conditional Execution (Else)         ing item and End If processing item. The measurement two is divided according to the comparison result ob- tained using the set expressions and conditions.           Branch         Image: Conditional Coop         The set processes are repeated until the loop count reaches the specified number, and then the next pro- cess starts.           Image: Conditional Coop         Loop         Insert between the Loop processing item. Used to stop the loop before the loop count reaches the specified number.           Image: Conditional Coop         Select Execution (Select)         Used to set conditions. The measurement flow is divid- divided according to the comparison result obtained using the conditions given by expressions.           Image: Conditional Cosp         Select Execution (Case)         Used to make a judgment. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Controller or a PC via PLC Link, Fieldbus interface (EtherCAT #4, EtherNet/IP (Ufort than mes- sage communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a pro- grammable controller or a PC via PLC Link, Fieldbus interface (EtherCAT #4, EtherNet/IP (Ufort than mes- sage communication), PROFINET).           Image: Result Output (Message)         Output data to the external devices such as a pro- grammable controller or a PC with processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.           Image: Result Display         Used for displayi		h		comparison result obtained using the set expressions
Branch         Image: Coop         reaches the specified number, and then the next process starts.           Image: Coop         Loop         reaches the specified number, and then the next process starts.           Image: Coop         Loop         Insert between the Loop processing item and End Loop processing item. Used to stop the loop before the loop count reaches the specified number.           Image: Coop         Select Execution (Select)         Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Coop         Select Execution (Case)         Used to make a judgment. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Coop         Result Output (I/O)         Output data to the external devices such as a programmable controller or a PC via PLC lunk, Fieldbus inderface (EtherCAT ¥4, EtherNet/IP (other than message communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a programmable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.           Image: Result Display         Output measurement results and/or judgment results to the external devices such as a programmable controller or a PC via Parallel interface exts.           Image: Result Display         Output data to the external devices such as a programmable controller or a PC via Parallel inter		5		ing item and End If processing item. The measurement flow is divided according to the comparison result ob-
Output result         Exception         Loop processing item. Used to stop the loop before the loop count reaches the specified number.           Image: Select Execution (Select)         Select Execution (Select)         Used to set conditions. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Select Execution (Case)         Select Execution (Case)         Used to make a judgment. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Select Execution (Case)         Select Execution (Case)         Used to make a judgment. The measurement flow is divided according to the comparison result obtained using the conditions given by expressions.           Image: Result Output (I/O)         Output data to the external devices such as a programmable controller or a PC via PLC Link, Fieldbus interface (EtherCAT ¥4, EtherNet/IP (other than message communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a programmable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.           Image: Result Display         Output measurement results and/or judgment results to the external devices such as a programmable controller or a PC via Parallel interface ex5.           Image: Result Display         Used for displaying the texts or the figures in the camera image.           Image: Display Last NG Image         Display	Branch	(7	Loop	reaches the specified number, and then the next pro-
Output result         Result Output (0)         Output data to the external devices such as a pro- grammable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as a PI (0)           Image         Result output (Parallel 1 / 0)         Output measurement results and/or judgment results to the external devices such as a programmable con- troller or a PC via Parallel interface *5.           Image         Result Display         Quetput measurement results and/or judgment results to the external devices such as a programmable con- troller or a PC via Parallel interface *5.           Image         Display Last NG Image         Display the last NG images.         Display Image		¢7		Loop processing item. Used to stop the loop before the
Output result         Select Execution (Case)         divided according to the comparison result obtained using the conditions given by expressions.           Output data to the external devices such as a pro- grammable controller or a PC via PLC Link, Fieldbus output result         Result Output (I/ 0)         Output data to the external devices such as a pro- grammable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.           Display Last NG Image         Result Display         Used for displaying the texts or the figures in the cam- era image.           Display Last NG Image         Display Last NG Image         Display the last NG images.		Ψ		ed according to the comparison result obtained using
Output result         Result Output (I/ O)         grammable controller or a PC via PLC Link, Fieldbus interface (EtherCAT ¥4, EtherNet/IP (other than mes- sage communication), PROFINET).           Output result         Result Output (Message)         Output data to the external devices such as a pro- grammable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a *.csv* file into the Sensor Controller as well.           Image         Result output (Parallel I / O)         Output measurement results and/or judgment results to the external devices such as a programmable con- troller or a PC via PLC.           Image         Result Display         Used for displaying the texts or the figures in the cam- era image.           Image         Display Last NG Image         Display the last NG images.           Image         Display Image         Processing item to retain images, including measure-		st.		divided according to the comparison result obtained using the conditions given by expressions.
Output result         Result Output (Message)         grammable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.           Image         Result output (Parallel 1 / O)         Output measurement results and/or judgment results the external devices such as a programmable con- troller or a PC via Parallel interface *5.           Image         Result Display         Used for displaying the texts or the figures in the cam- era image.           Display Last NG Image         Display the last NG images.           Image         Display Image			O)	grammable controller or a PC via PLC Link, Fieldbus interface (EtherCAT *4, EtherNet/IP (other than mes-
Image: New York         New York         New York         To the external devices such as a programmable controller or a PC via Parallel interface *5.           Image: Display result         Image: Display Last NG Image         Used for displaying the texts or the figures in the camera image.           Image: Display Last NG Image         Display the last NG images.         Display Image	Output result			grammable controller or a PC with non-procedure mode via Ethernet or RS-232C. This processing item allows you to save the logging data as a ".csv" file into the Sensor Controller as well.
Display result         Display Last NG Image         Display the last NG images.           Display result         Display Image         Processing item to retain images, including measure-				to the external devices such as a programmable con-
Display result image Display uterast No infrages.		OK	Result Display	
	Display result	NG		Display the last NG images.
		6		

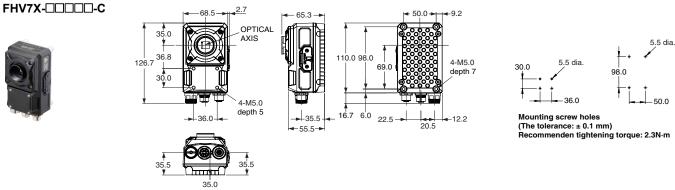
2D Codes that can be read : Data Matrix (ECC200) 2D Codes that can be read : Data Matrix (ECC200), QR Code Bar Codes that can be read : JAN/EAN/UPC (including add-on codes), Code 39, Codabar (NW-7), ITF (Interleaved 2 of 5), Code 93, Code 128, GS1-128, GS1 DataBar (RSS-14 / RSS Limited / RSS Expanded), Pharmacode The FHV-SDU30 EtherCAT Interface is required for EtherCAT connection. The FHV-SDU10 Parallel Interface is required for Parallel I/O connection.

(Unit: mm)

# Dimensions

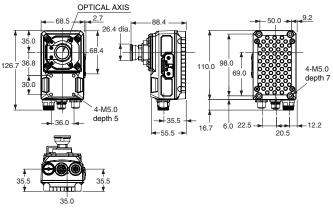
## **Smart Cameras**

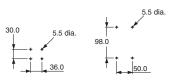
# C Mount Models



All-in-one Models with Lens Module High-speed Lens Modules FHV7X-DDDD-H06



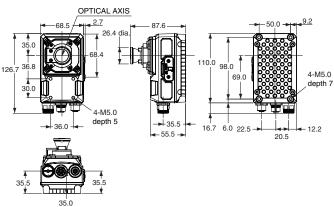


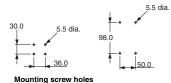


Mounting screw holes (The tolerance: ± 0.1 mm) Recommenden tightening torque: 2.3N·m

## FHV7X-000-H19

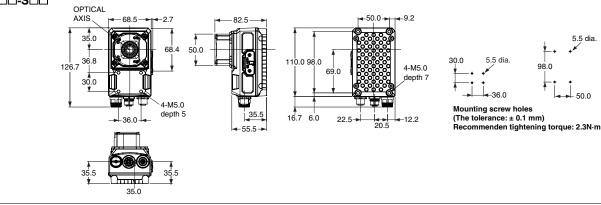






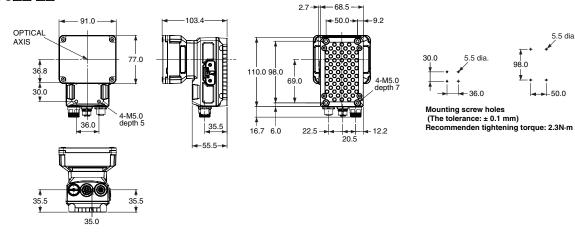
(The tolerance: ± 0.1 mm) Recommenden tightening torque: 2.3N·m

# Standard Lens Modules FHV7X-



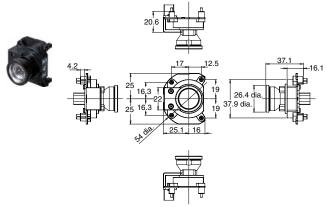
#### All-in-one Models with Lens and Lighting Modules FHV7X-0000-H00-00/ FHV7X-0000-S00-00



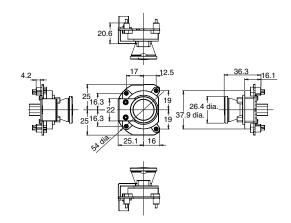


## Lens Modules

**High-speed Lens Modules** FHV-LEM-H06







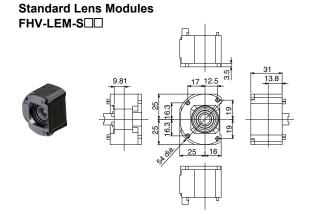
5.5 dia.

50.0

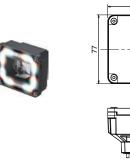
98.0

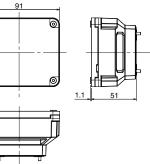
36.0

# **Lighting Modules**



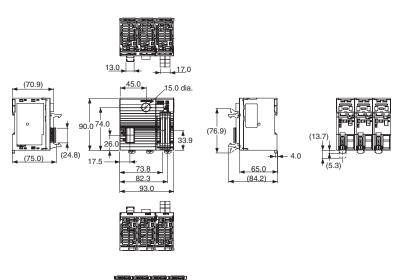
FHV-LTM-



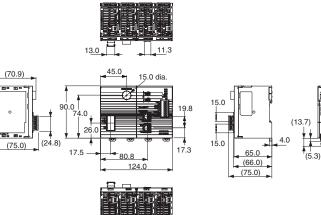


## Smart Camera Data Unit



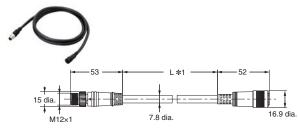


FHV-SDU30

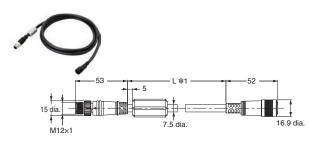




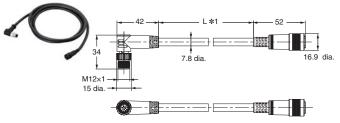
## Bending Resistance Cables (Straight) FHV-VUB2 □M



## 

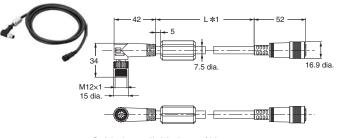


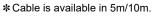
## Bending Resistance Cables (Right angle) FHV-VULB2 □M



\* Cable is available in 2m/3m/5m/10m/20m.

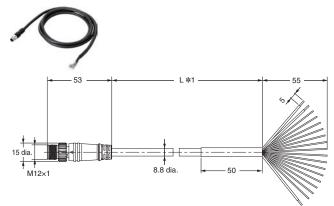
# Super Bending Resistance Cables (Right angle) FHV-VULBX2 □M



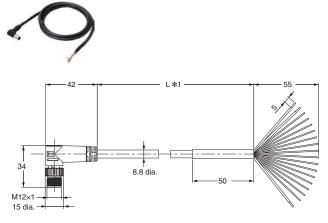


## Cables

I/O cable (Bend resistant, straight) FHV-VDB2 ⊡M

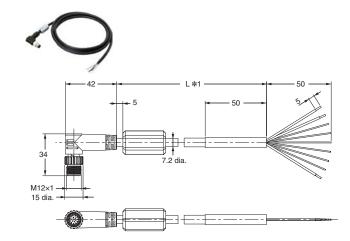


## I/O cable (Bend resistant, right angle) FHV-VDLB2 □M



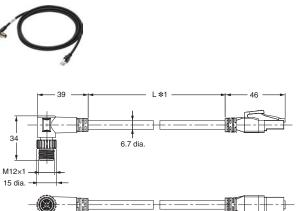
\* Cable is available in 2m/3m/5m/10m/20m.

## I/O cable (Super bend resistant, right angle) FHV-VDLBX2 □M



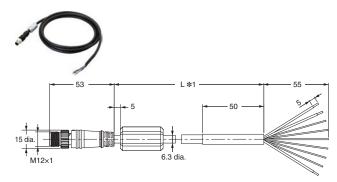
\* Cable is available in 5m/10m.

# Ethernet cable (Bend resistant, right angle) FHV-VNLB2 □M

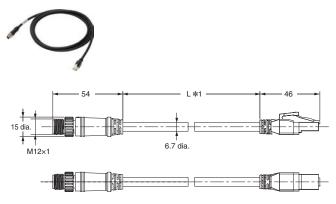


\* Cable is available in 2m/3m/5m/10m/20m.

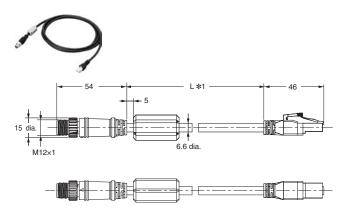
## I/O cable (Super bend resistant, straight) FHV-VDBX2 □M



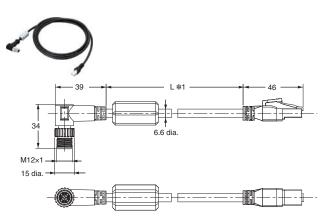
## Ethernet cable (Bend resistant, straight) FHV-VNB2 □M



# Ethernet cable (Super bend resistant, straight) FHV-VNBX2 □M

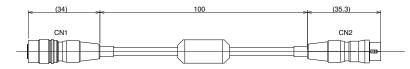


# Ethernet cable (Super bend resistant, right angle) FHV-VNLBX2 IM



\* Cable is available in 5m/10m.

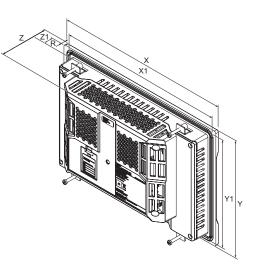
# External Light Junction Cables for MDMC Light FHV-VFLX-GD



# Optical Filters Light Cover Polarization Filter, Diffusion Filter FHV-XDF/-XPL/-XPL-IR FHV-XDF/-XPL/-XPL-IR FHV-XCV Image: Constraint of the state of the

Touch Panel Monitor OMRON Model NYE2A-20F11-00WR1000

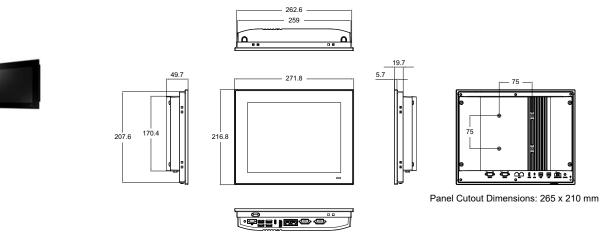




Screen size	Dimensions				Panel cutout dimensions		
Screen Size	X	Y	Z	R	X1	Y1	Z1 <b>*</b> 1
15.4 inch 4	120 mm	291 mm	69 mm	6.0 mm	392 <sup>-0</sup>	268 <sup>-0</sup> +1 mm	1.6 to 6.0 mm
12.1 inch 3	340 mm	244 mm	69 mm	6.0 mm	310 <sup>-0</sup> mm	221 <sup>-0</sup> mm	1.0 10 0.0 mm

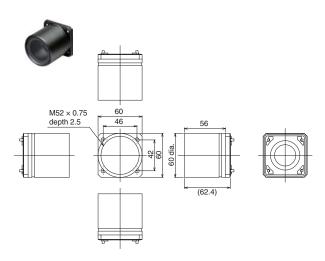
\*1. The minimum panel thickness depends on the panel material.

### Advantech Model PPC-310-OMR

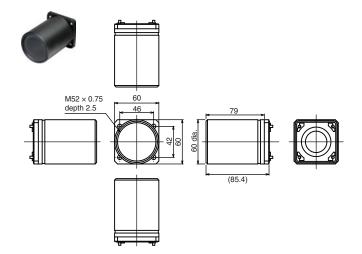


## Waterproof Hoods

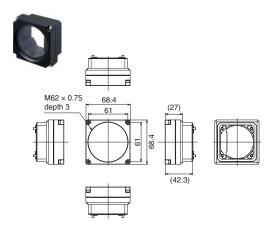
for C-mount Lens (Short) FHV-XHD-S



for C-mount Lens (Long) FHV-XHD-L



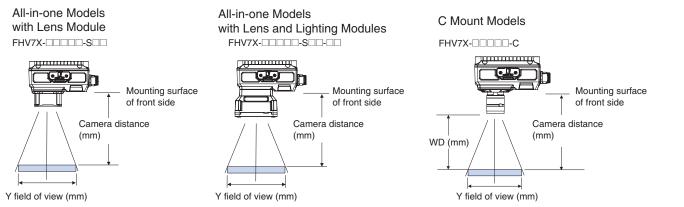
for Lens Modules FHV-XHD-LEM



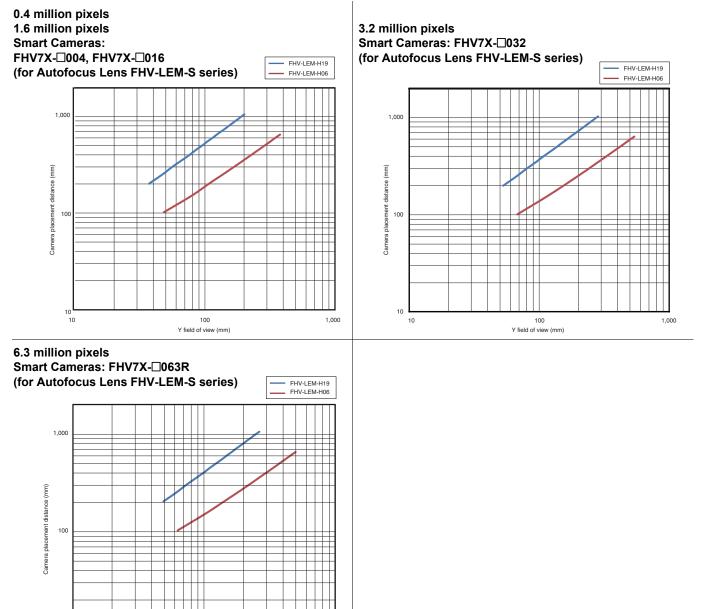
# **Meaning of Optical Chart**

# How-to View the Optical Chart

The X axis of the optical chart shows the field of vision (mm). The Y axis of the optical chart shows the camera installation distance (mm). The lengths of the fields of view given in the optical charts are the lengths of the Y axis.



# Lens Modules: High-speed Lens Modules (Autofocus)



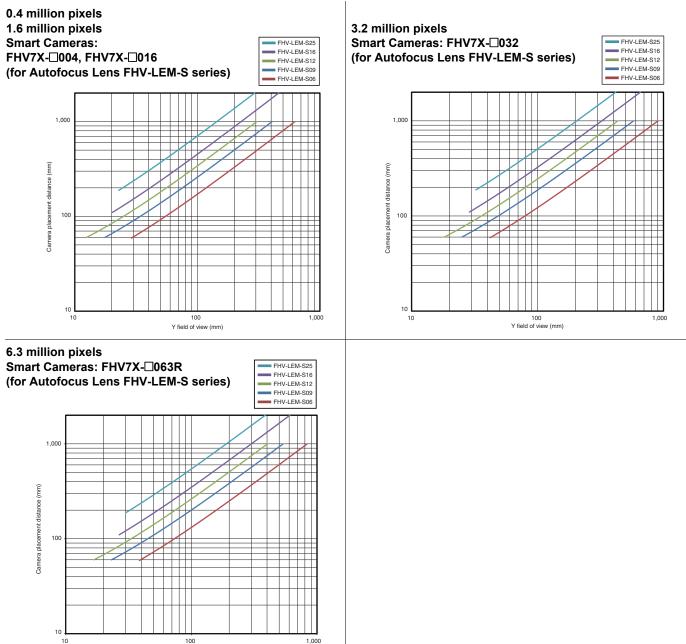
1,000

100

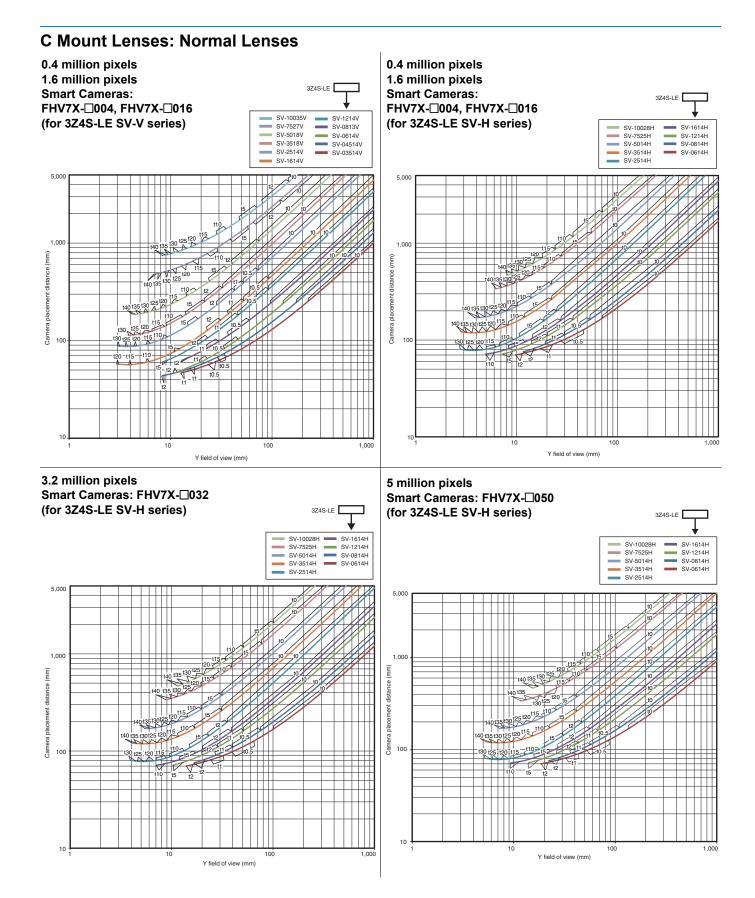
Y field of view (mm)

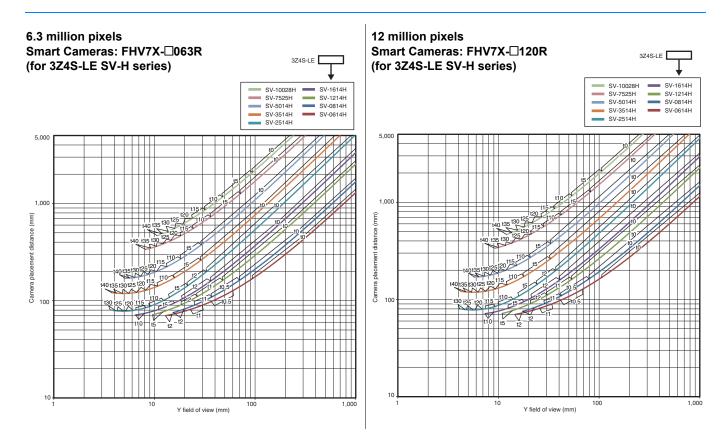
10 L

## Lens Modules: Standard Lens Modules (Autofocus)



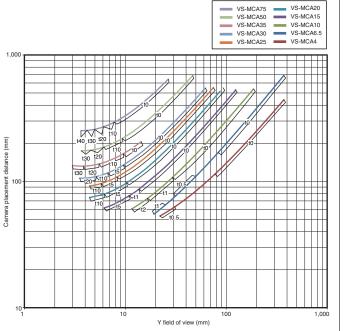
100 Y field of view (mm)

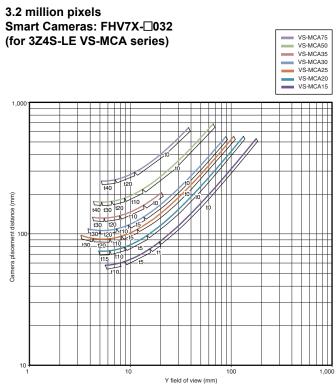


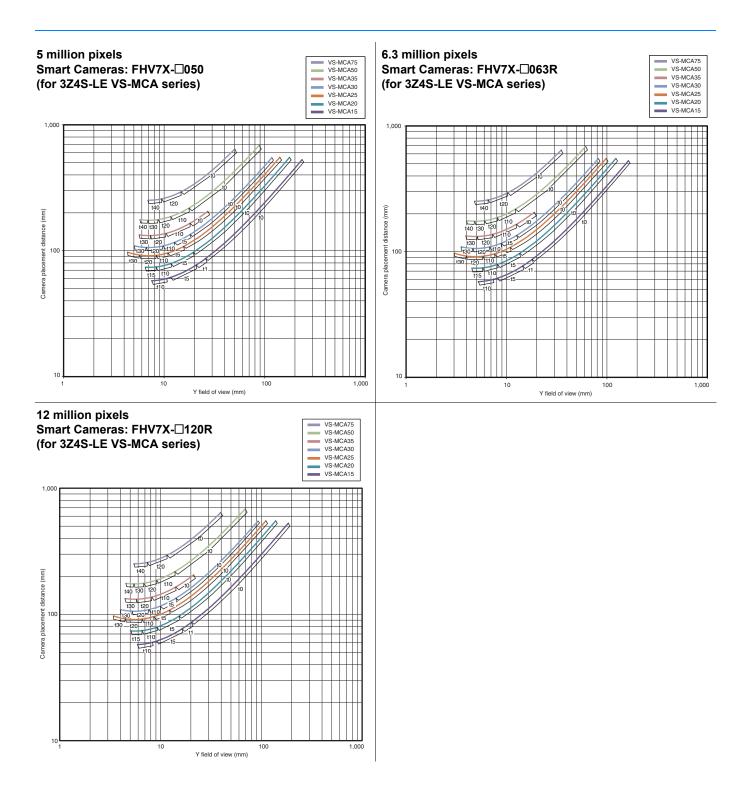


## C Mount Lenses: Vibration/Shock-resistance Lens

#### 400,000 pixels 1.6 million pixels Smart Cameras: FHV7X-□004, FHV7X-□016 (for 3Z4S-LE VS-MCA series)







56

# **Related Manuals/Catalog**

Cat. No.	Series	Manual
Z365	FH/FHV7	Vision System FH/FHV Series User's Manual
Z341	FH/FHV7	Vision System FH/FHV Series Processing Item Function Reference Manual
Z342	FH/FHV7	Vision System FH/FHV Series User's Manual for Communications Settings
Z408	FHV7	Smart Camera FHV Series Setup Manual
Q198	FLV/FL	FLV/FL Vision Accessory CATALOG

Sysmac is a trademark or registered trademark of OMRON Corporation in Japan and other countries for OMRON factory automation products.
 Think&See is a trademark or registered trademark of OMRON Corporation in Japan and other countries.
 EtherNet/IP® is a trademark of ODVA.

• EtherCAT<sup>®</sup> is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

- EtherCAI® is a registered trademark and patented technology, licensed by Beckholl Automation Gribm, Germany.
  QR code is the registered trademark of DENSO WAVE.
  The SD, SDHC, microSD, and microSDHC logos are trademarks of SD-3C, LLC.
  Other company names and product names in this document are the trademarks or registered trademarks of their respective companies.
  The product photographs and figures that are used in this catalog may vary somewhat from the actual products. Microsoft product screen shot(s) reprinted with permission from Microsoft Corporation.
  The permission of Shutterstock.com was received for images that were used.

MEMO

# **Terms and Conditions Agreement**

## Read and understand this catalog.

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

## Warranties.

- (a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied.
- (b) Limitations. OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE.

Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right. (c) Buyer Remedy. Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty.

See http://www.omron.com/global/ or contact your Omron representative for published information.

## Limitation on Liability; Etc.

OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY.

Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

## Suitability of Use.

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

## Programmable Products.

Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.

## Performance Data.

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

## Change in Specifications.

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

## Errors and Omissions.

Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

Note: Do not use this document to operate the Unit.

OMRON Corporation Industrial Automation Company

Kyoto, JAPAN

Contact : www.ia.omron.com

#### **Regional Headquarters**

OMRON EUROPE B.V. Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31) 2356-81-300 Fax: (31) 2356-81-388

**OMRON ASIA PACIFIC PTE. LTD.** 438B Alexandra Road, #08-01/02 Alexandra Technopark, Singapore 119968 Tel: (65) 6835-3011 Fax: (65) 6835-3011 **OMRON ELECTRONICS LLC** 2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900 Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD. Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-6023-0333 Fax: (86) 21-5037-2388 Authorized Distributor:

©OMRON Corporation 2018-2024 All Rights Reserved. In the interest of product improvement, specifications are subject to change without notice. CSM\_8\_1 Cat. No. Q264-E1-16 1124 (1118)