

## **Autonomous Mobile Robots**

# OL-450S Series

# Self-navigating, ultra-low, mobile robots that transport cages and carts with a combined payload up to 450 kg

Natural feature navigation:
 Automatically plans efficient routes and prevents collisions;
 capable of omni-directional navigation

 Fleet management:
 Scale deployment with AMR prioritization and multi-robot coordination, for manufacturing environments

 Easy integration: Installs quickly, without facility modifications

 Ultra-low design:
 Fits underneath roll cages and carts for autonomous transportation of existing storage solutions

· Wireless charging



## **Ordering Information**

Model	Description	Ordering Code
OL-450S2	Omni Lift AMR with standard length lift plate	37590-70000
OL-450S3	Omni Lift AMR with extended length lift plate	37590-80000

Note: All AMRs in a fleet must have the same version of the FLOW Core software installed. Other considerations must be made when adding AMRs to a fleet. Contact your local OMRON representative for more information.

**Note:** The battery for the OL-450S Series AMR must be ordered separately (part number 28110-020). Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

#### Items Included with AMR

Item Description		
Labels	Warning and product labels	
Printed Documentation	Printed guides for safety, unpacking and assembling	
Lift Rings	Hardware for lifting the AMR	

## **Accessories and Optional Items**

Item	Details	Ordering Code
Battery*1	Rechargeable power source for the AMR.	28110-020
Stationary Electronics and Stationary Coil	Power supply box for charging the AMR battery. Includes the external charging coil for wireless charging, cables and covers. Power cable and mounting hardware are user supplied.	28110-101
Charging Ramp	Floor mounted, wireless charging protective surface.	
Service Charger	Portable charger for use in an AMR power loss event. The charger is rated for 200 to 240 VAC at 50/60 Hz.	28110-103
Manual Mover	Used for moving unpowered AMRs.	28110-501
Lift Bridge	Provides an alternate method to lower the lifting mechanism. No charger included.	28110-503
Lift Bridge Charger	Provides charging equipment for the Lift Bridge battery. The charger is rated for 220 to 240 VAC at 50 Hz.	28110-508
Work Bench	Adjustable height table used for performing maintenance tasks.	28110-504

#### **OL-450S Series**

Item	Details	Ordering Code
Maintenance Kit 1	Wipes for cleaning scanners.	28110-506
Maintenance Kit 2	Fluid for cleaning scanners.	28110-505
Mobile I/O Box	Used with a Fleet Manager to summon an AMR to a goal or control connected devices with I/O.	23419-802
Mobile I/O Box Power Supply	Recommended for purchase with the Mobile I/O Box.	23419-812

<sup>\*1</sup> Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

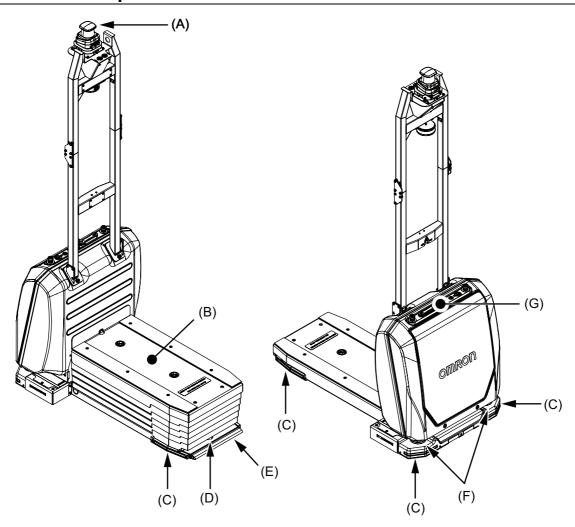
### **Software Licenses**

Product Name	Applicable For	Configuration	Ordering Code
Fleet Operations Workspace Core Fleet Manager License, 3 Year		Initial entitlement for a 3 year renewable FLOW Core license. Replace □□ with 05, 10, 15, 20, 25, 30, to indicate the number of AMRs licensed to connect. Replace □□ with 50 for 31 or more AMRs.	30271-1□□*1
Fleet Operations Workspace Core Fleet Upgrade		Entitlement for a fleet connection limit increase by one additional AMR (used for existing installations).	30271-001
Fleet Operations Workspace Core Renewal	Virtual Fleet Manager	Entitlement for a 1 year renewal of the FLOW Core license. Replace $\square$ with a value of 05 to 30 to indicate the number of AMRs licensed to connect. Replace $\square$ with 50 for 31 or more AMRs.	30271-2□□
Flord On continue Westerness		Entitlement for a 1 year renewable FLOW iQ license.	30271-701
Fleet Operations Workspace iQ License (FLOW iQ)		Entitlement for a 3 year renewable FLOW iQ license.	30271-703
		Entitlement for a 5 year renewable FLOW iQ license.	30271-705
Cell Alignment Positioning System (CAPS) License	AMR	AMR Alignment using software-defined target. Entitlement for a perpetual CAPS license.	20271-805
Cycle Time Optimization		Enables reduced cycle times with fewer stops and path caching. Entitlement for a perpetual Cycle Time Optimization license.	20271-905

<sup>\*1</sup> After expiration of a FLOW Core Fleet Manager license, all Virtual Fleet Manager functionality will continue to operate without requiring subscription renewals. An active subscription is required for software upgrades and to access subsequent software releases, including bug fixes, feature upgrades, and performance improvements.

**Note:** To upgrade to the latest version of the FLOW Core software, contact your local OMRON representative. Please note that an active subscription is required for access to software upgrades.

# **Features and Components**



Item	Description	Item	Description
Α	360-degree Scanner	Е	Rear Bumper
В	Lifting Plate	F	Front Safety Scanners
С	Light Strips	G	Control Strip
D	Rear Scanner		

# **Specifications**

Item Model		Details			
		OL-450S2 OL-450S3			
Weight (with Battery)		185 kg	190 kg		
Ambient Temperature		5 to 40°C			
	Storage Temperature	-20 to 60°C	-20 to 60°C		
Environment _	Operating and Storage Humidity	5% to 95% (non-condensing)			
	Operating Environment	Indoors only, no excessive dust, no corrosive gas			
	Altitude	2000 m (max.)			
	Ingress Protection Class	IP20			
	Dust / Smoke	Accumulated dust smaller than 40 µm cannot exceed 11.7 mL / m² in the operation environment. Avoid operating in areas with smoke or dust.			
	Enclosure Rating	NEMA Type 2			
	Atmospheric	No hazardous materials, (no explosive gas or oil mist)			

#### **OL-450S Series**

Ground Clearance		Item	De	tails		
Profession   Province   Provin		Model	OL-450S2	OL-450S3		
Minimum Levelness   FL25 (per ACI 117 standard)		Ground Clearance	10 mm			
Minimum Levelness   FL25 (per ACI 117 standard)		Minimum Floor Flatness	NEN 2747-2001 / flatness category 5, DIN 18202 Group 3			
Floor Conditions   Maximum floor resistance 1 GΩ		Minimum Levelness	<u> </u>			
Maximum Step Traversal   No step traversal permitted						
Maximum Step Traversal   No step traversal permitted		Abrasion Resistance				
Maximum Gap Traversal**   10 mm						
Maximum Slope   Flat surfaces only	Conditions	•	· ' '			
Minimum Floor Compressive Strength   9.9 MPa (min.), NEN-EN 206-1: 2014 / strength category C25 / 30		•				
Minimum Coefficient of Friction   Static coefficient of friction μs ≥ 0.4		•	,	strength category C25 / 30		
Navigation   Routing   environment mapping		·	Static coefficient of friction µs ≥ 0.6	3 7 7 2 2 2 2 2		
Environmental Map-making Method   MobilePlanner		Routing		afety scanning laser, based on		
Lifting         Lifting Height Lifting Speed         308 mm           Lifting Speed         40 mm/s           Run Time         Full payload: approximately 7 hours No payload: approximately 11 hours           Swing Radius         685 mm           Maximum Translational Speed (forward and lateral)         1200 mm/s           Maximum Reverse Speed         300 mm/s           Maximum Translational Acceleration         750 mm/s²           Maximum Rotational Deceleration         1000 mm/s²           Maximum Rotational Speed**         65°/s         35°/s           Maximum Rotational Deceleration         165°/s²         85°/s           Maximum Moment of Inertia         100 kg-m²         85°/s           Stop Position Repeatability (Single AMR)*3         To a position: ±160 mm, ±7°         With CAPS: ±6 mm, ±0.6°           Ville CAPS: ±6 mm, ±0.6°         With CAPS: ±6 mm, ±0.6°         Stop Position Repeatability (Fleet)*3         To a position: ±160 mm, ±7°           Drive Wheels         Materials         Steel with Vulkollan (polyurethane) tread           Stationary Electronics and Stationary Coil         EN 1SO 12100, EN 1SO 13849-1, EN/IEC 60204-1, EN 1SO 3691-4 (except clad 4.12), EN61000-6-2, EN61000-6-4, KS C 9610-6-2, KS C 9610-6-4           Wireless         ELEE 802.11 a/b/g           Stationary Electronics and Stationary Coil         EN 60335-2-29, EN 62311, E	Navigation	Environmental Map-making Method		vironment and upload the scan data to		
Lifting Speed		Lifting Capacity	450 kg			
Run Time	Lifting		308 mm			
No payload: approximately 11 hours		Lifting Speed	40 mm/s			
Turn Radius   750 mm		Run Time				
Maximum Translational Speed (forward and lateral)   1200 mm/s		Swing Radius	685 mm			
Maximum Reverse Speed   300 mm/s		Turn Radius	750 mm			
Mobility         Maximum Translational Acceleration         750 mm/s²           Maximum Translational Deceleration         1000 mm/s²           Maximum Rotational Speed*2         65°/s         35°/s           Maximum Rotational Deceleration         165°/s²         85°/s           Maximum Moment of Inertia         100 kg-m²         85°/s           Stop Position Repeatability (Single AMR)*3         To a position: ±160 mm, ±7° With CAPS: ±6 mm, ±0.6°           Stop Position Repeatability (Fleet)*3         To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°           Drive Wheels         Materials         Steel with Vulkollan (polyurethane) tread           Battery         UN 38.3         EN ISO 12100, EN ISO 13849-1, EN/IEC 60204-1, EN ISO 3691-4 (except claded 4.12), EN61000-6-2, EN61000-6-4, KS C 9610-6-2, KS C 9610-6-4           Wireless         IEEE 802.11 a/b/g           Certification Markings         AMR         CE, KC           Battery         CE         KC           Stationary Electronics and Stationary Coil         CE, KC           Stationary Electronics and Stationary Coil         CE, CMETus			1200 mm/s			
Maximum Translational Deceleration         1000 mm/s²           Maximum Rotational Speed*2         65°/s         35°/s           Maximum Rotational Acceleration         165°/s²         85°/s           Maximum Rotational Deceleration         165°/s²         85°/s           Maximum Moment of Inertia         100 kg-m²           Stop Position Repeatability (Single AMR)*3         To a position: ±160 mm, ±7° With CAPS: ±6 mm, ±0.6°           Stop Position Repeatability (Fleet)*3         To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°           With CAPS: ±10 mm, ±0.8°           Steel with Vulkollan (polyurethane) tread           Drive Wheels         Makerials         Steel with Vulkollan (polyurethane) tread           With CAPS: ±10 mm, ±0.8°           Steel with Vulkollan (polyurethane) tread           With CAPS: ±10 mm, ±0.8°           UN 38.3           Stationary Electronics and Stationary Coil         EN 60335-2-29, EN 62311, EN 55011, EN 61000-6-2, UL 1564           Wireless         IEEE 802.11 a/b/g           Cet, KC           Stationary Electronics and Stationary Coil         CE, CMETus           Stationary Electronics and Stationary Coil         CE, CMETus		Maximum Reverse Speed	300 mm/s			
Maximum Rotational Speed*2   65°/s   35°/s   85°/s		Maximum Translational Acceleration	750 mm/s <sup>2</sup>			
Maximum Rotational Acceleration         165°/s²         85°/s           Maximum Rotational Deceleration         165°/s²         85°/s           Maximum Moment of Inertia         100 kg-m²           Stop Position Repeatability (Single AMR)*³         To a position: ±160 mm, ±7° With CAPS: ±6 mm, ±0.6°           Stop Position Repeatability (Fleet)*³         To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°           Drive Wheels         Materials         Steel with Vulkollan (polyurethane) tread           AMR         EN ISO 12100, EN ISO 13849-1, EN/IEC 60204-1, EN ISO 3691-4 (except claded 4.12), EN61000-6-2, EN61000-6-4, KS C 9610-6-4           Battery         UN 38.3           Stationary Electronics and Stationary Coil         EN 60335-2-29, EN 62311, EN 55011, EN 61000-6-2, UL 1564           Wireless         IEEE 802.11 a/b/g           AMR         CE, KC           Battery         CE           Stationary Electronics and Stationary Coil         CE, CE	Mobility	Maximum Translational Deceleration	1000 mm/s <sup>2</sup>			
Maximum Rotational Deceleration   165°/s²   85°/s		Maximum Rotational Speed*2	65°/s 35°/s			
Maximum Moment of Inertia   100 kg-m²   To a position: ±160 mm, ±7°   With CAPS: ±6 mm, ±0.6°		Maximum Rotational Acceleration	165°/s²	85°/s		
Stop Position Repeatability (Single AMR)*3  Stop Position Repeatability (Fleet)*3  Stop Position Repeatability (Fleet)*3  To a position: ±160 mm, ±7° With CAPS: ±6 mm, ±0.8°  To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Repeatability (Fleet)*3  To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Repeatability (Fleet)*3  To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Repeatability (Fleet)*3  To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±6 mm, ±0.6°  To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°  Step Position Posi		Maximum Rotational Deceleration	165°/s²	85°/s		
AMR)*3         With CAPS: ±6 mm, ±0.6°           Stop Position Repeatability (Fleet)*3         To a position: ±160 mm, ±7° With CAPS: ±10 mm, ±0.8°           Drive Wheels         Materials         Steel with Vulkollan (polyurethane) tread           AMR         EN ISO 12100, EN ISO 13849-1, EN/IEC 60204-1, EN ISO 3691-4 (except claded 4.12), EN61000-6-2, EN61000-6-4, KS C 9610-6-2, KS C 9610-6-4           Battery         UN 38.3           Stationary Electronics and Stationary Coil         EN 60335-2-29, EN 62311, EN 55011, EN 61000-6-2, UL 1564           Wireless         IEEE 802.11 a/b/g           AMR         CE, KC           Battery         CE           Stationary Electronics and Stationary Coil         CE, CE           Stationary Electronics and Stationary Coil         CE, CMETus		Maximum Moment of Inertia	100 kg-m <sup>2</sup>			
Stop Position Repeatability (Fleet)   With CAPS: ±10 mm, ±0.8°			To a position: ±160 mm, ±7° With CAPS: ±6 mm, ±0.6°			
Wheels         Materials         Steel with Vulkollan (polyurethane) tread           AMR         EN ISO 12100, EN ISO 13849-1, EN/IEC 60204-1, EN ISO 3691-4 (except claded 4.12), EN61000-6-2, EN61000-6-4, KS C 9610-6-2, KS C 9610-6-4           Battery         UN 38.3           Stationary Electronics and Stationary Coil         EN 60335-2-29, EN 62311, EN 55011, EN 61000-6-2, UL 1564           Wireless         IEEE 802.11 a/b/g           AMR         CE, KC           Battery         CE           Stationary Electronics and Stationary Coil         CE, cMETus		Stop Position Repeatability (Fleet)*3				
Standards   Battery   UN 38.3		Materials	Steel with Vulkollan (polyurethane) tread	d		
Stationary Electronics and Stationary Coil EN 60335-2-29, EN 62311, EN 55011, EN 61000-6-2, UL 1564  Wireless IEEE 802.11 a/b/g  Certification Markings CE, KC  Stationary Electronics and Stationary Coil CE, cMETus		AMR	EN ISO 12100, EN ISO 13849-1, EN/IEC 60204-1, EN ISO 3691-4 (except claus 4.12), EN61000-6-2, EN61000-6-4, KS C 9610-6-2, KS C 9610-6-4			
Wireless IEEE 802.11 a/b/g  Certification Markings AMR CE, KC  Battery CE  Stationary Electronics and Stationary Coil CE, cMETus	Standards	Battery	UN 38.3			
Certification Markings     AMR     CE, KC       Battery     CE       Stationary Electronics and Stationary Coil     CE, cMETus		Stationary Electronics and Stationary Coil	EN 60335-2-29, EN 62311, EN 55011, I	EN 61000-6-2, UL 1564		
Certification Markings   Battery   CE   Stationary Electronics and Stationary Coil   CE, cMETus		Wireless				
Markings Stationary Electronics and Stationary Coil CE, cMETus		AMR	CE, KC			
Stationary Electronics and Stationary Coil CE, cMETus		Battery	CE			
Safety Scanners 2 front safety scanners, 29 zone sets, selected based on velocity		Stationary Electronics and Stationary Coil	il CE, cMETus			
	Safety Features	Safety Scanners	2 front safety scanners, 29 zone sets, selected based on velocity			
Safety E-Stop Buttons 2 buttons on Control Strip		E-Stop Buttons	2 buttons on Control Strip			
Features Rear Bumper Stops AMR when rear bumper is depressed by physical contact		Rear Bumper	Stops AMR when rear bumper is depres	ssed by physical contact		
Audible Indicators Audible warning buzzer, programmable through MobilePlanner		Audible Indicators	Audible warning buzzer, programmable	through MobilePlanner		
Visual   LED Light Strips   of AMR		LED Light Strips	Shows direction of movement and operational status, located on front and rear			
Safety Approach Light Projects a visible red laser light in AMR travel direction	muicators	Safety Approach Light	Projects a visible red laser light in AMR	travel direction		

<sup>\*1:</sup> A 10 mm gap cannot be traversed at speeds greater than 750 mm/s.

<sup>\*2:</sup> The maximum rotational speed is reduced to 17 degrees/s when the AMR is traveling at speeds over 20 mm/s.
\*3: Stop position repeatability values were obtained using default AMR parameters and a map created by the OL-450S Series AMR.

#### **MobilePlanner Software Requirements**

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Operating System		Windows 10 (64-bit version), Windows 11
MobilePlanner PC	CPU	1.5 GHz dual-core CPU recommended
	Main Memory	1.5 GB min. (4 GB min. recommended)
	Hard Disk	At least 400 MB of available space
	Video Memory	256 MB min.
	Display	XGA 1024 x 768, 16 million colors minimum
MobilePlanner Operating Tablet Edition System		Android® OS, Version 9 or newer, minimum 2 GB of RAM
		iOS®, Version 10 or newer
Supported Languages		English, German, Japanese, French, Italian, Korean, Spanish, Polish, Simplified Chinese and Traditional Chinese

# Virtual Fleet Manager Software, Minimum Hardware Requirements

Fleet Size / AMR Count	Small/	Medium	Large	X-Large
	≤ 5	≤ 15	≤ 30	> 30*1
Virtual CPU	2 (	2 Cores 4 C		Cores
Clock Speed		4 GHz	8 GHz	12 GHz
Virtual RAM		8 GB	16 GB	24 GB
Virtual Disk		512 GB		1 TB
FLOW Software Version	Minimum FLOW Core 5.0			
*** 0 * * * * * * * * * * * * * * * * *				

<sup>\*1:</sup> Contact your local OMRON representative for fleets larger than 100.

Note: The PC/IPC/Server is supplied by the user.

#### **Charging Station**

Maximum Current	16 A		
Input Voltage	200 to 240 VAC, 50/60 Hz, single phase		
Output Voltage	15 VDC to 60 VDC (28 VDC nominal)		
Power Consumption	3.3 kW		
<b>Maximum Output Current</b>	60 A		
Humidity	0 to 95% non-condensing		
Charging Method	Wireless (primary), wired (secondary)		
Ambient Operating Temperature	-10 to 40°C		
Storage Temperature	-20 to 55°C		
Ingress Protection	Stationary Electronics: IP20		
Ingress Protection	Stationary Coil: IP68		
Altitude	2000 m maximum		
Pollution Degree	1		
<b>Equipment Class</b>	Class A		
Weight	Stationary Electronics 5.9 kg Stationary Coil 2.8 kg		

#### **Battery**

LiFePO4
25.6 VDC
42 Ah nominal
45 min. (5 hours of operation)*1
Approx. 6000 cycles*2*3
80%
Wireless (primary), wired (secondary)
10 to 40°C
-20 to 60°C
10 to 90% non-condensing
2000 m
IP54
20 kg

<sup>\*1:</sup> Charging time can vary based on battery cell temperature and state of charge to prolong battery life.

#### **Service Charger**

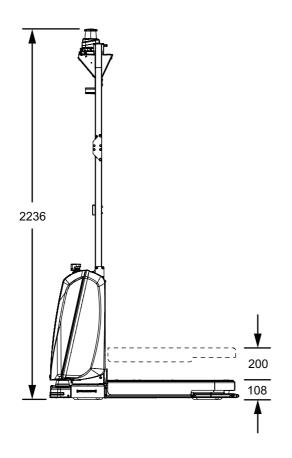
Input Voltage	200 to 240 VAC, 50/60 Hz
Input Current (max.)	2.2 A at 230 VAC
Output Voltage	24 VDC
Output Current	15 A (fused to 20 A)
Ambient Operating Temperature	0 to 35°C
Ingress Protection	IP21
Weight	3.5 kg

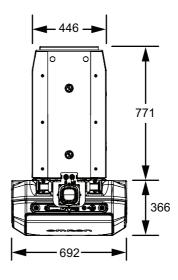
<sup>\*2:</sup> Approximately 80% of nominal battery capacity will be available after using the battery at 100% depth of discharge.

<sup>\*3:</sup> Under the following conditions: Temperature: 15 to 30°C, relative humidity 25% to 85%

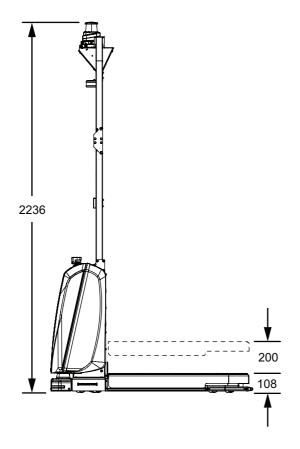
**Dimensions** (Unit: mm)

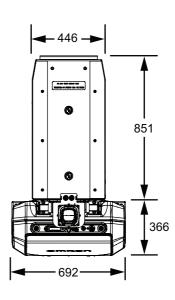
#### OL-450S2



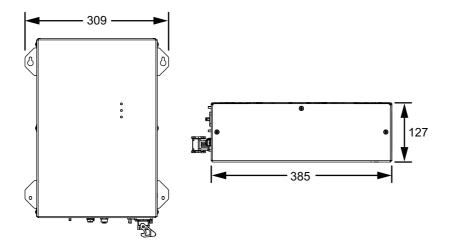


#### OL-450S3

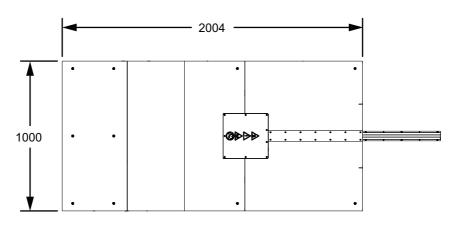




#### **Stationary Electronics Dimensions**



### **Charging Ramp Dimensions**





#### **OL-450S Series**

## **Related Manuals**

Catalog Number	Manual Title
M109	AMR (Autonomous Mobile Robot) OL-series User's Manual
l617	Advanced Robotics Command Language AMR Reference Guide
I618	Advanced Robotics Control Language Fleet Manager AMR Integration Guide
1635	Fleet Operations Workspace Core User's Manual
1636	Fleet Operations Workspace (FLOW) Migration Guide
1637	Fleet Operation Workspace Core Integration Toolkit User's Manual
M107	Fleet Operation Workspace Core Integration Toolkit - MQTT API User's Manual
1665	Fleet Operations Workspace iQ User's Manual
1677	Mobile I/O Box User's Manual
1695	Virtual Fleet Manager Installation Guide

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- · The product photographs and figures that are used in this catalog may vary somewhat from the actual products.

# **Terms and Conditions Agreement**

#### Read and understand this catalog.

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

#### Warranties.

- (a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied.
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See http://www.omron.com/global/ or contact your Omron representative for published information.

#### **Limitation on Liability; Etc.**

OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY.

Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

#### Suitability of Use.

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

#### **Programmable Products.**

Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.

#### Performance Data.

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

#### Change in Specifications.

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

#### **Errors and Omissions.**

Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

Note: Do not use this document to operate the Unit. This document describes AMR functionality supported with FLOW v5.3

Contact: www.ia.omron.com

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