# OMRON

## Connection Guide Integration of 3G3M1 to NX-safety (Hardwired)

## 3G3M1-STD 3G3M1-ECT



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## 1. Introduction

Thank you for using the Connection guide: **Integration of 3G3M1-STD to NX-safety V1.0.2** Use it when programming with the automation software Sysmac Studio.

This manual contains information that is necessary to use the product as is and/or together with Sysmac Studio.

## 1.1. Intended Readers

This manual is intended for the following personnel.

Those who have knowledge of electrical systems (an electrical engineer or the equivalent) and also are qualified for one of the following:

- Personnel in charge of introducing the control equipment
- · Personnel in charge of designing the control systems
- Personnel in charge of installing and maintaining the control equipment
- · Personnel in charge of managing the control systems and facilities

## 1.2. Notice

This manual describes the necessary information to get started with the 3G3M1. Refer also to the following manual's for more information.

| Name  | Catalog<br>No. | Model  | Application  | Description   |
|---|----------------|--|--|---|
| Sysmac Studio Version<br>1 Operation Manual                     | W504           | SYSMACSE2                                    | To learn about how to<br>operate Sysmac<br>Studio and its<br>features. | Describes how to operate Sysmac Studio.   |
| Sysmac Studio Version<br>V1 Drive Functions<br>Operation Manual | 1589           | SYSMACSE2                                    | To learn about how to set and adjust the servo driver.                 | Describes how to operate<br>Sysmac Studio.  |
| 3G3M1 Standard Type<br>User's Manual                            | 1669           | 3G3M1 STD                                    | Multi-function<br>Compact Inverter                                     | Describes the installation/wiring of<br>the 3G3M1 Series Inverter, and<br>parameter setting method which is<br>required for the operation, as well<br>as troubleshooting and inspection<br>methods. |
| 3G3M1 EtherCAT Type<br>User's Manual                            | 1670           | 3G3M1 ECT                                    | Multi-function<br>Compact Inverter                                     | Describes the installation/wiring of<br>the 3G3M1 Series Inverter, and<br>parameter setting method which is<br>required for the operation, as well<br>as troubleshooting and inspection<br>methods. |
| NX-series Safety<br>Control Unit User's<br>Manual               | Z930           | NX-SL[]][][]<br>NX-SI[][][]]<br>NX-SO[][][]] | To learn about how to<br>operate Sysmac<br>Studio and its<br>features  | Describes how to operate and use<br>NX-series Safety Control Units  |

Please read and understand this manual before using the 3G3M1-STD or 3G3M1-ECT or Keep this manual in a safe place where it will be available for reference during operation.

## 1.3. Terms and Conditions Agreement

## 1 NO WARRANTY

- 1) The functions and function block Library is distributed as a sample in the hope that it will be useful, but without any warranty. It is provided "as is" without warranty of any kind, either expressed or implied, including, but not limited to, the implied warranties of merchantability and fitness for a particular purpose. The entire risk as to the quality and performance of the function block is with you. Should the function block prove defective, you assume the cost of all necessary servicing, repair or correction.
- 2) In no event unless required by applicable law the author will be liable to you for damages, including any general, special, incidental or consequential damages arising out of the use or inability to use the function block (including but not limited to loss of data or data being rendered inaccurate or losses sustained by you or third parties or a failure of the function block to operate with any other programs), even if the author has been advised of the possibility of such damages.

#### 2 LIMITATION OF LIABILITY

- 1) OMRON SHALL HAVE NO LIABILITY FOR DEFECT OF THE SOFTWARE.
- 2) OMRON SHALL HAVE NO LIABILITY FOR SOFTWARE PARTS DEVELOPED BY THE USER OR ANY THIRD PARTY USING THE FUNCTION BLOCK DESCRIBED ON THIS MANUAL.

#### **3 APPLICABLE CONDITIONS**

USER SHALL NOT USE THE SOFTWARE FOR THE PURPOSE THAT IS NOT PROVIDED IN THE ATTACHED USER MANUAL.

#### **4 CHANGE IN SPECIFICATION**

The software specifications and accessories may be changed at any time based on improvements and other reasons.

#### 5 ERRORS AND OMISSIONS

The information in this manual has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

## 1.4. Safety Precautions

#### Definition of Precautionary Information

The following notation is used in this manual to provide precautions required to ensure safe usage of 3G3M1 Standard Type.

The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions.

The following notation is used.

|           | Indicates a potentially hazardous situation which, if not<br>avoided, could result in death or serious injury. Additionally,<br>there may be severe property damage. |
|-----------|--|
| A Caution | Indicates a potentially hazardous situation which, if not<br>avoided, may result in minor or moderate injury, or property<br>damage.                                 |



#### Precautions for Safe Use

Indicates precautions on what to do and what not to do to ensure safe usage of the product.



#### Precautions for Correct Use

Indicates precautions on what to do and what not to do to ensure proper operation and performance.



### Additional Information

Additional information to read as required. This information is provided to increase understanding or make operation easier.

#### **Explanation of Symbols**

| $\bigcirc$ | $\odot$ This symbol indicates a prohibited item (an item you must not do).<br>The specific instruction is indicated using an illustration or text inside or near $\odot$ .<br>The symbol shown to the left indicates "non-specific general prohibitions." |
|------------|---|
|            | $\odot$ This symbol indicates a prohibited item (an item you must not do).<br>The specific instruction is indicated using an illustration or text inside or near $\odot$ .<br>The symbol shown to the left indicates "disassembly prohibited."            |
|            | $\Delta$ This symbol indicates caution and warning.<br>The specific instruction is indicated using an illustration or text inside or near $\Delta$ .<br>The symbol shown to the left indicates "Caution against electric shock."                          |
|            | $\Delta$ This symbol indicates caution and warning.<br>The specific instruction is indicated using an illustration or text inside or near $\Delta$ .<br>The symbol shown to the left indicates "Caution against fire."                                    |

| $\underline{\mathbb{N}}$ | $\Delta$ This symbol indicates caution and warning.<br>The specific instruction is indicated using an illustration or text inside or near $\Delta$ .<br>The symbol shown to the left indicates "general caution."                   |
|--------------------------|---|
|                          | $\Delta$ This symbol indicates caution and warning.<br>The specific instruction is indicated inside $\Delta$ as well as by using text.<br>The symbol shown to the left indicates "risk of hot surface."                             |
| 0                        | This symbol indicates a compulsory item (an item that must be done).<br>The specific instruction is indicated using an illustration or text inside or near .<br>The symbol shown to the left indicates a "general compulsory item." |
|                          | ● This symbol indicates a compulsory item (an item that must be done).<br>The specific instruction is indicated inside ● as well as by using text.<br>The symbol shown to the left indicates "grounding required."                  |

## Warning list

|   | Indicates a potentially hazardous situation which, if not  | avoided.           |
|---|--|--------------------|
| WARNING could result in death or serious injury. Additionally, there may be severe property damage. |  |                    |
|   | inal of the inverter. (200-V class: type-D grounding, 400- |                    |
| V class: type-C grounding) Not doin shock or fire.  | g so may result in a serious injury due to an electric     | A                  |
|   | uring inverter power supply and for 10 minutes after       | Δ                  |
| power shut off.   |  | 14                 |
| Doing so may result in a serious inju   | ury due to an electric shock.                              |                    |
| Switch various switches, change wit   | ring and perform inspections at least 10 minutes after     |                    |
| the power supply has been shut off  |  |                    |
| There is a risk of severe injury due t  | to electric shock.   |                    |
| Wiring work must be carried out or  | nly by qualified personnel. Do not touch cables when the   | 14                 |
| 1   | nally, only designated personnel should perform            |                    |
| maintenance or inspections, or repl   | lace parts.  |                    |
| There is a risk of severe injury due t  |  | A                  |
|   | pply is OFF, wait at least 10 minutes and then perform     | $\sqrt{7}$         |
| wiring.   |  |                    |
|   | itches with wet hands. Also, remove metal objects          | A                  |
|   | g work, and use insulating tools when using tools.         | $\sqrt{7}$         |
| Not doing so may result in a serious  | s injury due to an electric shock.                         |                    |
|   | ng resistors and the motor, which become too hot           |                    |
| during  |  |                    |
| the power supply and for some tim   | e after the power shut off.                                |                    |
| Doing so may result in a burn.  | conducted after the neuror supply uses turned off          | •                  |
| Not doing so may result in a serious  | conducted after the power supply was turned off.           |                    |
|   | sarily shut off even if the safety stop function is        |                    |
| activated.  | source stop runction is                                    |                    |
| There is a risk of severe injury.   |  | Λ                  |
| Do not enter the operating area du  | ring operation.  | /!\                |
|   |  |                    |
| There is a risk of severe injury due t  | o electric shock.  |                    |
| Do not perform maintenance while  |  | 14                 |
|   |  |                    |
|   |  |                    |
| Although this product is manufactu  | red under strict quality control, install equipment to     |                    |
| ensure safety when used with appli  | ications in which serious accidents or property damage     | $\sum$             |
| can be anticipated in the event of it   |  |                    |
| Not doing so may result in accident   |  |                    |
|   | er (3G3M1 Series) is designed to drive a three-phase       | $\mathbf{\Lambda}$ |
|   | notor. Do not use it for single-phase motors or for other  | $\sim$             |
| purposes.   | ant l  |                    |
| Doing so may result in fire or accide   | ent.   | 1                  |

| Install the inverter on a non-flammable material such as metallic wall. Also, do not place flammable object nearby.<br>Doing so may result in fire.   |             |
|---|-------------|
| Be sure to perform wiring after installing the inverter unit. Also, tighten terminals with specified torque.<br>Not doing so may result in injury, electric shock or fire.  | $\triangle$ |
| Ensure that the specifications of the input power of the product match the power supply to which the product is to be connected.<br>Not doing so may result in fire or accidents.   | $\triangle$ |
| Be sure to use the wire of specified size.<br>Not doing so may result in fire.  |             |
| When wiring each inverter to the power supply, install a molded-case circuit breaker or<br>earth leakage circuit breaker (with overcurrent protection function). Use recommended<br>molded-case circuit breakers or earth leakage circuit breakers that do not exceed the<br>recommended current capacity.<br>Not doing so may result in fire.  |             |
| If no suitable equipment to detect leakage is installed in the upstream power supply line, in<br>order to avoid the entire power supply system's shutdown due to operation of devices such<br>as earth leakage circuit breaker as this is undesirable to operation, install an earth leakage<br>circuit breaker individually to inverters to break the individual inverter power supply lines<br>only.<br>Not doing so may result in fire.  |             |
| When the capacity of the power transformer is 500 kVA or more and 10 times or more than the rated capacity of the inverter, ensure that a DC reactor is connected.<br>Not doing so may result in fire.  |             |
| Never connect the power lines to the inverter output terminals U, V, or W. Doing so may result in fire.   |             |
| When connecting a braking resistor, do not connect it to any terminal other than terminals P(+) and DB. Doing so may result in fire or accident.  | $\triangle$ |
| Do not bundle multiple cables as one cable.<br>Doing so may result in fire.   |             |
| Do not connect a surge suppressor to the output lines of the inverter.<br>Doing so may result in fire.  |             |
| In general, sheaths of the control signal wires do not use reinforced insulation, therefore if<br>a control signal wire comes into direct contact with a live part of the main circuit, the<br>insulation of the sheath might break down. In these cases, there is a danger of the control<br>signal wire being exposed to high voltage from the main circuit, therefore ensure that the<br>control signal wires will not come into contact with live parts of the main circuit.<br>Not doing so may result in electric shock or accidents. |             |

| Even if the inverter has interrupted power to the motor, if the voltage is applied t<br>main circuit input terminals L1/R, L2/S and L3/T, voltage may be output to inverte<br>terminals U, V and W.<br>This may result in a serious injury due to an electric shock.   |            |
|--|------------|
| Even if the motor is stopped due to DC braking or pre-excitation, voltage is outpu<br>inverter output terminals U, V and W.<br>This may result in a serious injury due to an electric shock.   | t to       |
| Starting auto-tuning involves motor rotation. Sufficiently check that motor rotation with it no danger beforehand.<br>Not doing so may result in injury or accidents.  | on carries |
| The inverter may operate with acceleration/deceleration time or speed different set due to stall prevention function. Design the machine so that safety is ensured such cases.<br>Not doing so may result in accidents.  |            |
| The inverter can easily have high-speed operation set. When changing the speed carefully check the specifications of motors or machine beforehand.<br>Additionally, set the parameters only after fully understanding the User's Manual user recklessly changes the parameters and then operates the inverter, the moto rotate at a torque or speed not permitted for the machine.<br>This may result in injury.           | I. If the  |
| If you enable the "Restart mode after momentary power failure" (F014 = 3 or 4), inverter automatically restarts running the motor when the power is recovered. I machine so that safety is ensured even after such restarts.<br>Not doing so may result in injury or accidents.  |            |
| The STOP key on the Operator may be disabled due to parameter setting, etc. Pro<br>emergency stop switch separately.<br>Not doing so may result in accidents.  | ovide an   |
| If the motor stops as a result of a trip, the inverter may automatically restart and<br>motor depending on the parameter setting. Design the machine so that human sa<br>the safety of surroundings is ensured at the time of restarting.<br>Not doing so may result in accidents.   |            |
| Remove any cause of the protective functions operating, then check the RUN con<br>OFF and cancel the alarm. Canceling the alarm when the RUN command is ON me<br>the inverter will supply power to the motor, which may start rotation thus posing<br>This may result in accidents.  | eans that  |
| When switching start methods or speed by external input, the motor may start su<br>the speed may abruptly change.<br>This may result in injury or accidents.   | uddenly or |
| Input terminals have functions such as run, stop and speed change. If the parame<br>changed while signals are input to the input terminals, the motor operation may<br>change. Ensure that you change parameters only after fully securing safety.<br>Not doing so may result in injury or accidents.  |            |
| The branch circuit protection being open may indicate an interruption in the fault<br>In order to reduce the danger of fire and electric shock, inspect energized parts and<br>controller components, and replace if damaged.<br>In the event of the overload relay current element burning out, the entire overload<br>must be replaced.<br>Not doing so may result in a serious injury due to an electric shock or fire. | nd other   |
|  | 1          |

| Output terminals (ROA, ROB) use relays, and may remain ON, OFF or undetermined when their lifetime is reached. For safety, equip the inverter with an external protective function. Not doing so may result in fire or accidents.  | $\underline{\mathbb{N}}$ |
|--|--------------------------|
| Do not dismantle, repair or modify the product.<br>Doing so may result in injury or electric shock.  |                          |
| Always carry out the daily and periodic inspections described in the User's Manual. Use<br>other inverter for long periods of time without carrying out regular inspections could result<br>in malfunction or damage of the inverter, and an accident or fire could occur.<br>This may result in fire or accident.   |                          |
| It is recommended that parts for periodic replacement be replaced in accordance with the standard replacement frequency indicated in the User's manual. Use of the inverter for long periods of time without replacement could result in malfunction or damage of the inverter, and an accident or fire could occur.<br>This may result in fire or accident.           |                          |
| It is recommended that periodic inspections be carried out every one to two years,<br>however, they should be carried out more frequently depending on the usage conditions.<br>Not doing so may result in fire or accident.   | $\triangle$              |
| When using a DC reactor, AC reactor, braking resistor or noise filter, etc., there is the possibility that a human body may touch the main circuit terminal block (live parts). In such cases, take measures such as installing the inverters in an location not easily accessible by humans.<br>Not doing so may result in a serious injury due to an electric shock. |                          |
| There are conditions for compliance with the EU Low Voltage Directive and Machinery<br>Directive. Strictly observe the conditions listed in the instruction manual or user's manual.<br>Not doing so may result in a serious injury due to an electric shock or fire.  | $\land$                  |

## **Caution list**

| $\wedge$ | Caution |
|----------|---------|
|----------|---------|

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

| If connecting a commercially available braking resistor or regenerative braking unit, this may result in a moderate burn due to the heat generated in the braking resistor or regenerative braking unit.<br>In case of a braking resistor, install a thermal relay that monitors the temperature of the resistor. Configure a sequence that enables the inverter power to turn OFF when unusual over heating is detected in the braking resistor or regenerative braking unit. |            |
|--|------------|
| The inverter has high voltage parts inside which, if short-circuited, might cause damage<br>to itself or other property.<br>Place covers on the openings or take other precautions to make sure that no metal<br>objects such as cutting bits or lead wire scraps go inside when installing and wiring.  |            |
| Install a stop motion device to ensure safety. Not doing so might result in a minor injury.<br>(A holding brake is not a stop motion device designed to ensure safety.)<br>Be sure to confirm safety before conducting maintenance, inspection or parts  |            |
| replacement.   |            |
| A breakdown of the built-in braking transistor could result in braking resistor heating or<br>damage to the inverter's internal units. Shut off the main power of the inverter using<br>Braking transistor broken signal (DBAL).   |            |
| A breakdown of the built-in braking transistor or misconnection of the braking resistor<br>could result in braking resistor heating or damage to the inverter's internal units.<br>If the inverter does not start up or continue being undervoltage (LU) after the main<br>power of the inverter is turned ON, shut off the main power of the inverter.  |            |
| When installing the product, use only the specified screws.<br>Not doing so may result in fire or accidents.   |            |
| Do not install or operate an inverter with damaged external or internal components.<br>Doing so may result in injury, fire or accidents.   | $\bigcirc$ |
| Prevent lint, paper fibers, sawdust, dust, metallic chips, or other foreign materials from getting into the inverter or from accumulating on the cooling fin. Not doing so may result in fire or accidents.  |            |
| Support the inverter case or cooling fin instead of the surface cover during transportation.<br>Not doing so may result in injury due to the inverter dropping.  |            |
| The inverter, motor and wiring generate electric noise. Be careful about malfunction of<br>the nearby sensors and devices. Take noise control measures to prevent them from<br>malfunctioning.<br>Not doing so may result in accidents.  |            |
| The inverter has an overload protection function. Set the protection level using parameters.   |            |

| The brake function of the inverter does not provide any holding mechanism. Provide a separate holding brake if necessary.<br>Not doing so may result in injury.                     | 0           |
|---|-------------|
| Comply with the local ordinance and regulations when disposing of the product.<br>Not doing so may result in injury.  | 0           |
| UL and cUL compliance is subject to conditions. Strictly observe the conditions listed in the instruction manual or user's manual.<br>Not doing so may result in fire or accidents. | $\triangle$ |

## 1.5. Change Log

| Revision | Date          | Correction   |  |
|----------|---------------|--|--|
| 1.0.0    | December 2022 | Original   |  |
| 1.0.1    | May 2025      | Minor changes in text , added -ECT                 |  |
| 1.0.2    | July 2025     | Minor changes in text, changes of Safety standards |  |
| 1.0.2    | July 2025     |  |  |

## 2. Overview

This document describes the procedure for connecting the 3G3M1-STD or 3G3M1-ECT to a NX-series safety master via the EDM signal from 3G3M1 inverter and provides the quick setup procedure.

## 3.

## **Safety Function**

The safety function is designed so that the safety stop functions of category 0 (uncontrolled stop) specified in IEC 60204-1 is used to meet the safety standards of PL-e under ISO 13849-1.

• STO Function by Safety Input Signal



## **Precautions for Correct Use**

The Safety part of the 3G3M1 is only working when the main power is ON. If the drive is powered by an external 24vdc power supply the safety part is not active.

## 3.1. Safety

| Function              | Standard         |
|-----------------------|------------------|
| STO (Safe Torque Off) | EN/IEC 61800-5-2 |

## 3.2. Response Time

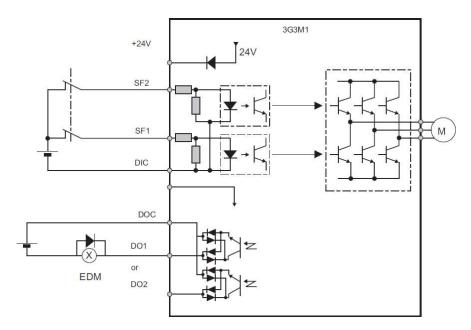
| Response          | ime           | Remarks  |
|-------------------|---------------|--|
| STO response time | 50 ms or less | Time from when the SF1/SF2 signal state changes to |
|                   |               | STO up to when power to the motor is cut off       |
| EDM response time | 50 ms         | Time from when the SF1/SF2 signal state changes to |
|                   |               | STO up to when the EDM signal state changes to ON  |

## 3.3. Safety Related Parameters

| Parameter | Value    | Standard       |
|-----------|----------|----------------|
| PL        | E        | EN/ISO 13849-1 |
| Cat       | 3        |                |
| MTTFd     | >62 year |                |
| DCavg     | Medium   |                |

| Parameter    | Value                   | Standard             |
|--------------|-------------------------|----------------------|
| SIL          | 3                       | EN/IEC 61508-1 to -7 |
| HFT          | 1                       | EN/IEC 61800-5-2     |
| SFF          | >90%                    |                      |
| PFH          | 3.00 × 10 <sup>-9</sup> |                      |
| PFD          | 2.00 × 10 <sup>-5</sup> |                      |
| Mission time | 20 years                |                      |

**3.4. Wiring** Wiring example when EDM is enabled (for compliance with ISO13849-1 PL-e)

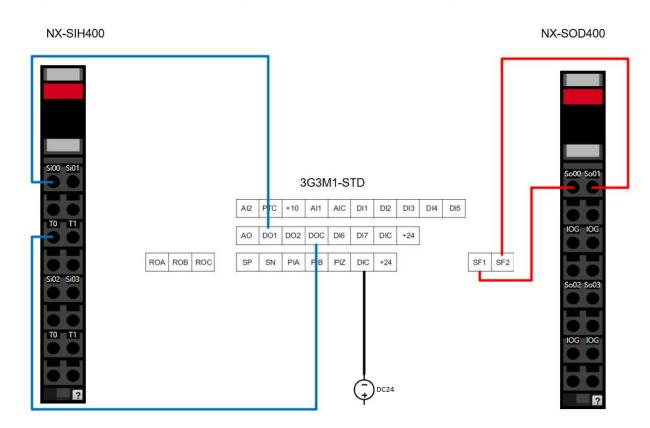


## Setup 3G3M1 and NX Safety

## 4.1. Wiring between 3G3M1 and NX safety I/O

4.

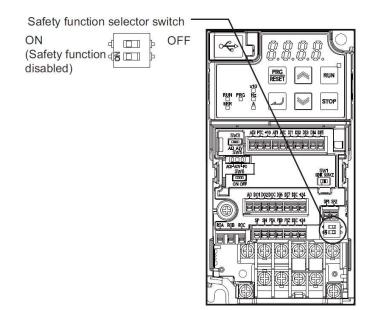
Wiring between 3G3M1 and NX safety units with common power supply



The safety controller in our case is connected on a NX-ECC203 that is powered by +24Vdc, that means the 3G3M1 needs a reference -0Vdc from the same power source. The -0Vdc is connected to the DIC terminal.

## 4.1. 3G3M1-STD Safety Function Settings

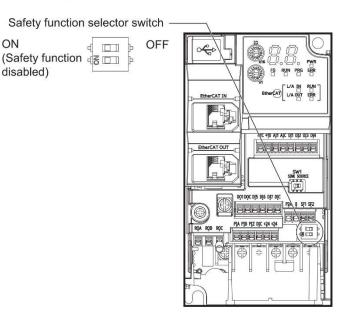
Turn OFF the safety function selector switch SW9 when the inverter power supply is turned OFF. Set SW9 to enabled (OFF) or disabled (ON) so that both sides are at the same position at all times.



## 4.1. 3G3M1-ECT Safety Function Input Signal Settings

ON

Turn OFF the safety function selector switch SW9 when the inverter power supply is turned OFF. Set SW9 to enabled (OFF) or disabled (ON) so that both sides are at the same position at all times. This is to disable or enable the physical terminals of STO on the 3G3M1-ECT. Nothing that we



To activate Safety hardwired on 3G3M1, change both switches on SW9 to OFF (Right), like picture below.



## 4.2. Parameter setup 3G3M1

Setup parameter E20 for the D01 output to be assigned to the EDM (External Device Monitoring) function.

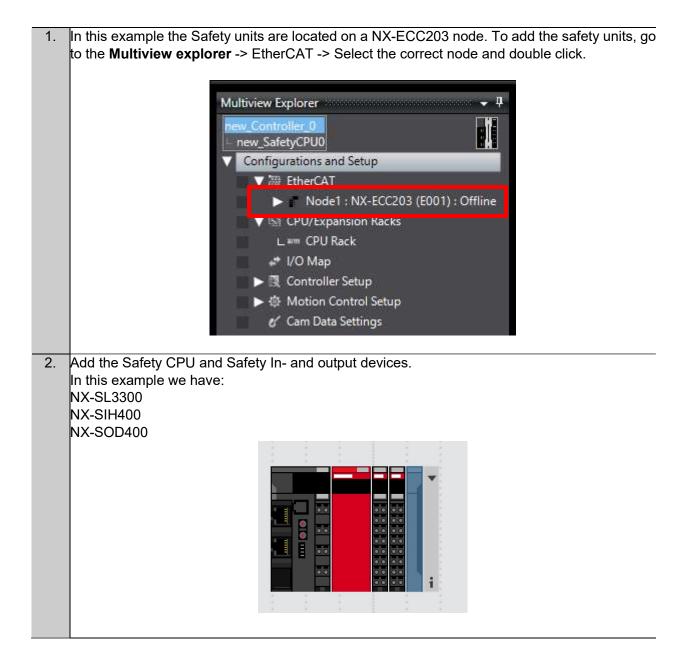
| Parameter | Function name                                  | Data   | Default settings |
|-----------|--|--|------------------|
| E20       | Output Terminal<br>[DO1]<br>Function Selection | 101: DECF (EN circuit failure detected)<br>102: EDM (Safety monitor) | -                |

## Sysmac Studio – Configuration and setup

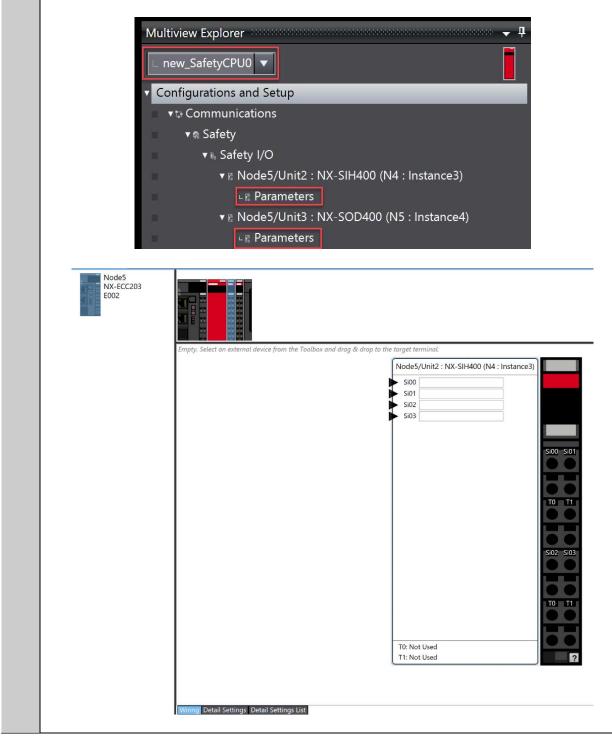
## 5.1. Selecting a Safety CPU and Safety Input and Output devices

5.

This example will demonstrate how to add a double channel mechanical E-stop together with a reset button.



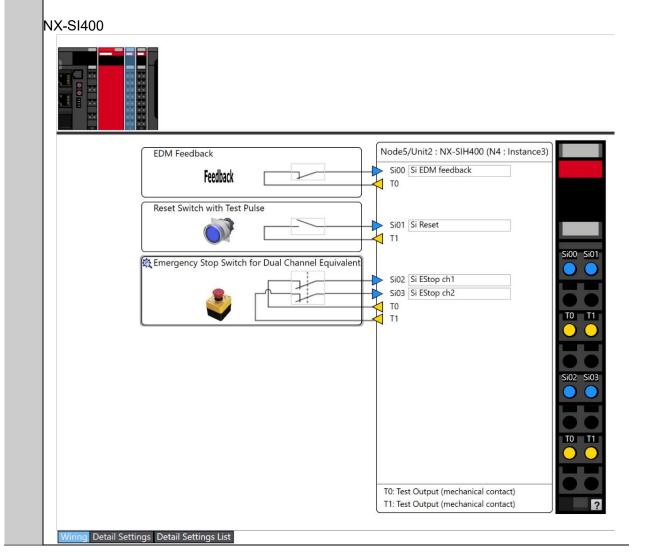
3. Select the Safety CPU in the dropdown list -> Go to the **Parameters** section (Safety -> Safety I/O – Select a node)

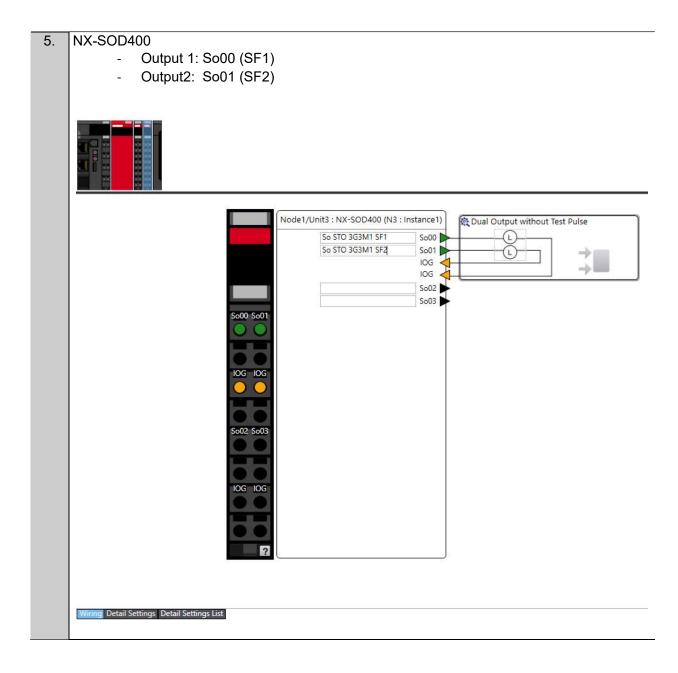


- 4. Use the toolbox to select a safety device -> drag and drop parameter to the triangle knob. In this example we use:
  - EDM Feedback from 3G3M1
  - Reset Switch with Test Pulse
  - Emergency Stop Switch for Dual Channel Equivalent.



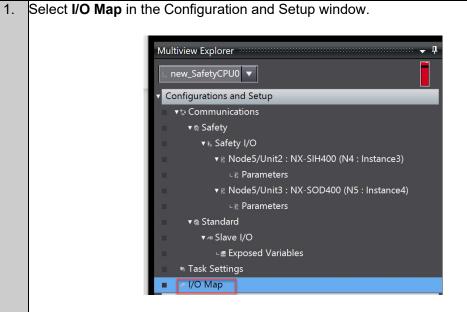
Select a unique comment on Safety Input and Safey Output (or wait until I/O Map)





## 5.2. I/O Map

Map the safety variables for the Safety part.



2. Enter unique variable names manually or right click and generate name. Comment is same text shown on each card in Parameter Setup.

| Position |     | Port                          | R/W | Data Type | Variable  | Variable Comment | Variable Typ   |
|----------|-----|-------------------------------|-----|-----------|-----------|------------------|----------------|
|          | V . | CPU/Expansion Racks           |     |           |           |                  |                |
| NXBusMa: |     | NX102-9000                    |     |           |           |                  |                |
|          | V 8 | EtherCAT Network              |     |           |           |                  |                |
| EtherCAT |     | Master                        |     |           |           | 1                | 1              |
| Node1/Ur | V   | NX-SIH400                     |     |           |           |                  |                |
|          |     | Safety Inputs and Status      |     |           |           | 111              |                |
|          |     | Si00 Logical Value            | R   | SAFEBOOL  | SI_EDM_M1 | Si EDM feedback  | Global Variabl |
|          |     | Si01 Logical Value            | R   | SAFEBOOL  | SI_Reset  | Si Reset         | Global Variabl |
|          |     | Si02 Logical Value            | R   | SAFEBOOL  | SI_ESTOP  | Si Estop ch1     | Global Variabl |
|          |     | Si03 Logical Value            | R   | SAFEBOOL  |           | Si Estop ch2     |                |
|          |     | Safety Connection Status      | R   | SAFEBOOL  | 9         |                  |                |
|          |     | Safety Input Terminal Status  | R   | SAFEBOOL  |           |                  |                |
| Node1/Ur | T   | NX-SOD400                     |     |           |           |                  |                |
|          |     | ▼ Status                      |     |           |           |                  |                |
|          |     | Safety Connection Status      | R   | SAFEBOOL  |           |                  |                |
|          |     | Safety Output Terminal Status | R   | SAFEBOOL  |           |                  |                |
|          |     | ▼ Safety Outputs              |     |           |           |                  |                |
|          |     | So00 Output Value             | w   | SAFEBOOL  | SO_STO_M1 | So STO 3G3M1 SF1 | Global Variabl |
|          |     | So01 Output Value             | w   | SAFEBOOL  |           | So STO 3G3M1 SF2 |                |
|          |     | So02 Output Value             | w   | SAFEBOOL  |           |                  |                |
|          |     | So03 Output Value             | W   | SAFEBOOL  |           | <i>n</i> <       |                |

### Precautions for Correct Use

内

Do not enter a variable name for the second input or output of dual channel devices. Sysmac Studio handles the dual channel as one variable.

## 5.3. Program

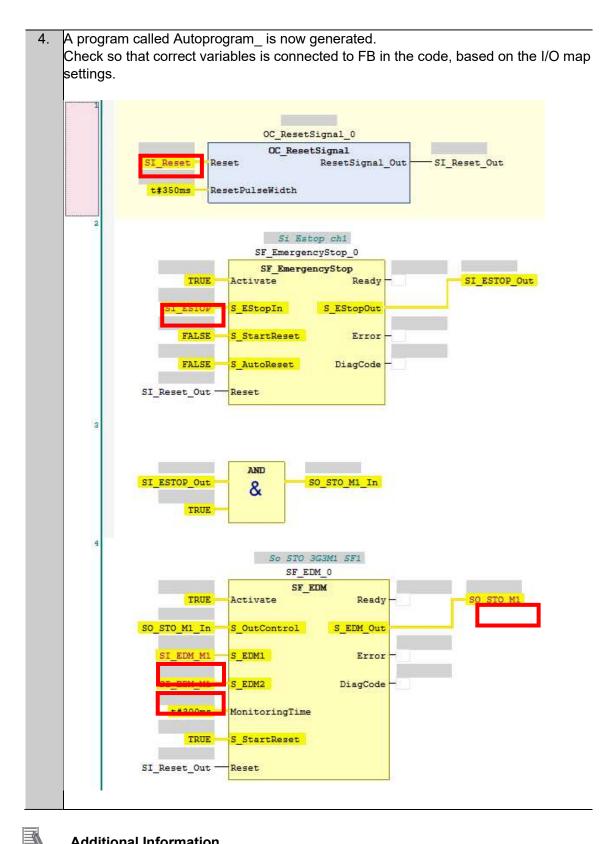
Program can be made from scratch but in this program example will be created using automatically programming feature, inside of Sysmac Studio.

| 1. | To automatically generate a safety program right-click on the Programs and select <b>Automatic programming function</b> |
|----|---|
|    |   |
|    | Multiview Explorer  |
|    | □ new_SafetyCPU0 ▼  |
|    | ✓ Configurations and Setup  |
|    | ▼ Communications  |
|    | v ⊚ Safety  |
|    | ▼ № Safety I/O  |
|    | ▼ 🖻 Node5/Unit2 : NX-SIH400 (N4 : Instance3)  |
|    | ା ଅ Parameters  |
|    | ► 🖻 Node5/Unit3 : NX-SOD400 (N5 : Instance4)  |
|    | ▼ @ Standard  |
|    | ▼⊲ Slave I/O  |
|    | ⊾   |
|    | Task Settings   |
|    | * I/O Map   |
|    | Programming   |
|    | v∎ POUs   |
|    | Add   |
|    | Li≋ Function Bl Paste   |
|    |   |
|    | Automatic Programming   |
|    | s Safety Task   |
|    |   |
| 2. | Register variables that are assigned to a safety In- or Output device.  |
|    |   |
|    | Automatic Programming X   |
|    |   |
|    |   |
|    | Generate Register Variables   |
|    |   |
|    |   |
|    | Automatic Programming   |
|    | Automatic Programming X   |
|    |   |
|    | Variables are registered to the Input and Output Settings.  |
|    | Please select the registration target from the following options.   |
|    |   |
|    | Only device variables that assigned an input device or output   |
|    | O device in Safety Slave Unit Parameters or Connection Settings of  |
|    | the originator.   |
|    | All global variables (SAFEBOOL only)  |
|    |   |
|    | If the variable with the same name is already registered, do not overwrite  |
|    | the settings for that variable.   |
|    |   |
|    | OK Cancel   |
|    |   |
|    |   |
|    |   |

## 3.

Select Reset signal After register all safety variables, it is time to Generate the code.

| Reset Signal SI      | Reset    |                           |                              |                                    |
|----------------------|----------|---------------------------|------------------------------|------------------------------------|
| ▼ Input Settings     |          |                           |                              |                                    |
| No. 1<br>1 SI_ESTOP  | Variable | I Comment<br>Si Estop ch1 | Reset Type  <br>Manual SF_Em | Function Block Name<br>argencyStop |
|                      |          | -                         |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
| <u> </u>             |          |                           |                              |                                    |
| ▼ Output Settings    |          |                           |                              |                                    |
| No. 1<br>1 SO_STO_M1 | Variable | So STO 3G3M1 SF1          | I Use EDM I<br>TRUE          |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |
|                      |          |                           |                              |                                    |



## Additional Information

The Safety program is just an example and is created by the Automatic programming function in Sysmac studio. For further details about how to setup and program the NX-SL[][][]] Safety controller please refer to NX Safety Controller (Cat. No. Z930) and the NX Safety Instructions Reference Manual (Cat. No. Z931)