

SERVOSISTEMA SERIE G

Ahorre espacio, ahorre cableado, ahorre tiempo



» Tamaño compacto

» MECHATROLINK-II

» Rendimiento mejorado

Pequeños en tamaño, pero no en características

Teniendo en mente su aplicación, los servodrivés serie G le ofrecen funciones adicionales para el desarrollo de sus máquinas con una mayor rapidez, flexibilidad y eficacia.

Entre las nuevas funciones se incluyen una mejor respuesta de velocidad, una gama más amplia de servomotores y un auto-tuning rápido e intuitivo. Todo ello los hace perfectos para muchas aplicaciones y siempre con la calidad y servicio de asistencia que caracterizan a Omron.

Características principales y beneficios:

- Servosistema ultracompacto con unas dimensiones mínimas: 15 x 4 cm
- Auto-tuning para una puesta en marcha rápida y sencilla
- Bus de motion integrado MECHATROLINK-II que reduce el cableado y permite la configuración y diagnóstico remotos de los servosistemas
- Par de arranque elevado: 300% durante 3 segs.
- Control de posición, velocidad y par
- Fuente de alimentación de potencia y control independientes
- Posicionado rápido y preciso
- Gama de servomotor desde 50 W hasta 1,5 kW
- Encoder incremental y absoluto
- Servomotores cilíndricos y planos de hasta 3.000 rpm
- Compatible con servomotores SmartStep 2
- Supresión de vibraciones

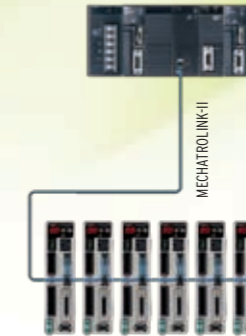


Ahorre espacio, ahorre cableado, ahorre tiempo

De varios cables...

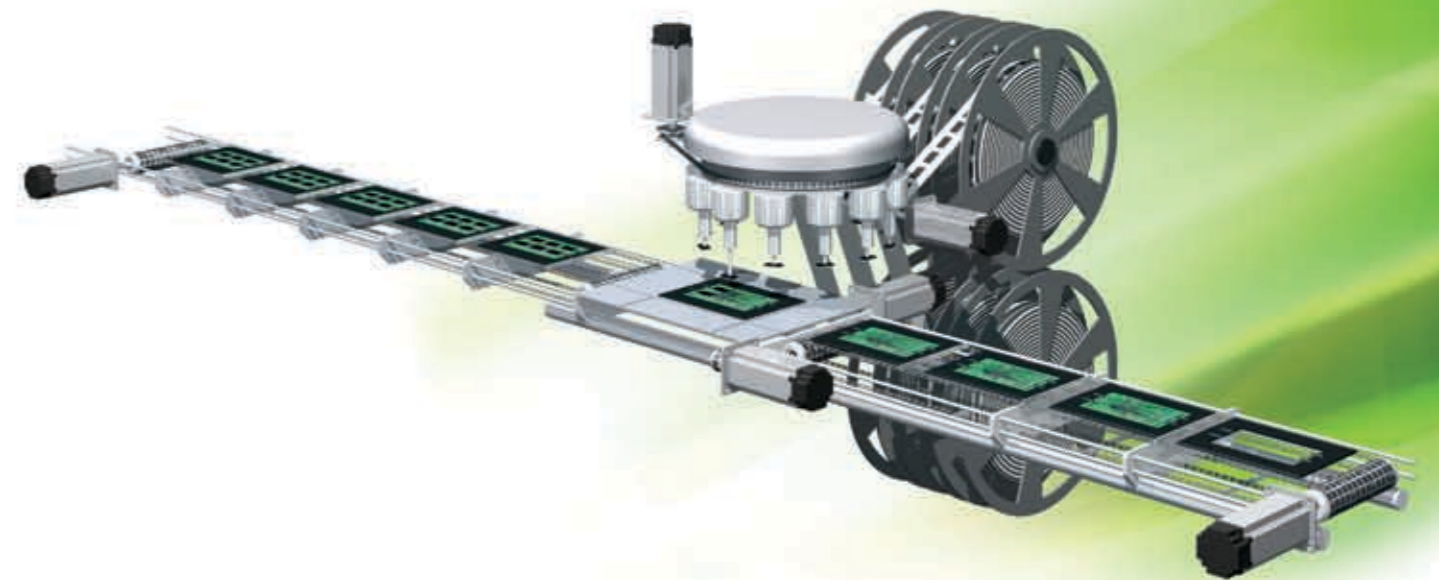


a un único cable



Conexión sencilla: un único cable

Gracias al bus de motion integrado MECHATROLINK-II, le bastará con un solo cable para conectar varios servos. La ventaja no reside solamente en el ahorro de cableado y tiempo de instalación, sino también en la reducción de los posibles errores de conexión. También obtiene una fiabilidad aún mayor, ya que la conexión a través de un único cable resulta mucho más segura que una solución de cableado múltiple.



Auto-tuning rápido y sencillo

En los gráficos se muestra el perfil de movimiento con un servosistema serie G en una aplicación con un coeficiente de inercia de 16:1. El ajuste se realiza de forma sencilla por medio del CX-Drive y sólo tarda un minuto en completarse.

El resultado es un control extraordinario que garantiza que el servosistema y, por lo tanto, la máquina funcionen de forma óptima sin apenas requerir conocimientos por parte del usuario.

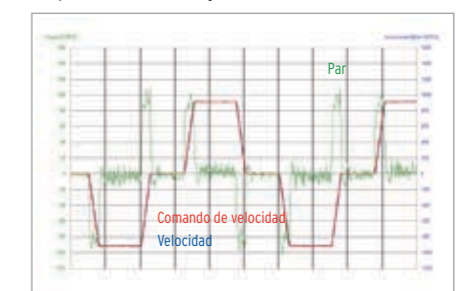
Una vez en funcionamiento, la función integrada de auto-tuning en tiempo real se ocupa de los posibles cambios de la inercia de la carga, garantizando la calidad de fabricación de la pieza.

Además, hay disponibles numerosos filtros notch y de supresión para eliminar las vibraciones de la máquina independientemente de su dirección.

Antes del auto-tuning



Después del auto-tuning



G-Series y NCF: posicionado óptimo para un máximo de 16 ejes por tarjeta

Sistema de posicionado completo y compacto

En un espacio mínimo puede disponer de un sistema PTP completo y potente combinando la unidad CJ1W-NCF71 y el servo de la serie G. Esta configuración ofrece un posicionado de 16 ejes con interpolación lineal y circular, además de función de interrupt feeding. El sistema NCF y la serie G ofrecen la solución ideal para aplicaciones en las que el espacio es crítico.

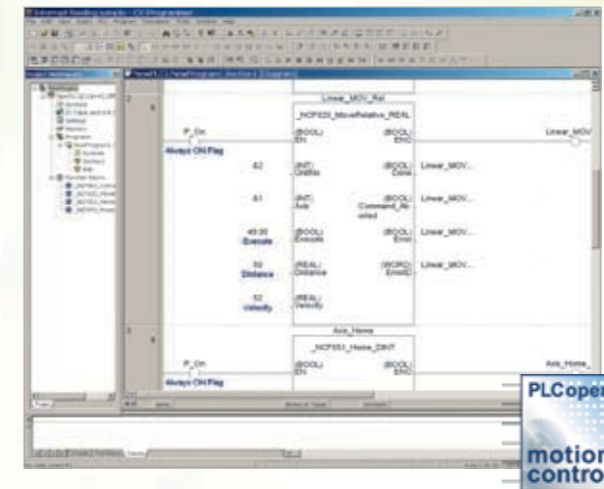
Transparencia total desde un host remoto

Cuando la serie G se controla mediante una unidad de posicionado NCF, el servodrive es totalmente transparente para un PC remoto. Esto se consigue conectando un sistema MECHATROLINK-II desde la serie G al PLC y conectando éste al PC mediante un puerto serie o Ethernet, lo que lo hace totalmente compatible con el Smart Platform de Omron.



PLCopen

PLCopen, estándar mundial para la programación del control industrial, proporciona una interfaz de programación estándar para armonizar los métodos de diseño y funcionamiento de sistemas de control industrial.



NCF: características principales y otras ventajas

- 16 ejes, posicionado punto a punto mediante ML II
- Capacidad de ampliación y flexibilidad del sistema con modelos de 2, 4 y 16 ejes
- Configuración rápida, sencilla y fiable
- Optimizado para aplicaciones de posicionado
- Cableado simplificado
- Integración con Smart Platform de Omron

CJ1W-NC271 CJ1W-NC471 CJ1W-NCF71



2 ejes 4 ejes 16 ejes



Hasta 16 ejes

R88D-GN□/R88M-G□

G-Series servo system

Compact in size big in features. Save space, save wiring, save time

- Built-in MECHATROLINK-II motion bus
- Position, speed and torque control
- High-response frequency of 1 kHz
- Real time auto-tuning
- Vibration suppression
- Separate power and control power supply
- Available motors with absolute and incremental with 17-bit encoder for greater accuracy
- Cylindrical and flat servo motors up to 3000 rpm
- Servomotors supported by SmartStep2, G-Series and G5-Series servo drives
- Peak torque 300% of continuous torque during 3 seconds or more depending on model
- IP65 and shaft oil seal available



Ratings

- 230 VAC single-phase 100 W to 1.5 kW (8.62 Nm)

System configuration



Servo drive type designation

Servo drive

R88D-GN04H-ML2

G-Series servo drive

N: Network type

Capacity

01	100 W
02	200 W
04	400 W
08	750 W
10	1.0 kW
15	1.5 kW

Model

ML2: MECHATROLINK-II communications

Source voltage

H: 230 V

Servo drive specifications

G-Series servo drive

Servo drive type		R88D-GN□	01H-ML2	02H-ML2	04H-ML2	08H-ML2	10H-ML2	15H-ML2
Applicable servomotor		R88M-G□	05030□/10030□	20030□	40030□	75030□	G1K020T□	90010T□/1K030T□/ 1K5□0T□
		R88M-GP□	10030□	20030□	40030□	-	-	-
Basic specifications	Max. applicable motor capacity	W	100	200	400	750	1000	1500
	Continuous output current	Arms	1.16	1.6	2.7	4.0	5.9	9.8
	Max. output current	Arms	3.5	5.3	7.1	14.1	21.2	28.3
	Input power	Main circuit	For single-phase, 200 to 240 VAC +10 to -15% (50/60 Hz)			For single-phase/ three-phase, 200 to 240 VAC +10 to -15% (50/60 Hz)		
	Supply	Control circuit	For single-phase, 200 to 240 VAC +10 to -15% (50/60 Hz)					
	Control method		IGBT-driven PWM method					
	Feedback		Serial encoder (incremental/absolute)					
	Conditions	Usage/storage temperature	0 to +55 °C / -20 to 65 °C					
		Usage/storage humidity	90% RH or less (non-condensing)					
		Altitude	1000m or less above sea level					
Vibration/shock resistance		5.88 m/s ² / 19.6 m/s ²						
Configuration		Base mounted						
Approx. weight	Kg		0.8	1.1	1.5		1.7	
Performance	Speed control range	1:5000						
	Speed variance	Load variance	During 0 to 100% load ±0.01 max. (at rated speed)					
		Voltage variance	0% at ±10% of rated voltage (at rated speed)					
		Temperature variance	0 to 50°C ±0.1% max. (at rated speed)					
	Frequency characteristics	1 kHz						
Torque control accuracy (reproducibility)	±3% (at 20% to 100% of rated torque)							
Soft start time setting	0 to 10 s (acceleration time and deceleration time can be set)							
Command Input	MECHATROLINK Communication	MECHATROLINK-II commands (for sequence, motion, data setting/reference, monitor, adjustment and other commands)						
	I/O signal	Sequence input signal	Emergency stop, 3 external latch signals, forward/reverse torque limit, forward/reverse run prohibit, origin proximity, 3 general-purpose inputs					
		Sequence output signal	It is possible to output three types of signals: positioning completed, speed coincidence, rotation speed detection, servo ready, current limit, speed limit, brake release and warning signal					

Servo drive type		R88D-GN□	01H-ML2	02H-ML2	04H-ML2	08H-ML2	10H-ML2	15H-ML2
Applicable servomotor		R88M-G□	05030□/10030□	20030□	40030□	75030□	G1K020T□	90010T□/1K030T□/ 1K5□0T□
		R88M-GP□	10030□	20030□	40030□	-	-	-
Communications	RS-232 communications	Interface	Personal computer					
		Transmission rate	From 2400 to 57600 bps					
		Functions	Parameter setting, status display, alarm display (monitor, clear, history), servo drive data tracing function, test run/autotuning operations, real time trace, absolute encoder setting, default values function					
	MECHATROLINK communications	Communications protocol	MECHATROLINK-II					
		Transmission rate	10 Mbps					
		Data length	32 bytes					
		Functions	Parameter setting, status display, alarm display (monitor, clear, history), default values function					
	Integrated functions	Automatic load inertia detection	Horizontal and vertical axis mode. One parameter rigidity setting.					
		Dynamic brake (DB)	Operates when main power OFF, servo alarm, overtravel or servo OFF					
		Regenerative processing	Built-in regeneration resistor in models from 750 W to 1.5 kW. External regeneration resistor optionally.					
Overtravel (OT) prevention function		Dynamic brake, disables torque or emergency stop torque during POT and NOT operation						
Emergency stop (STOP)		Emergency stop input						
Encoder divider function		Optional division pulses possible						
Electronic gearing		0,01<Numerator/Denominator<100						
Internal speed setting function		8 internal speeds						
Protective functions		Overvoltage, undervoltage, overcurrent, overload, regeneration overload, servo drive overheat						
Analog monitor Output		The actual servomotor speed, command speed, torque and number of accumulated pulses can be measured using an oscilloscope or other device.						
Panel operator		Display functions	A 2-digit 7-segment LED display shows the servo drive status, alarm codes, parameters, etc. MECHATROLINK-II communications status LED indicator (COM)					
		Switches	Rotary switch for setting the MECHATROLINK-II node address					

Servo drive part names



Dimensions

Servo drives

R88D-GN01H-ML2 / GN02H-ML2 (200 V, 100 to 200 W)



R88D-GN04H-ML2 (200 V, 400 W)



R88D-GN08H-ML2 (200 V, 750 W)



R88D-GN10H-ML2 / GN15H-ML2 (200 V, 1 kW to 1,5 kW)



Servo motors type designation

Servo motor

R88M-GP10030H-BOS2

G-Series Servomotor

Motor Type

- Blank: Cylinder type
- P: Flat type

Capacity

050	50 W
100	100 W
200	200 W
400	400 W
750	750 W
900	900 W
1K0	1 kW
1K5	1.5 kW

Rated Speed (r/min)

10	1000
20	2000
30	3000

Shaft end specifications

Blank	Straigh shaft, no key
S2	Straigh, key, tapped

Oil seal specifications

Blank	No oil seal
O	Oil seal

Brake specifications

Blank	No brake
B	Brake

Voltage and encoder specifications

- H: 230 V with incremental encoder
- T: 230 V with absolute encoder

Servo motor specifications

Cylindrical servo motors 3000/2000/1000 r/min

Ratings and specifications

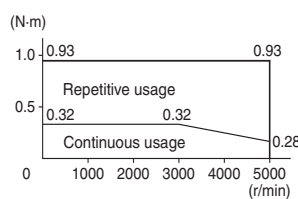
Applied voltage		230 V									
Servo motor model R88M-□		G05030	G10030	G20030	G40030	G75030	G1K030T	G1K530T	G1K020T	G1K520T	G90010T
Rated output	W	50	100	200	400	750	1000	1500	1000	1500	900
Rated torque	N·m	0.16	0.32	0.64	1.3	2.4	3.18	4.77	4.8	7.15	8.62
Instantaneous peak torque	N·m	0.45	0.90	1.78	3.67	7.05	9.1	12.8	13.5	19.6	18.4
Rated current	A (rms)	1.1		1.6	2.6	4	7.2	9.4	5.6	9.4	7.6
Instantaneous max. current	A (rms)	3.4		4.9	7.9	12.1	21.4	28.5	17.1	28.5	17.1
Rated speed	min ⁻¹	3000							2000		1000
Max. speed	min ⁻¹	5000				4500	5000		3000		2000
Torque constant	N·m/A (rms)	0.14	0.19	0.41	0.51	0.64	0.44	0.51	0.88	0.76	1.13
Rotor moment of inertia (JM)	kg·m ² ×10 ⁻⁴	0.025	0.051	0.14	0.26	0.87	1.69	2.59	6.17	11.2	
Allowable load moment of inertia (JL)	Multiple of (JM)	30				20	15		10		
Rated power rate	kW/s	10.4	20.1	30.3	62.5	66	60	88	37.3	45.8	66.3
Applicable Encoder		Incremental encoder (10000 pulses)					-				
		Incremental /Absolute encoder(17 bits)									
Allowable radial load	N	68		245		392		490		686	
Allowable thrust load	N	58		98		147		196			
Approx. mass	Kg (without brake)	0.3	0.5	0.8	1.2	2.3	4.5	5.1	6.8	8.5	
	Kg (with brake)	0.5	0.7	1.3	1.7	3.1	5.1	6.5	8.7	10.1	10
Brake specifications	Rated voltage	24 VDC +/-5%					24 VDC +/-10%				
	Holding brake moment of inertia J	0.002		0.018		0.075	0.25	0.33	1.35		
	Power consumption (at 20°C)	7		9		10	18	19	14	19	
	Current consumption (at 20°C)	0.3		0.36		0.42	0.74	0.81	0.59	0.79	
	Static friction torque	0.29		1.27		2.45	4.9	7.8	4.9	13.7	
	Rise time for holding torque	35		50		70	50		80	100	
Release time	20		15		20	15		70	50		
Basic specifications	Rating	Continuous									
	Insulation grade	Type B					Type F				
	Ambient operating/ storage temperature	0 to +40°C/ -20 to 65°C					0 to +40°C/ -20 to 80°C				
	Ambient operating/ storage humidity	85% RH max. (non-condensing)									
	Vibration class	V-15									
	Insulation resistance	20 MΩ min. at 500 VDC between the power terminals and FG terminal									
	Enclosure	Totally-enclosed, self-cooling, IP65 (excluding shaft opening and lead wire ends)									
	Vibration resistance	Vibration acceleration 49 m/s ²					Vibration acceleration 24.5 m/s ²				
Mounting	Flange-mounted										

Torque-speed characteristics

R88M-G05030H/T (50 W)



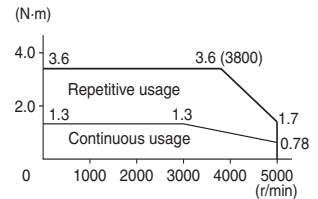
R88M-G10030H/T (100 W)



R88M-G20030H/T (200 W)



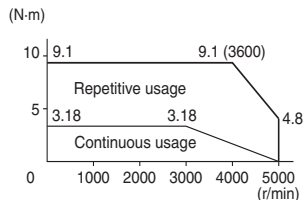
R88M-G40030H/T (400 W)



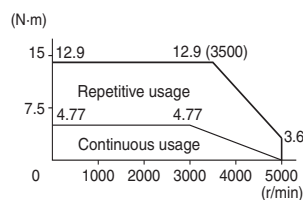
R88M-G75030H/T (750 W)



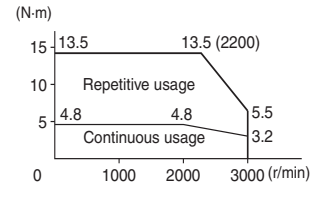
R88M-G1K030T (1 kW)



R88M-G1K530T (1.5 kW)



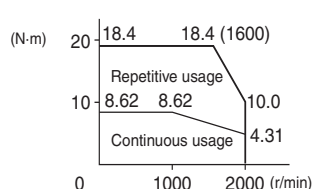
R88M-G1K020T (1 kW)



R88M-G1K520T (1.5 kW)



R88M-G90010T (900 W)



Flat servo motors 3000 r/min

Ratings and specifications

Applied voltage		230 V		
Servo motor model R88M-□		GP10030□	GP20030□	GP40030□
Rated output	W	100	200	400
Rated torque	N·m	0.32	0.64	1.3
Instantaneous peak torque	N·m	0.86	1.8	3.65
Rated current	A (rms)	1	1.6	2.5
Instantaneous max. current	A (rms)	3.1	4.9	7.5
Rated speed	min ⁻¹	3000		
Max. speed	min ⁻¹	5000		
Torque constant	N·m/A (rms)	0.34	0.42	0.54
Rotor moment of inertia (JM)	kg·m ² ×10 ⁻⁴	0.1	0.35	0.64
Allowable load moment of inertia (JL)	Multiple of (JM)	20		
Rated power rate	kW/s	10.2	11.5	25.5
Applicable encoder		Incremental (10000 pulses)		
		Incremental /Absolute encoder(17 bits)		
Allowable radial load	N	68	245	
Allowable thrust load	N	58	98	
Approx. mass	Kg (without brake)	0.7	1.3	1.8
	Kg (with brake)	0.9	2	2.5
Brake specifications	Rated voltage	24VDC +/-10%		
	Holding brake moment of inertia J	kg·m ² ×10 ⁻⁴	0.03	0.09
	Power consumption (at 20°C)	W	7	10
	Current consumption (at 20°C)	A	0.29	0.41
	Static friction torque	N·m (minimum)	0.29	1.27
	Rise time for holding torque	ms (max.)	50	60
	Release time	ms (max)	15	
Basic specifications	Rating	Continuous		
	Insulation grade	Type B		
	Ambient operating/ storage temperature	0 to +40 °C/ -20 to 80°C		
	Ambient operating/ storage humidity	85% RH max. (non-condensing)		
	Vibration class	V-15		
	Insulation resistance	20 MΩ min. at 500 VDC between the power terminals and FG terminal		
	Enclosure	Totally-enclosed, self-cooling, IP65 (excluding shaft opening and lead wire ends)		
	Vibration resistance	Vibration acceleration 49 m/s ²		
Mounting	Flange-mounted			

Torque-speed characteristics

R88M-GP10030H/T (100 W) R88M-GP20030H/T (200 W) R88M-GP40030H/T (400 W)



Dimensions

Servo motors

Cylindrical type 3000 r/min (230 V, 50-100 W)

Dimensions (mm)	Without brake	With brake	LN	Flange surface		Shaft end		Aprox. Mass (Kg)	
	LL	LL		D	S	B	Without brake	With brake	
R88M-G05030□□S2	72	102	26.5	30 ^{h7}	8 ^{h6}	3 ^{h9}	0.3	0.5	
R88M-G10030□□S2	92	122	46.5				0.5	0.7	



Cylindrical type 3000 r/min (230 V, 200-750 W)

Dimensions (mm)	Without brake	With brake	LR	KL1	Flange surface					Shaft end					Aprox. Mass (Kg)		
	LL	LL			D1	D2	C	G	Z	S	QK	B	H	T1	Tap x depth	Without brake	With brake
R88M-G20030□□S2	79.5	116	30	43	70	50 ^{h7}	60	6.5	4.5	11 ^{h6}	18	4 ^{h9}	4	2.5	M4x8L	0.8	1.3
R88M-G40030□□S2	99	135.5			90	70 ^{h7}	80	8		14 ^{h6}	22.5	5 ^{h9}	5	3	M5x10L	1.2	1.7
R88M-G75030□□S2	112.2	149.2	35	53	90	70 ^{h7}	80	8	6	19 ^{h6}	22	6 ^{h9}	6	3.5		2.3	3.1



Cylindrical type 3000, 2000 and 1000 r/min (230 V, 900 kW - 1.5 kW)

Dimensions (mm)	Without brake	With brake	LR	KL1	Flange surface								Shaft end					Aprox. Mass (Kg)		
					D1	D2	D3	C	G	F	Z	S	QK	B	H	T1	Tap x depth	Without brake	With brake	
R88M-G1K030T-□S2	175	200	55	98	100	80 ^{h7}	120	90	7	3	6.6	19 ^{h6}	42	6 ^{h9}	6	3.5	M5x12L	4.5	5.1	
R88M-G1K530T-□S2	180	205		103	115	95 ^{h7}	135	100	10		9								5.1	6.5
R88M-G1K020T-□S2	150	175		118	145	110 ^{h7}	165	130	12	6		22 ^{h6}	41	8 ^{h9}	7	4			6.8	8.7
R88M-G1K520T-□S2	175	200																	8.5	10.1
R88M-G90010T-□S2	175	200	70																10	



Flat type 3000 r/min (230 V, 100 W - 400 W)

Dimensions (mm)	Without brake	With brake	LR	KL1	Flange surface							Shaft end					Aprox. Mass (Kg)			
					D1	D2	C	F	G	Z	S	QK	B	H	T1	Tap x depth	Without brake	With brake		
R88M-GP10030H-□S2	60.5	84.5	25	43	70	50 ^{h7}	60	3	7	4.5	8 ^{h6}	12.5	3 ^{h9}	3	1.8	M3x6L	0.7	0.9		
R88M-GP10030T-□S2	87.5	111.5																		
R88M-GP20030H-□S2	67.5	100	30	53	90	70 ^{h7}	80	5	8	5.5	11 ^{h6}	18	4 ^{h9}	4	2.5	M4x8L	1.3	2		
R88M-GP20030T-□S2	94.5	127																		
R88M-GP40030H-□S2	82.5	115											14 ^{h6}	22.5	5 ^{h9}	5	3.0	M5x10L	1.8	2.5
R88M-GP40030T-□S2	109.5	142																		



Installation

Single-phase, 230 VAC



- *1 Connect when using an absolute encoder. If a backup battery is connected, an encoder cable with a battery is not required.
- *2 Connect B2-B3 for the models with a built-in regeneration resistor (models from 750 W).
- *3 If the amount of regeneration is large, connect an external regeneration resistor to B1-B2. For the models from 750 W, disconnect B2-B3.

Ordering information



Note: The symbols ①②③④⑤... show the recommended sequence to select the components in a G-Series servo system

Servo drives

Symbol	Specifications		Servo drive model	① Compatible rotary servo motors		
				Cylindric type	Flat type	
②	1 phase 200 VAC	100 W	R88D-GN01H-ML2	R88M-G05030□	R88M-GP10030□	
			R88M-G10030□			
			200 W	R88D-GN02H-ML2	R88M-G20030□	R88M-GP20030□
			400 W	R88D-GN04H-ML2	R88M-G40030□	R88M-GP40030□
			750 W	R88D-GN08H-ML2	R88M-G75030□	-
			1.0 kW	R88D-GN10H-ML2	R88M-G1K020T□	-
			1.5 kW	R88D-GN15H-ML2	R88M-G90010T□	-
			R88M-G1K030T□	-		
			R88M-G1K520T□	-		
			R88M-G1K530T□	-		

Control cables (for CN1)

Symbol	Name	Connect to	Model	
⑥	I/O connector kit	Servo drive I/O signals	R88A-CNU01C	
⑦	Terminal block cable		1 m	XW2Z-100J-B33
			2 m	XW2Z-200J-B33
⑧	Terminal block	-	XW2B-20G4	
			XW2B-20G5	
			XW2D-20G6	

Computer cable (for CN3)

Symbol	Name	Model
⑨	Computer cable RS232	2 m R88A-CCG002P2

MECHATROLINK-II cables (for CN6)

Symbol	Specifications	Length	Model
⑪	MECHATROLINK-II Terminator resistor	-	JEPMC-W6022-E
		MECHATROLINK-II cables	0.5 m
		1 m	JEPMC-W6003-01-E
		3 m	JEPMC-W6003-03-E
		5 m	JEPMC-W6003-05-E
		10 m	JEPMC-W6003-10-E
		20 m	JEPMC-W6003-20-E
		30 m	JEPMC-W6003-30-E

Footprint filters

Symbol	Applicable servodrive	Filter model	Rated current	Leakage current	Rated voltage
⑫	R88D-GN01H□	R88A-FIK102-RE	2.4 A	3.5 mA	250 VAC single-phase
	R88D-GN02H□				
	R88D-GN04H□	R88A-FIK104-RE	4.1 A	3.5 mA	
	R88D-GN08H□				
	R88D-GN10H□	R88A-FIK114-RE	14.2 A	3.5 mA	
	R88D-GN15H□				

External regenerative resistor

Symbol	Regenerative resistor unit model	Specifications
⑬	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

MECHATROLINK-II Motion controllers

Symbol	Name	Model
⑩	Trajexia stand-alone motion controller	TJ1-MC04 (4 axes)
		TJ1-MC16 (16 axes)
	Trajexia-PLC motion controller	CJ1W-MCH72
	Position Controller Unit for CJ1 PLC	CJ1W-NCF71 (16 axes)
		CJ1W-NC471 (4 axes)
		CJ1W-NC271 (2 axes)
	Position Controller Unit for CS1 PLC	CS1W-NCF71 (16 axes)
		CS1W-NC471 (4 axes)
		CS1W-NC271 (2 axes)

Computer software

Specifications	Model
Configuration and monitoring software tool for servo drives and inverters. (CX-drive version 1.70 or higher)	CX-drive
Complete OMRON software package including CX-drive. (CX-One version 3.10 or higher)	CX-One

Cylindrical servo motors 3000/2000/1000 r/min (50 - 1.5 kW)

Symbol	Specifications						Servo motor model	Compatible servo drives (2)
	Voltage	Encoder and design	Speed	Design	Rated torque	Capacity		
 (50-750 W)  (900-1500 W)	230 V	Incremental encoder (10000 pulses) Straight shaft with key & tap	3000 min ⁻¹	Without brake	0.16 Nm	50 W	R88M-G05030H-S2	R88D-GN01H-ML2
					0.32 Nm	100 W	R88M-G10030H-S2	R88D-GN01H-ML2
					0.64 Nm	200 W	R88M-G20030H-S2	R88D-GN02H-ML2
					1.3 Nm	400 W	R88M-G40030H-S2	R88D-GN04H-ML2
					2.4 Nm	750 W	R88M-G75030H-S2	R88D-GN08H-ML2
					2.4 Nm	750 W	R88M-G75030H-BS2	R88D-GN08H-ML2
				With brake	0.16 Nm	50 W	R88M-G05030H-BS2	R88D-GN01H-ML2
					0.32 Nm	100 W	R88M-G10030H-BS2	R88D-GN01H-ML2
					0.64 Nm	200 W	R88M-G20030H-BS2	R88D-GN02H-ML2
					1.3 Nm	400 W	R88M-G40030H-BS2	R88D-GN04H-ML2
					2.4 Nm	750 W	R88M-G75030H-BS2	R88D-GN08H-ML2
					2.4 Nm	750 W	R88M-G75030H-BS2	R88D-GN08H-ML2
		Absolute/ incremental encoder (17 bits) Straight shaft with key & tap	Without brake	0.16 Nm	50 W	R88M-G05030T-S2	R88D-GN01H-ML2	
				0.32 Nm	100 W	R88M-G10030T-S2	R88D-GN01H-ML2	
				0.64 Nm	200 W	R88M-G20030T-S2	R88D-GN02H-ML2	
				1.3 Nm	400 W	R88M-G40030T-S2	R88D-GN04H-ML2	
				2.4 Nm	750 W	R88M-G75030T-S2	R88D-GN08H-ML2	
				3.18 Nm	1 kW	R88M-G1K030T-S2	R88D-GN15H-ML2	
			With brake	4.77 Nm	1.5 kW	R88M-G1K530T-S2	R88D-GN15H-ML2	
				0.16 Nm	50 W	R88M-G05030T-BS2	R88D-GN01H-ML2	
				0.32 Nm	100 W	R88M-G10030T-BS2	R88D-GN01H-ML2	
				0.64 Nm	200 W	R88M-G20030T-BS2	R88D-GN02H-ML2	
				1.3 Nm	400 W	R88M-G40030T-BS2	R88D-GN04H-ML2	
				2.4 Nm	750 W	R88M-G75030T-BS2	R88D-GN08H-ML2	
2000 min ⁻¹	Without brake	3000 min ⁻¹	4.8 Nm	1 kW	R88M-G1K020T-S2	R88D-GN10H-ML2		
			7.15 Nm	1.5 kW	R88M-G1K520T-S2	R88D-GN15H-ML2		
			4.8 Nm	1 kW	R88M-G1K020T-BS2	R88D-GN10H-ML2		
			7.15 Nm	1.5 kW	R88M-G1K520T-BS2	R88D-GN15H-ML2		
			With brake	4.8 Nm	1 kW	R88M-G1K020T-BS2	R88D-GN10H-ML2	
				7.15 Nm	1.5 kW	R88M-G1K520T-BS2	R88D-GN15H-ML2	
	1000 min ⁻¹	3000 min ⁻¹		Without brake	8.62 Nm	900 W	R88M-G90010T-S2	R88D-GN15H-ML2
					8.62 Nm	900 W	R88M-G90010T-BS2	R88D-GN15H-ML2

Flat type servo motors 3000 r/min (100 - 400 W)

Symbol	Specifications				Servo motor model	Compatible servo drives (2)		
	Voltage	Encoder and design	Rated torque	Capacity				
	230 V	Incremental encoder (10000 pulses) Straight shaft with key & tap	3000 r/min	Without brake	0.32 Nm	100 W	R88M-GP10030H-S2	R88D-GN01H-ML2
					0.64 Nm	200 W	R88M-GP20030H-S2	R88D-GN02H-ML2
					1.3 Nm	400 W	R88M-GP40030H-S2	R88D-GN04H-ML2
				With brake	0.32 Nm	100 W	R88M-GP10030H-BS2	R88D-GN01H-ML2
					0.64 Nm	200 W	R88M-GP20030H-BS2	R88D-GN02H-ML2
					1.3 Nm	400 W	R88M-GP40030H-BS2	R88D-GN04H-ML2
		Absolute/ incremental encoder (17 bits) Straight shaft with key & tap	Without brake	0.32 Nm	100 W	R88M-GP10030T-S2	R88D-GN01H-ML2	
				0.64 Nm	200 W	R88M-GP20030T-S2	R88D-GN02H-ML2	
				1.3 Nm	400 W	R88M-GP40030T-S2	R88D-GN04H-ML2	
			With brake	0.32 Nm	100 W	R88M-GP10030T-BS2	R88D-GN01H-ML2	
				0.64 Nm	200 W	R88M-GP20030T-BS2	R88D-GN02H-ML2	
				1.3 Nm	400 W	R88M-GP40030T-BS2	R88D-GN04H-ML2	

Encoder Cables

Symbol	Specifications	Model	Appearance	
③	Encoder cable for absolute encoder (50-750 W) R88M-G(050/100/200/400/750)30T-□ R88M-GP(100/200/400)30T-□	1.5 m	R88A-CRGA001-5CR-E	
		3 m	R88A-CRGA003CR-E	
		5 m	R88A-CRGA005CR-E	
		10 m	R88A-CRGA010CR-E	
		15 m	R88A-CRGA015CR-E	
		20 m	R88A-CRGA020CR-E	
	Encoder cable for Incremental encoder (50-750 W) R88M-G(050/100/200/400/750)30H-□ R88M-GP(100/200/400)30H-□	1.5 m	R88A-CRGB001-5CR-E	
		3 m	R88A-CRGB003CR-E	
		5 m	R88A-CRGB005CR-E	
		10 m	R88A-CRGB010CR-E	
		15 m	R88A-CRGB015CR-E	
		20 m	R88A-CRGB020CR-E	
	Encoder cable for Absolute encoder (900-1500 W) R88M-G(1K0/1K5)30T-□ R88M-G(1K0/1K5)20T-□ R88M-G90010T-□	1.5 m	R88A-CRGC001-5NR-E	
		3 m	R88A-CRGC003NR-E	
		5 m	R88A-CRGC005NR-E	
		10 m	R88A-CRGC010NR-E	
		15 m	R88A-CRGC015NR-E	
		20 m	R88A-CRGC020NR-E	

Absolute Encoder Battery cable

Symbol	Specifications	Model	Appearance
③	Absolute Encoder battery cable Battery not included	0.3 m	R88A-CRGD0R3C
		One R88A-BAT01G Battery included	R88A-CRGD0R3C-BS
	Absolute Encoder backup battery 2,000 mA.h 3.6V	-	R88A-BAT01G

Note: The absolute encoder battery cable is only an extension and must be used with an absolute encoder cable.

Power cables

Symbol	Specifications	Model	Appearance
④	For servomotors from 50 to 750W R88M-G(050/100/200/400/750)30□ R88M-GP(100/200/400)30□ For servomotors with brake, a separate cable (R88A-CAGA□BR-E) is needed	1.5 m	R88A-CAGA001-5SR-E
		3 m	R88A-CAGA003SR-E
		5 m	R88A-CAGA005SR-E
		10 m	R88A-CAGA010SR-E
		15 m	R88A-CAGA015SR-E
		20 m	R88A-CAGA020SR-E
	For servomotors from 900 to 1.5 kW without brake R88M-G(1K0/1K5)30T-S2 R88M-G(1K0/1K5)20T-S2 R88M-G90010T-S2	1.5 m	R88A-CAGB001-5SR-E
		3 m	R88A-CAGB003SR-E
		5 m	R88A-CAGB005SR-E
		10 m	R88A-CAGB010SR-E
		15 m	R88A-CAGB015SR-E
		20 m	R88A-CAGB020SR-E
	For servomotors from 900 to 1.5 kW with brake R88M-G(1K0/1K5)30T-BS2 R88M-G(1K0/1K5)20T-BS2 R88M-G90010T-BS2	1.5 m	R88A-CAGB001-5BR-E
		3 m	R88A-CAGB003BR-E
		5 m	R88A-CAGB005BR-E
		10 m	R88A-CAGB010BR-E
		15 m	R88A-CAGB015BR-E
		20 m	R88A-CAGB020BR-E

Brake cable (for 50-750W servomotors)

Symbol	Specifications	Model	Appearance
⑤	Brake cable only. For servomotors from 50 to 750W with brake R88M-G(050/100/200/400/750)30□-BS2, R88M-GP(100/200/400)30□-BS2	1.5 m	R88A-CAGA001-5BR-E
		3 m	R88A-CAGA003BR-E
		5 m	R88A-CAGA005BR-E
		10 m	R88A-CAGA010BR-E
		15 m	R88A-CAGA015BR-E
		20 m	R88A-CAGA020BR-E

Connectors for power, encoder and brake cables

Specifications	Applicable Servomotor	Model
Connectors for power cables	Motor side	R88M-G(050/100/200/400/750)30□, R88M-GP(100/200/400)30□
	Motor side	R88M-G(1K0/1K5)30□-S2, R88M-G(1K0/1K5)20□-S2, R88M-G90010□-S2 (without brake)
	Motor side	R88M-G(1K0/1K5)30□-BS2, R88M-G(1K0/1K5)20□-BS2, R88M-G90010□-BS2 (with brake)
Connectors for encoder cables	Drive side (CN2)	-
	Motor side	R88M-G(050/100/200/400/750)30T-□, R88M-GP(100/200/400)30T-□ (Absolute encoder)
	Motor side	R88M-G(050/100/200/400/750)30H-□, R88M-GP(100/200/400)30H-□ (Incremental encoder)
	Motor side	R88M-G(1K0/1K5)30T-□, R88M-G(1K0/1K5)20T-□, R88M-G90010T-□
Connector for brake cable	Motor side	R88M-G(050/100/200/400/750)30□-BS2, R88M-GP(100/200/400)30□-BS2

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

In the interest of product improvement, specifications are subject to change without notice.

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